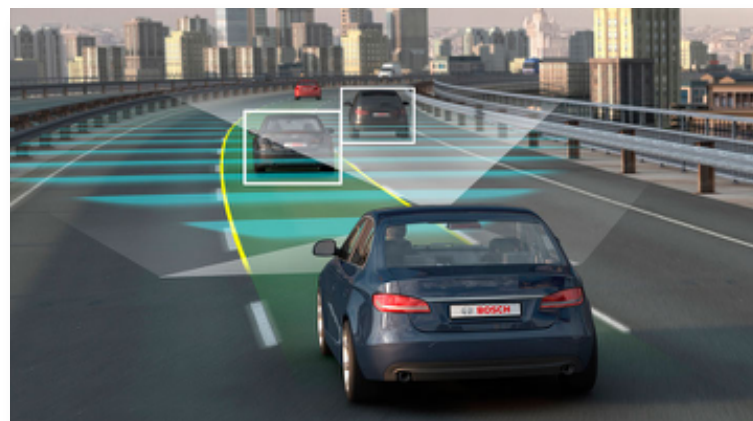
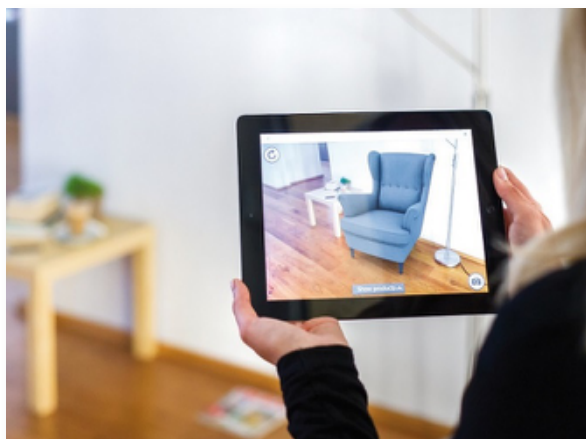


CS497P/597P: Computer Vision

Instructor: Scott Wehrwein

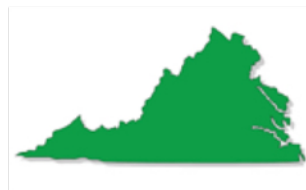


About Me

Scott Wehrwein



scott.wehrwein@wwu.edu



About Me

Research interests:

- **Computer vision** and graphics
- Computational photography and videography
- Photo and video enhancement
- Augmented reality

Today

1. What is computer vision?
2. Course overview

Today

- Readings
 - Szeliski, Chapter 1 (Introduction)

Every image tells a story



- Goal of computer vision: perceive the “story” behind the picture
- Compute properties of the world
 - 3D shape
 - Names of people or objects
 - What happened?

The goal of computer vision



0	3	2	5	4	7	6	9	8
3	0	1	2	3	4	5	6	7
2	1	0	3	2	5	4	7	6
5	2	3	0	1	2	3	4	5
4	3	2	1	0	3	2	5	4
7	4	5	2	3	0	1	2	3
6	5	4	3	2	1	0	3	2
9	6	7	4	5	2	3	0	1
8	7	6	5	4	3	2	1	0

Can the computer match human perception?



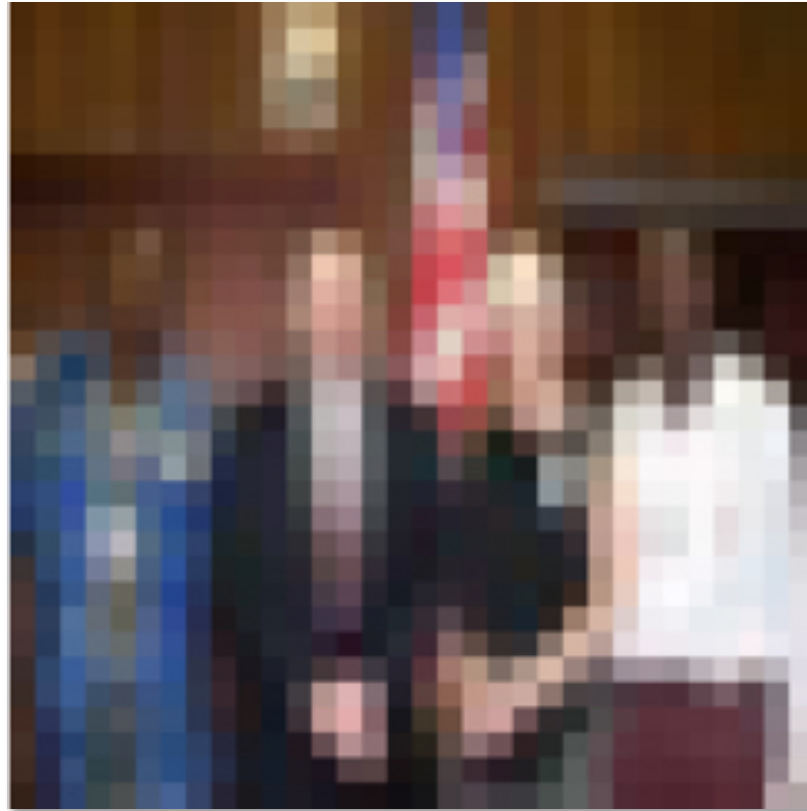
- Yes and no (mainly no)
 - computers can be better at “easy” things
 - humans are much better at “hard” things
- But huge progress has been made
 - Accelerating in the last 4 years due to deep learning
 - What is considered “hard” keeps changing

Human perception has its shortcomings



[Sinha and Poggio, *Nature*, 1996](#)

But humans can tell a lot about a scene from a little information...



Source: "80 million tiny images" by Torralba, et al.





IN CS, IT CAN BE HARD TO EXPLAIN
THE DIFFERENCE BETWEEN THE EASY
AND THE VIRTUALLY IMPOSSIBLE.

xkcd

9/24/2014

Introducing: Flickr PARK or BIRD

flickr

10/20/2014

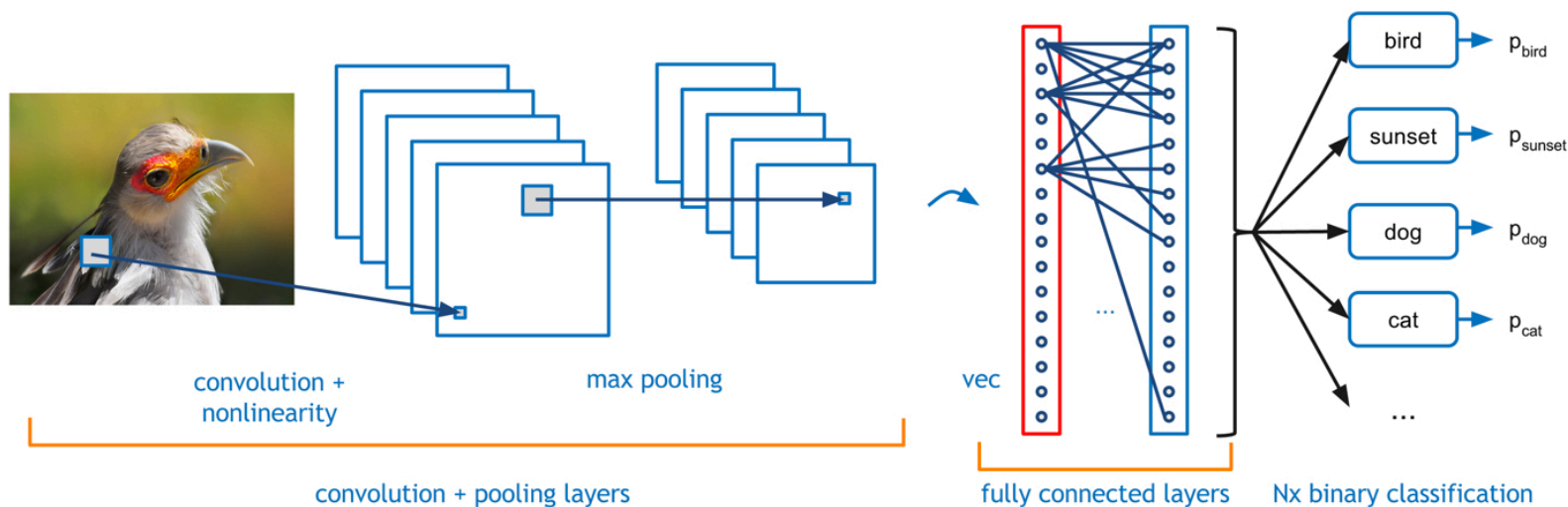


Zion National Park Utah by Les Haines

OR



Secretary Bird by Bill Gracey



Why is computer vision difficult?



