CSCI 497P/597P: Computer Vision



Lecture 19 The (correct) Pinhole Projection Matrix 360 (Spherical) Panoramas

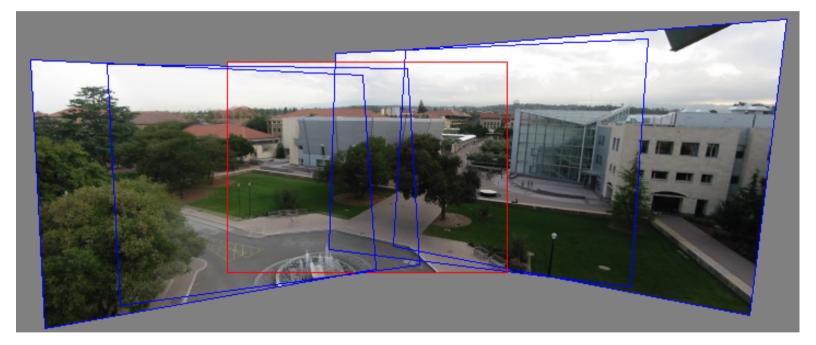
Announcements

- HW2 due tonight!
- How's P2 going?

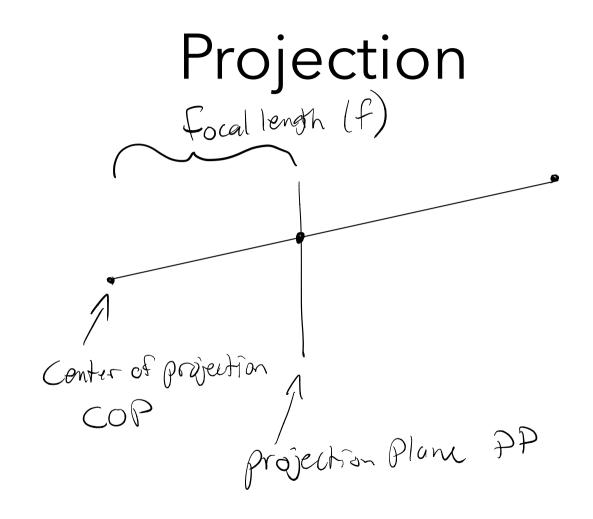
Goals

- Understand where images come from (under the pinhole camera model)
 - Be able to derive Understand the 3x4 pinhole projection matrix
- Know how to create 360 degree panoramas by mapping images onto a spherical surface instead.

Can we make 360 panoramas?

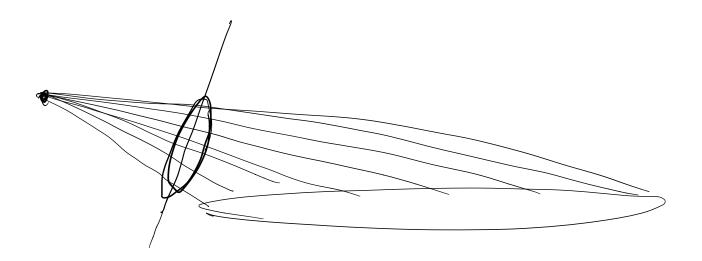


To answer this, we need to know how these images came to be. Why can we even make **any** panoramas with homographies?