Viewpoint variation



Illumination



Scale

Why is computer vision difficult?



Intra-class variation



Motion (Source: S. Lazebnik)

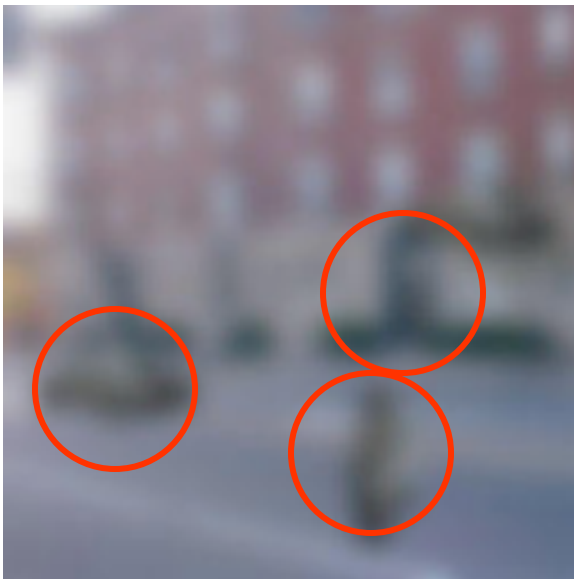
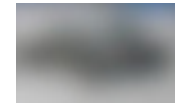
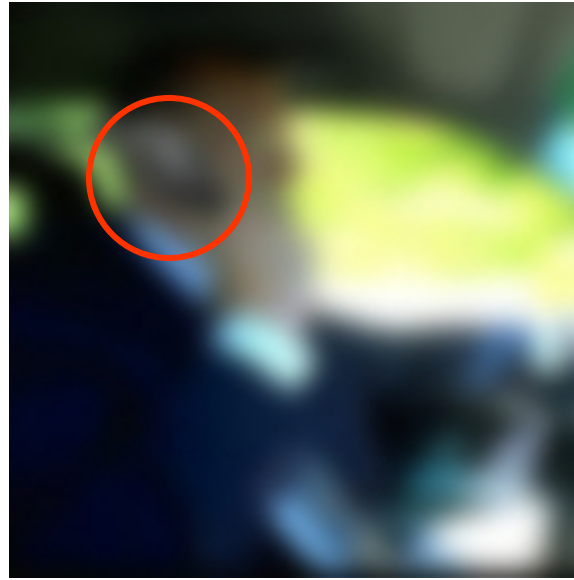
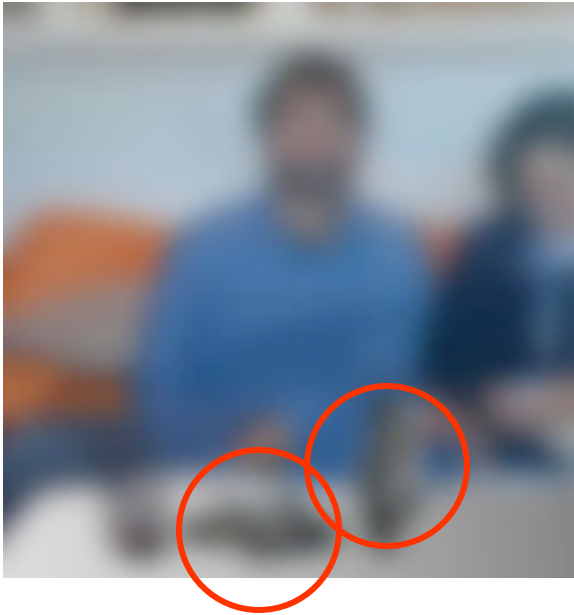


Background clutter



Occlusion

Challenges: local ambiguity



But there are lots of cues we can exploit...



Source: S. Lazebnik



The picture above is funny.

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- You recognize that Obama has his foot positioned just slightly on top of the scale. Notice the language I'm using: It is in terms of the 3D structure of the scene, not the position of the leg in the 2D coordinate system of the image.
- You know how physics works: Obama is leaning in on the scale, which applies a force on it. Scale measures force that is applied on it, that's how it works => it will over-estimate the weight of the person standing on it.
- The person measuring his weight is not aware of Obama doing this. You derive this because you know his pose, you understand that the field of view of a person is finite, and you understand that he is not very likely to sense the slight push of Obama's foot.
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The state of Computer Vision and AI: we are really, really far.

Oct 22, 2012



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 - Many different 3D scenes could have given rise to a particular 2D picture



- We often need to use prior knowledge about the structure of the world

The goals of computer vision

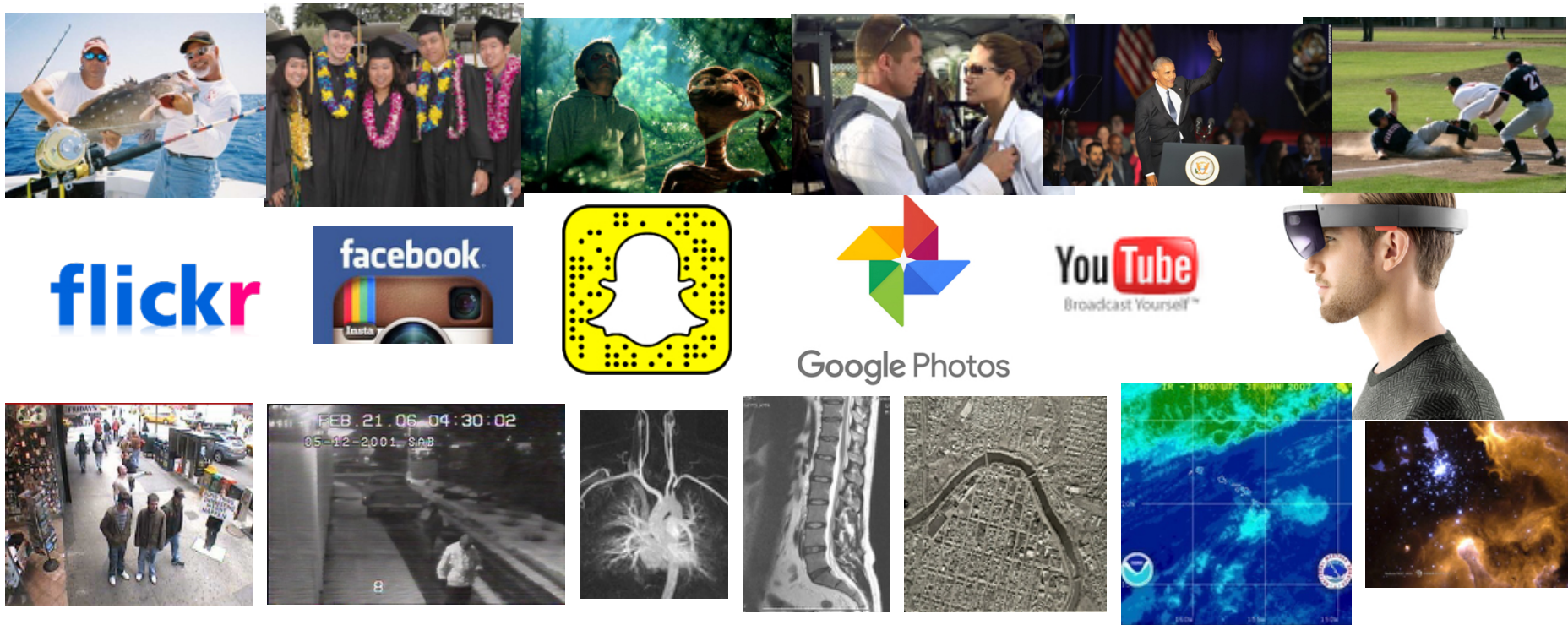
<https://www.youtube.com/watch?v=9MeaaCwBW28>

The goals of computer vision



Why study computer vision?

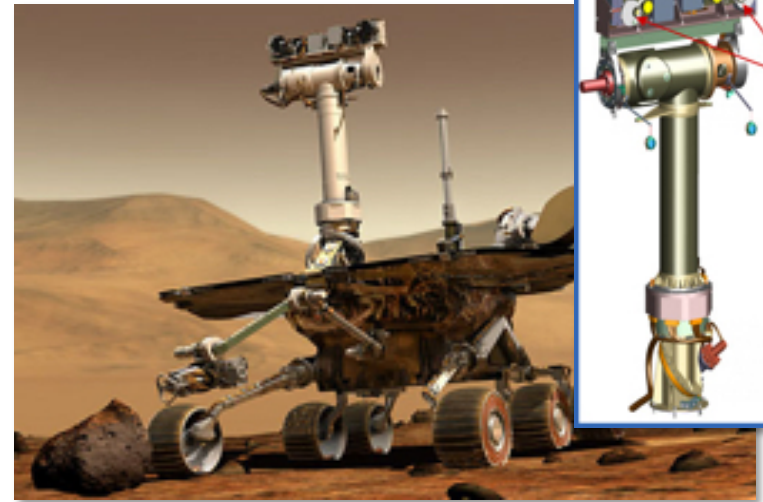
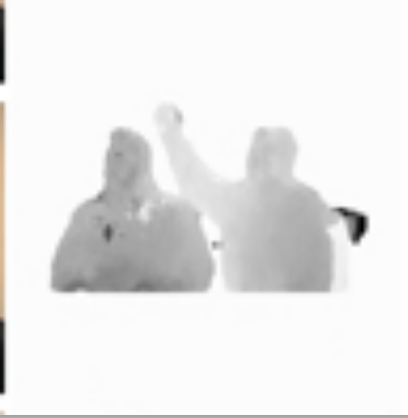
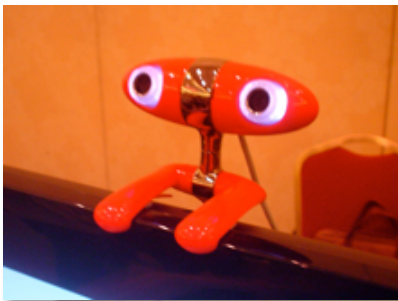
- Billions of images/videos captured per day



- Huge number of useful applications
- The next slides show the current state of the art