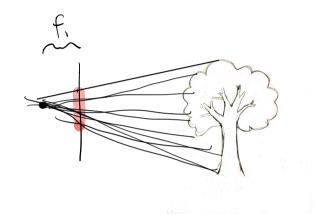


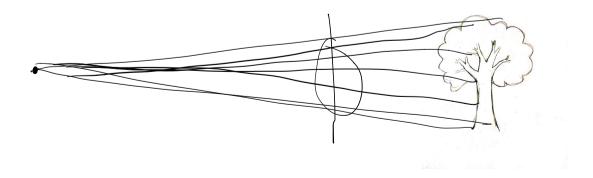


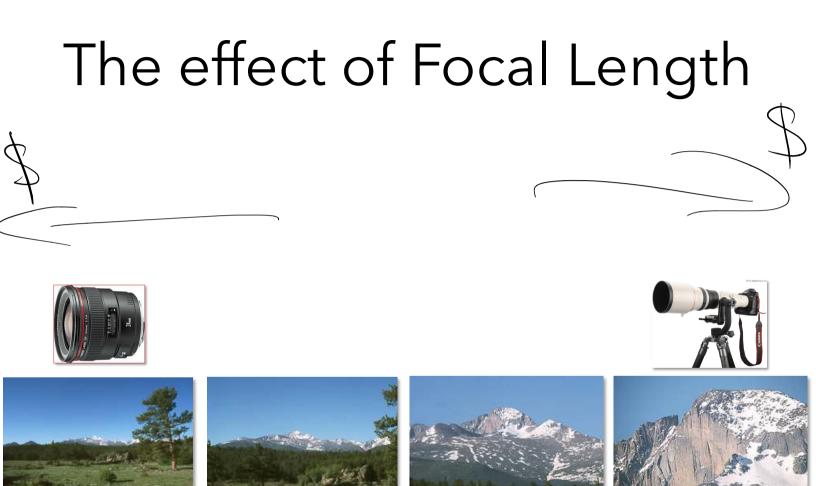




Focal Length







Z4 MM

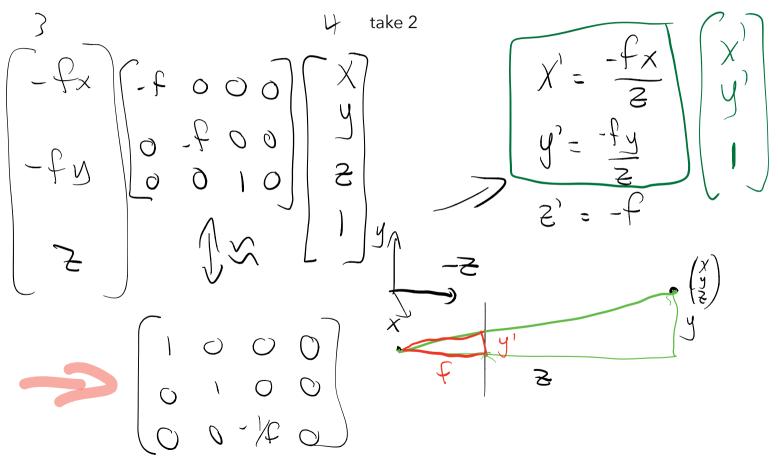
ZOMM

105 mm

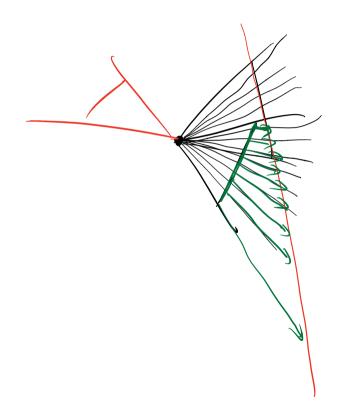
ZOOMM



Pinhole Projection Matrix



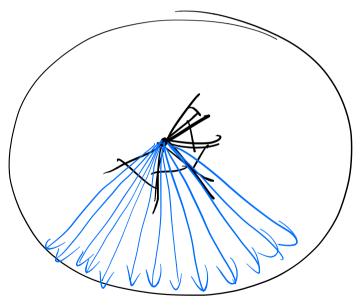
Planar Panoramas



We can't make 360 panoramas with homographies.

Spherical Panoramas

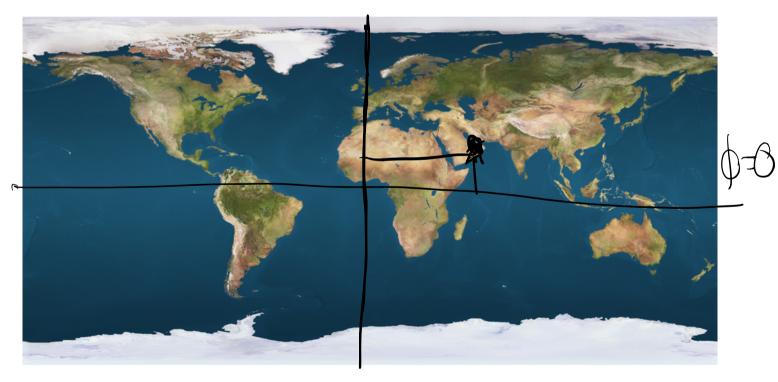
Idea: project images onto a **sphere** instead of a plane.



Example: Google Street View

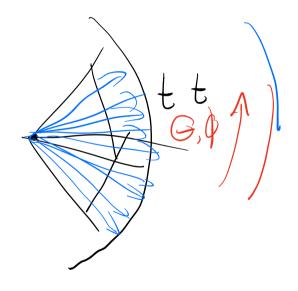


Unwrapping a Sphere



Spherical Panoramas

What motion model should we use?



Spherical Panoramas

1. Warp planar images onto the surface of a sphere

2. Align with **translational** motion model.

3. Stitch and blend as usual.