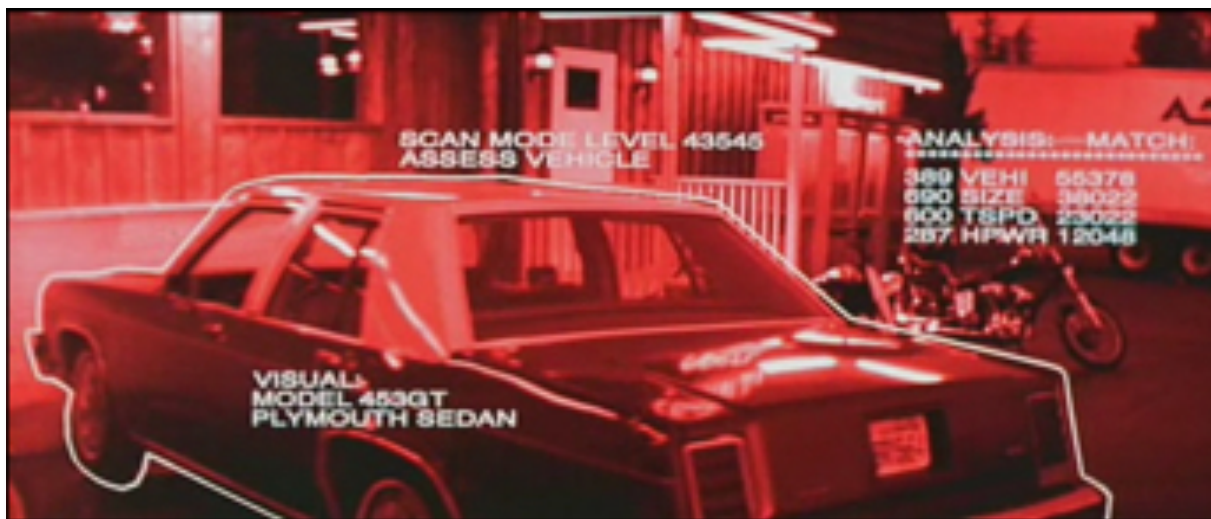
The goals of computer vision

- Compute the 3D shape of the world



The goals of computer vision

- Recognize objects and people



Terminator 2, 1991



sky

building

flag

face

banner

wall

street lamp

bus

bus

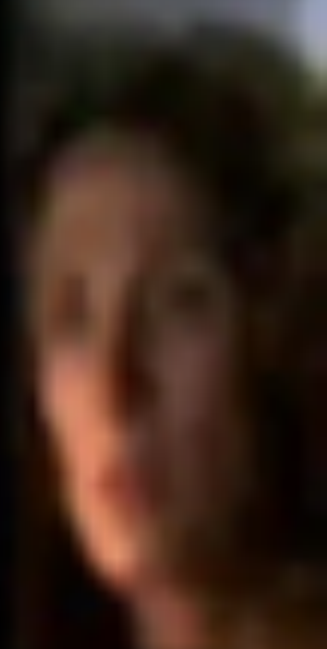
cars



The goals of computer vision

- “Enhance” images

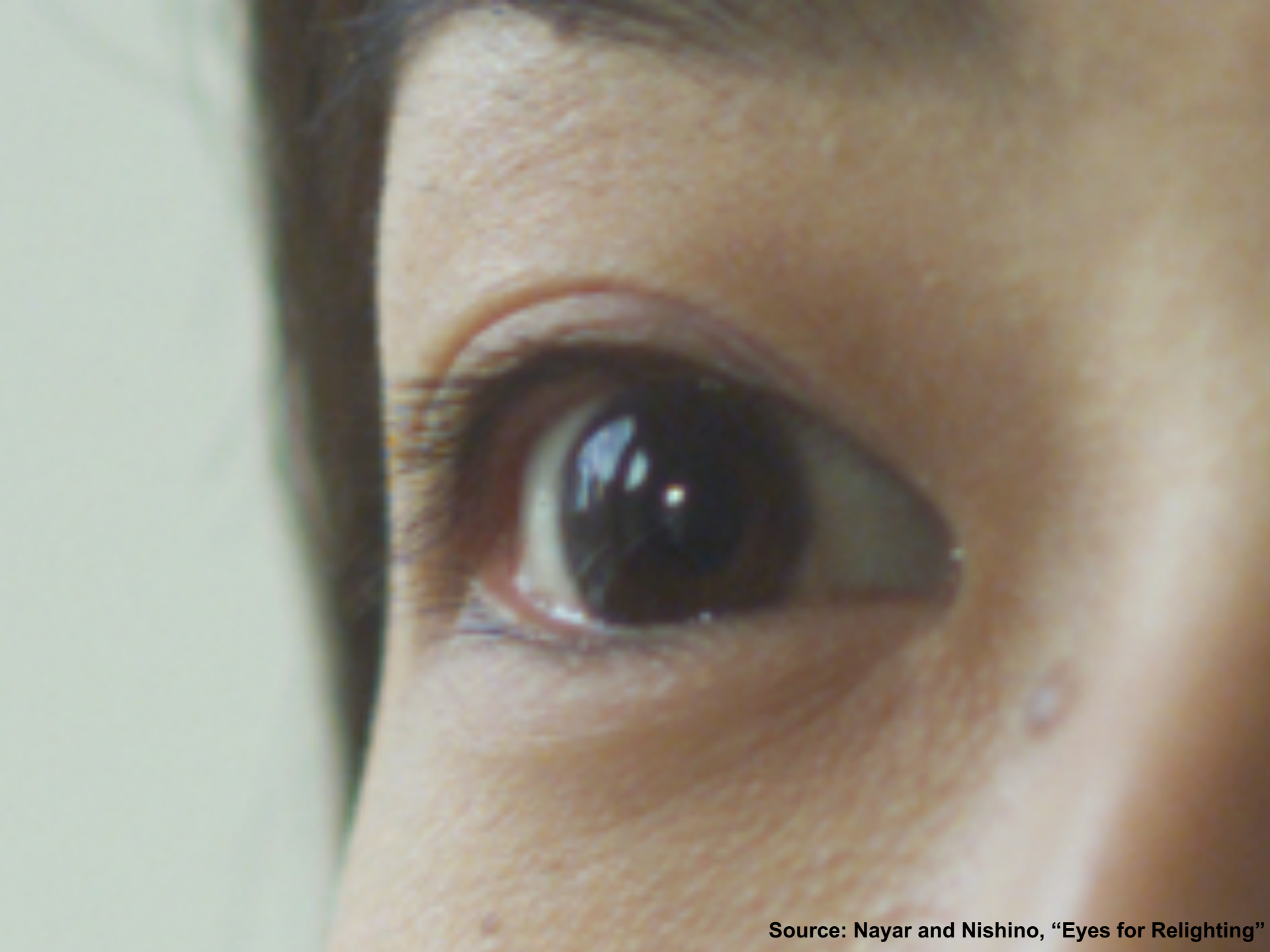




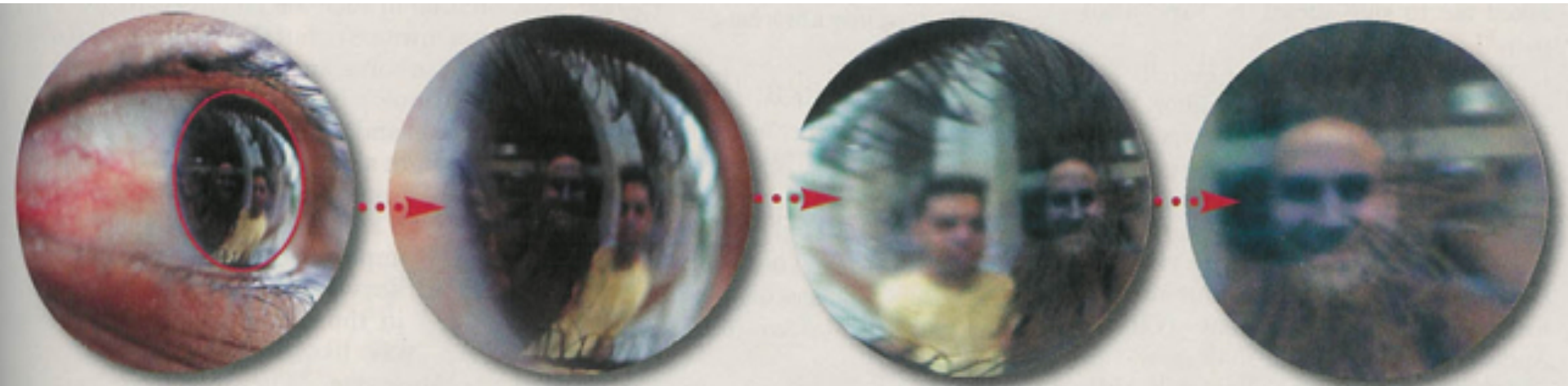
The goal of computer vision

- Forensics





Source: Nayar and Nishino, "Eyes for Relighting"



Source: Nayar and Nishino, "Eyes for Relighting"

— Researchers warn peace sign photos could expose fingerprints

But the likelihood of anyone actually using images to recreate prints is pretty slim.



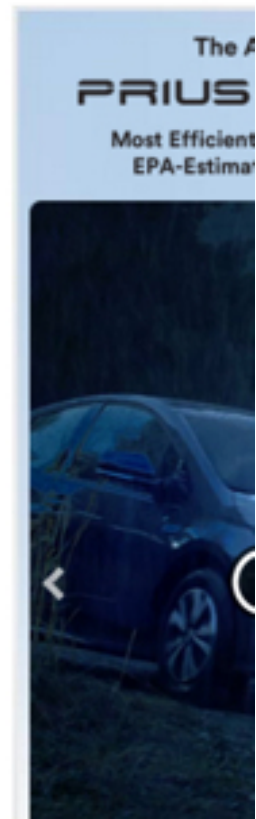
Jamie Rigg, @jmerigg
01.13.17 in [Security](#)

Comments

1721
Shares



Getty

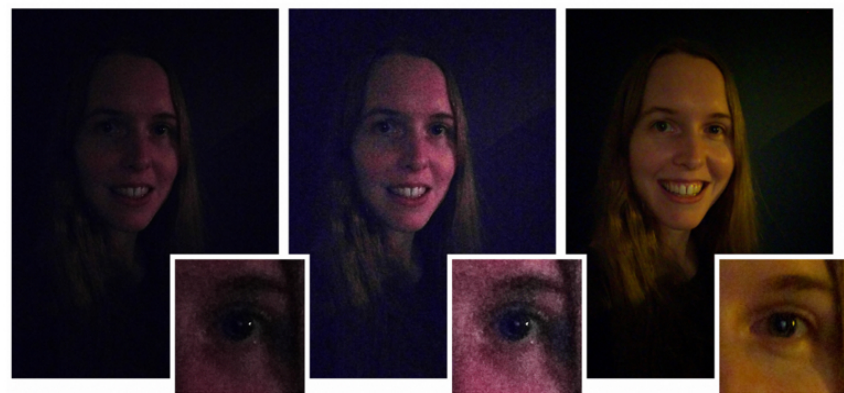


The goals of computer vision

- Improve photos (“Computational Photography”)



Super-resolution (source: 2d3)



Low-light photography

(credit: [Hasinoff et al., SIGGRAPH ASIA 2016](#))



Depth of field on cell phone camera
(source: [Google Research Blog](#))



Inpainting / image completion
(image credit: Hays and Efros)

Optical character recognition (OCR)

- If you have a scanner, it probably came with OCR software



Digit recognition, AT&T labs (1990's)
<http://yann.lecun.com/exdb/lenet/>



License plate readers
http://en.wikipedia.org/wiki/Automatic_number_plate_recognition



Automatic check processing



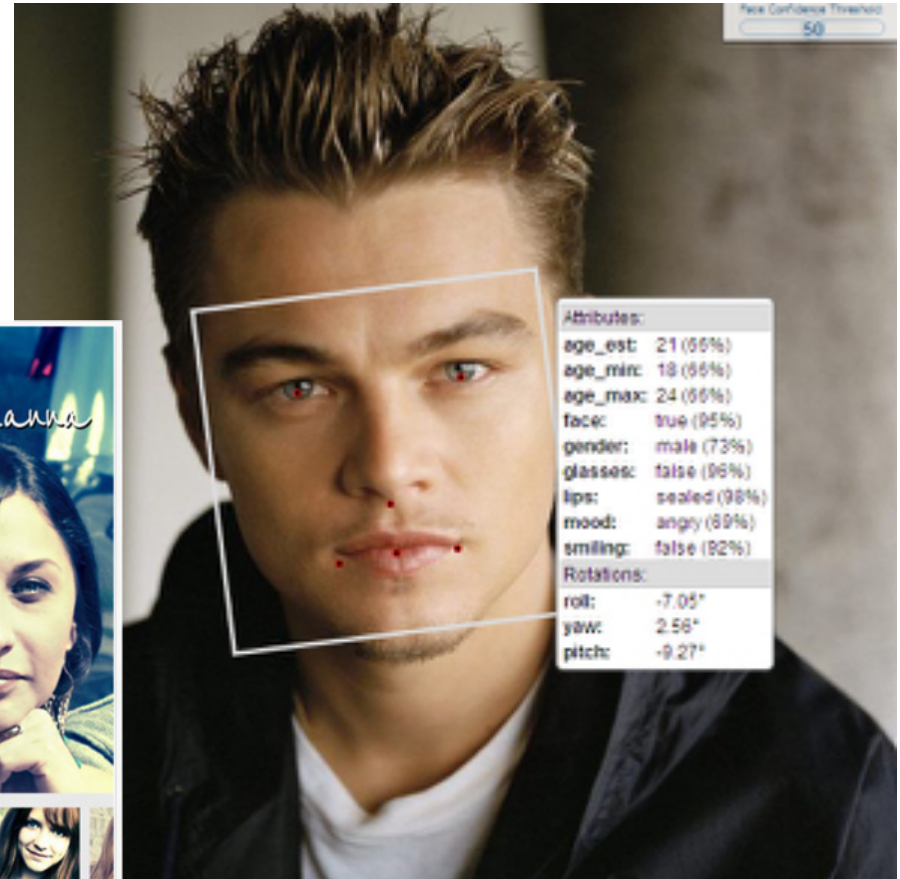
Sudoku grabber
<http://sudokugrab.blogspot.com/>

Face detection



- Nearly all cameras detect faces in real time
– (Why?)

Face Recognition



Face recognition



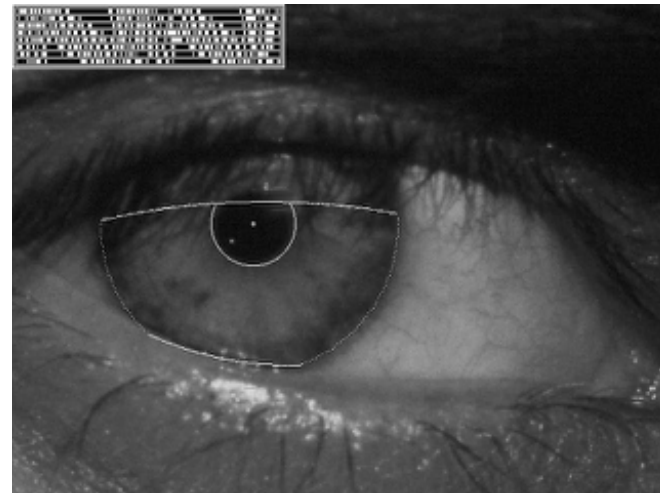
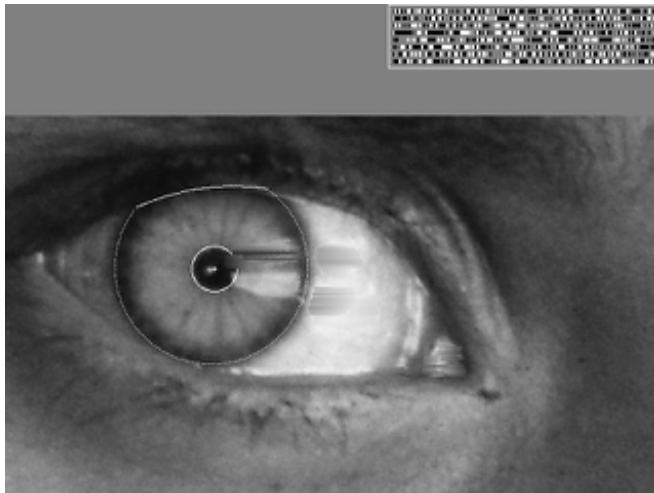
Who is she?

Source: S. Seitz

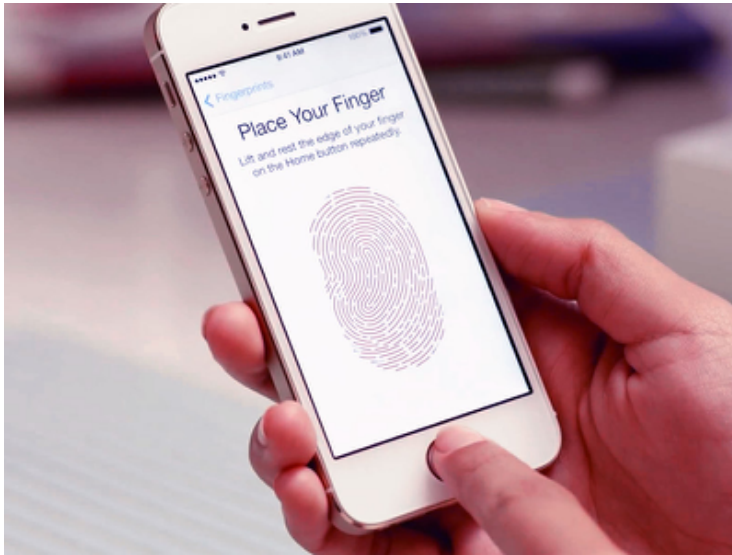
Vision-based biometrics



“How the Afghan Girl was Identified by Her Iris Patterns” Read the [story](#)



Login without a password



Fingerprint scanners on many new smartphones and other devices



Face unlock on Apple iPhone X
See also <http://www.sensiblevision.com/>

Bird Identification



Merlin Bird ID

Special effects: camera tracking

The screenshot displays the PFTrack software interface for camera tracking. The main view shows a 360-degree panoramic video of a church tower on a grassy hill. A grid is overlaid on the ground, and a purple pyramid-shaped object is visible in the foreground. The interface includes a timeline at the bottom with a playhead at frame 1096. On the left, there is a hierarchy tree showing the project structure. At the bottom, there are several control panels:

- Feature Tracking:** A table listing tracked features with columns for Name, From, and To frames.
- Spherical Camera Solver:** Settings for Inlier Threshold (Normal), Camera smoothing (None), and Orientation (Orient Ground to X-Y Plane).
- Display:** Options to show all features, projections, ground, and horizon.
- Planar Camera Output:** Settings for Output size (1080) and Multi-sample (1).

From Frame	To Frame	Name
1029	1127	Tracker 003953
1075	1124	Tracker 003953
1060	1102	Tracker 003954
1041	1098	Tracker 003955
1080	1123	Tracker 003956
1086	1102	Tracker 003957
1086	1104	Tracker 003958
1101	1116	Tracker 003960
1094	1096	Tracker 003941
1054	1102	Tracker 003942
900	1096	Tracker 003943
1017	1099	Tracker 003944

PFTrack

Special effects: shape capture



The Matrix movies, ESC Entertainment, XYZRGB, NRC

Special effects: motion capture

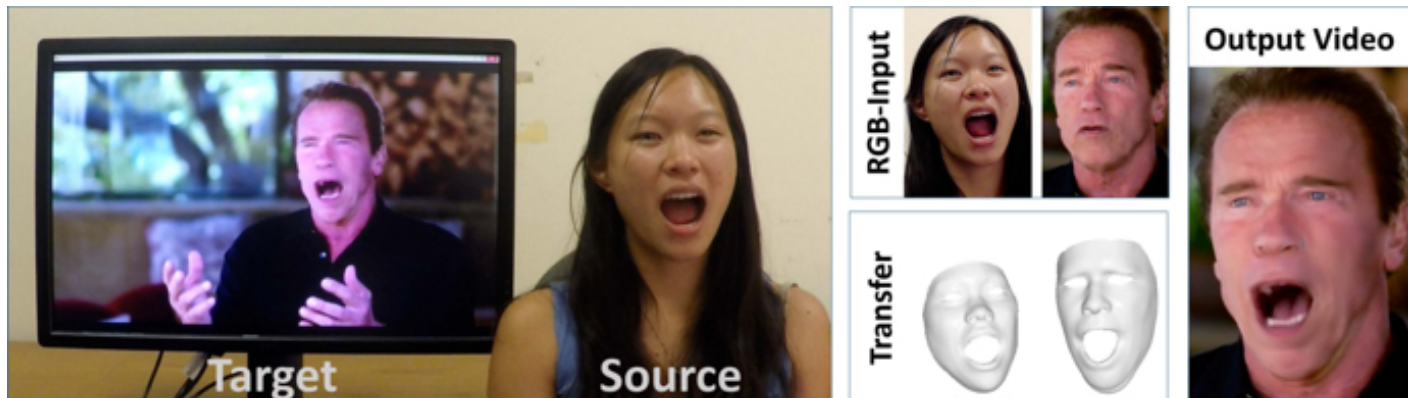


Pirates of the Caribbean, Industrial Light and Magic

3D face tracking w/ consumer cameras



Snapchat Lenses



[Face2Face system](#) (Thies et al.)

Sports



Sportvision first down line

Nice [explanation](http://www.howstuffworks.com) on www.howstuffworks.com



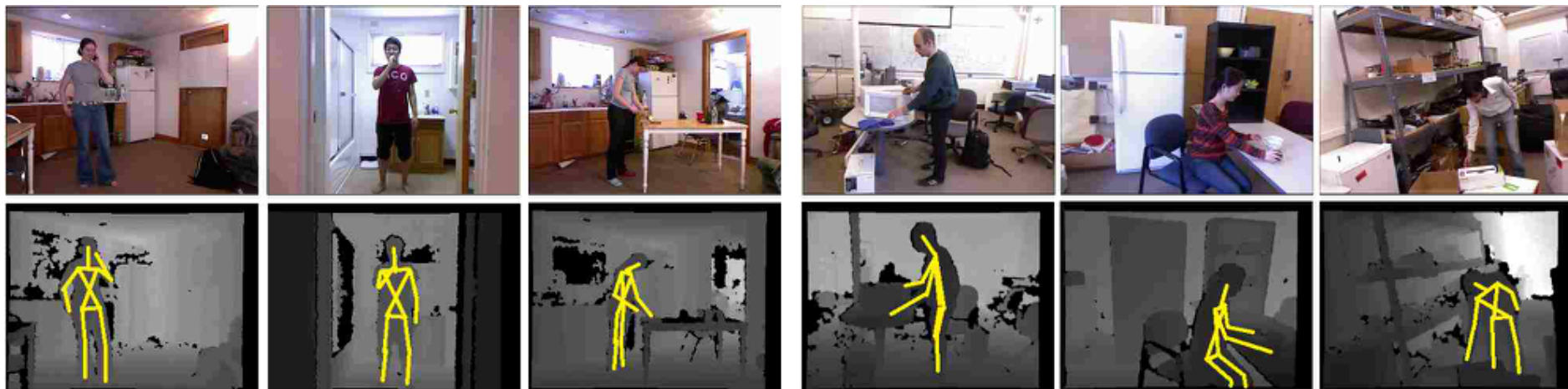
Vision-based interaction (and games)



Assistive technologies

Nintendo Wii has camera-based IR tracking built in. See [Lee's work at CMU](#) on clever tricks on using it to create a [multi-touch display](#)!

Kinect



RGB, depth, and Pose Estimation

Smart cars

▶▶ manufacturer products consumer products ◀◀

Our Vision. Your Safety.

rear looking camera forward looking camera

side looking camera

▶ **EyeQ** Vision on a Chip

▶ **Vision Applications**
Road, Vehicle, Pedestrian Protection and more

▶ **AWS** Advance Warning System

▶ **News**

- ▶ Mobileye Advanced Technologies Power Volvo Cars World First Collision Warning With Auto Brake System
- ▶ Volvo: New Collision Warning with Auto Brake Helps Prevent Rear-end

▶ all news

▶ **Events**

- ▶ Mobileye at Essip Auto, Paris, France
- ▶ Mobileye at SEMA, Las Vegas, NV

▶ read more

- [Mobileye](#)
- Tesla Autopilot
- Safety features in many high-end cars

Self-driving cars



Waymo, Uber, and many others

Robotics



NASA's Mars Curiosity Rover

[https://en.wikipedia.org/wiki/Curiosity_\(rover\)](https://en.wikipedia.org/wiki/Curiosity_(rover))



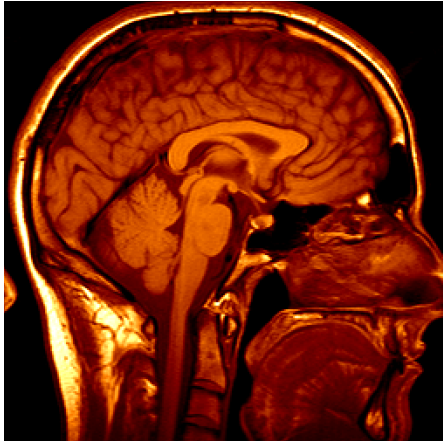
Amazon Picking Challenge

<http://www.robocup2016.org/en/events/amazon-picking-challenge/>

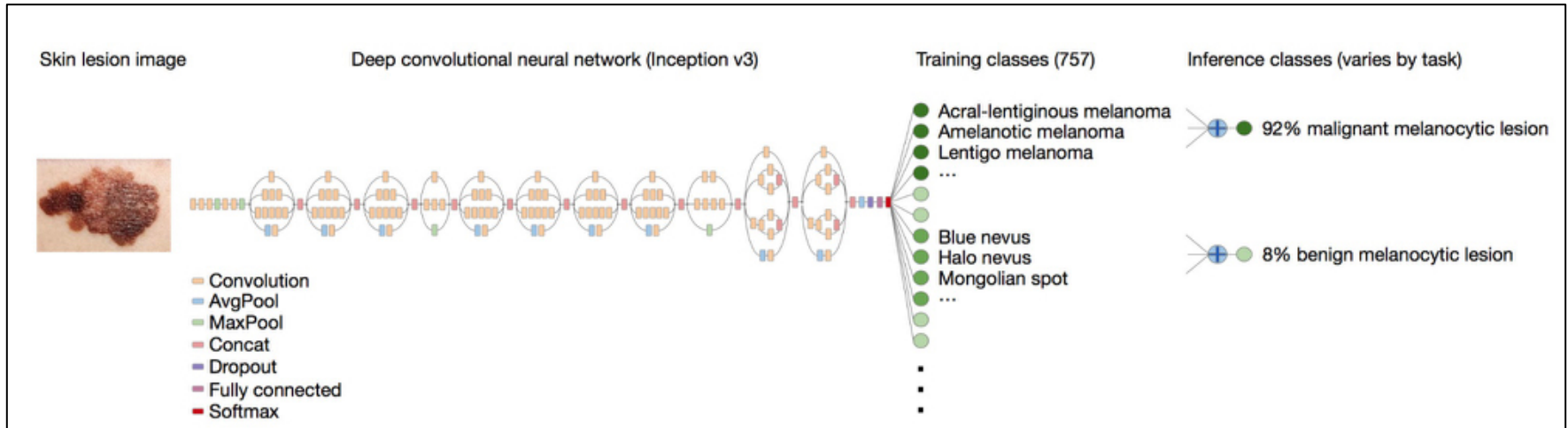


Amazon Prime Air

Medical imaging



3D imaging
(MRI, CT)



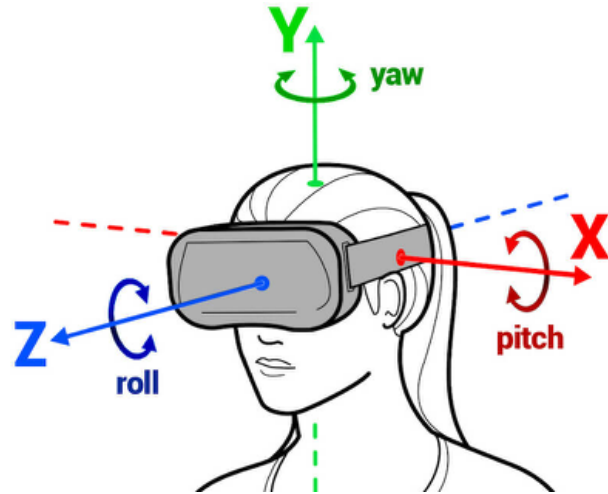
Skin cancer classification with deep learning
<https://cs.stanford.edu/people/esteva/nature/>

Facebook Buys Oculus, Virtual Reality Gaming Startup, For \$2 Billion

[+ Comment Now](#) [+ Follow Comments](#)



Virtual & Augmented Reality



6DoF head tracking



Hand & body tracking



3D scene understanding



3D-360 video capture

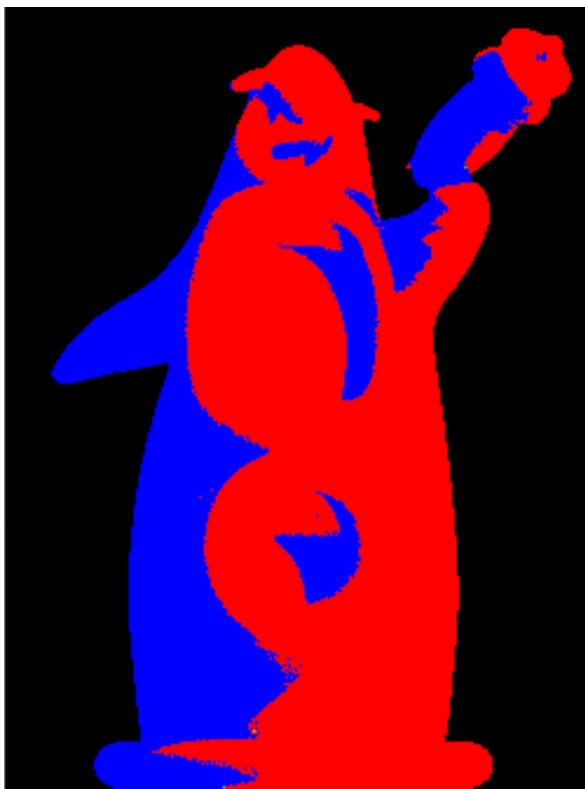
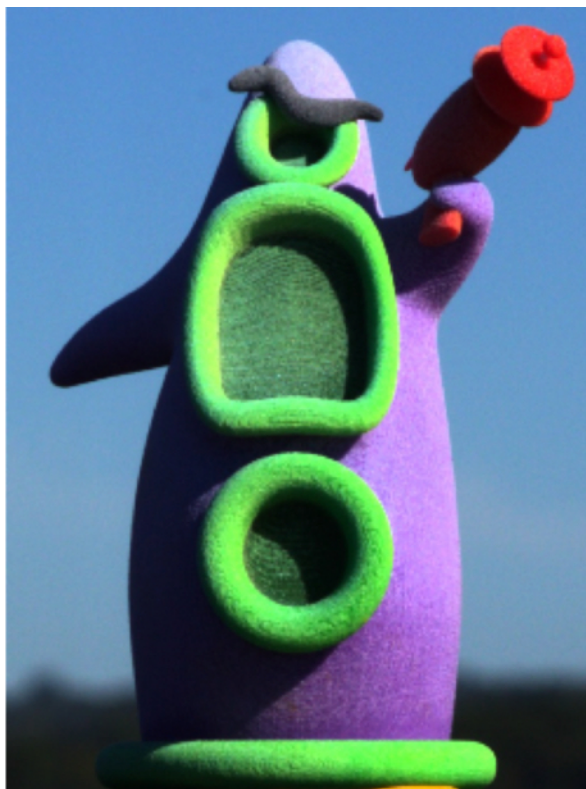
Current state of the art

- You just saw many examples of current systems.
 - Many of these are less than 5 years old
- This is a very active research area, and rapidly changing
 - Many new apps in the next 5 years
 - Deep learning powering many modern applications
- Many startups across a dizzying array of areas
 - VR/AR, deep learning, robotics, autonomous vehicles, medical imaging, construction, manufacturing, ...

My Work: Video Segmentation



My Work: Illumination Estimation

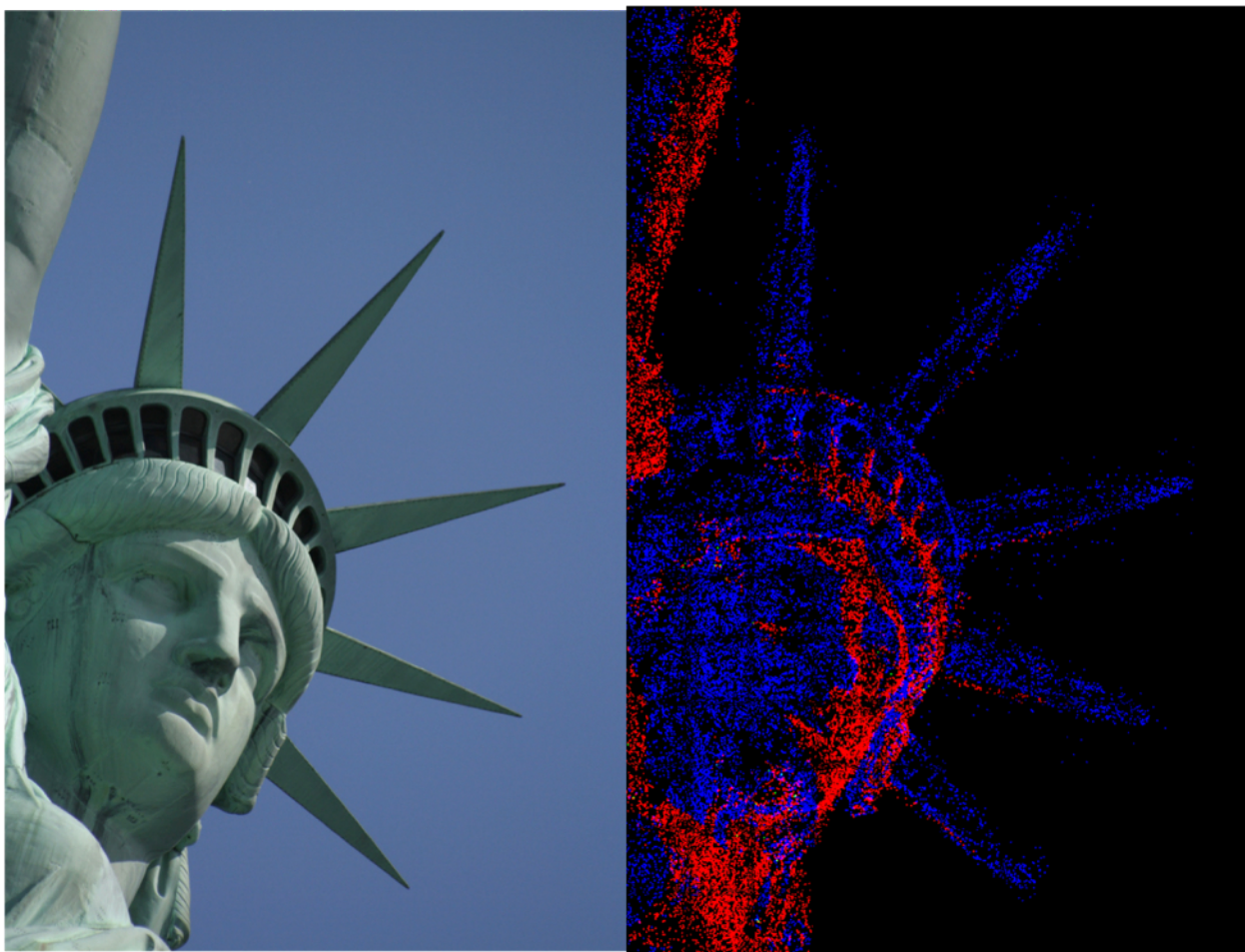




Sunlit

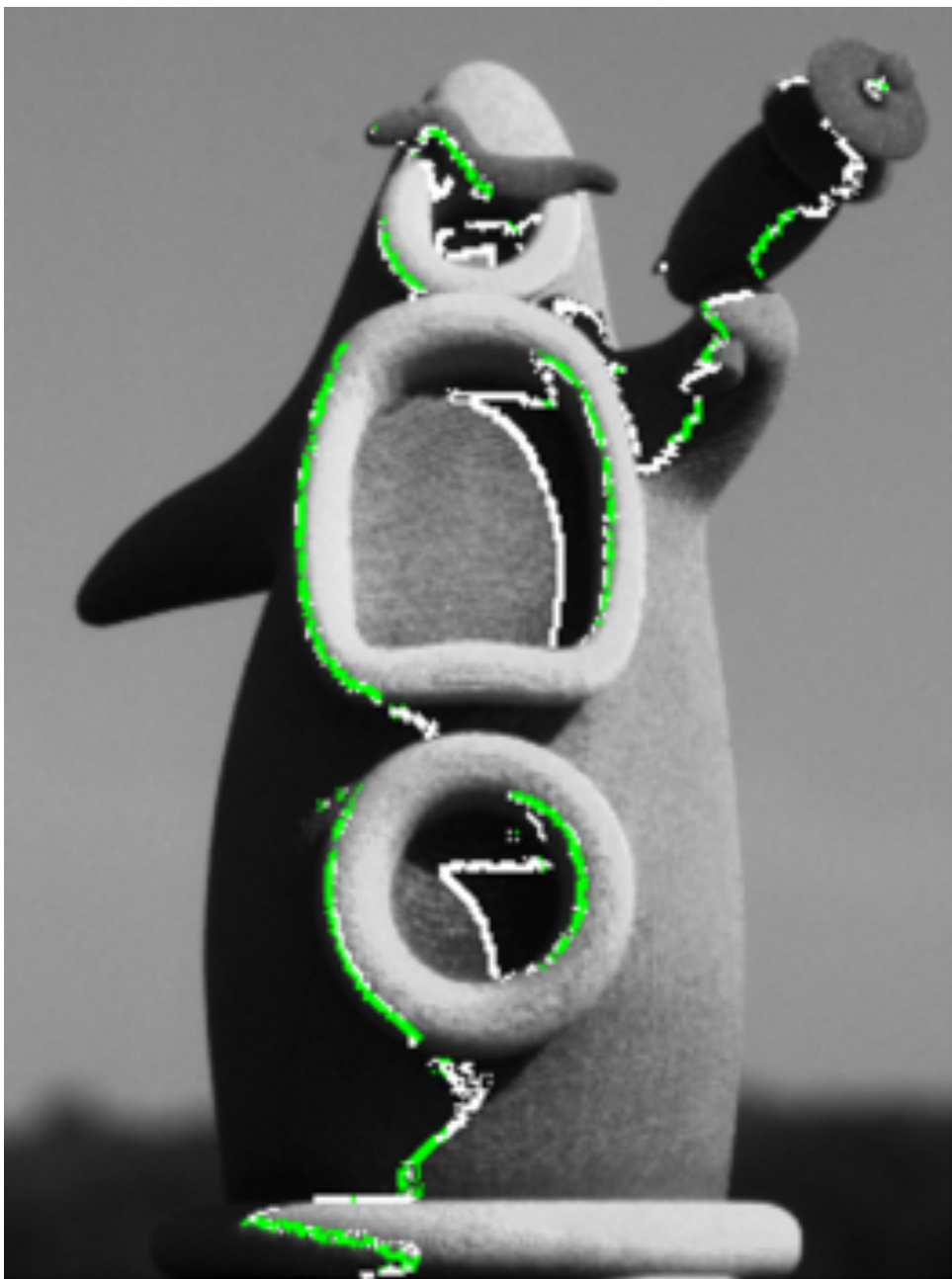


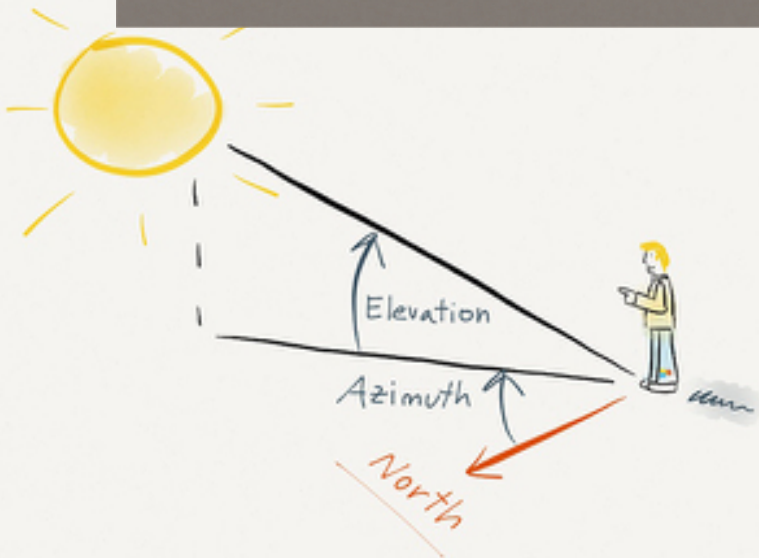
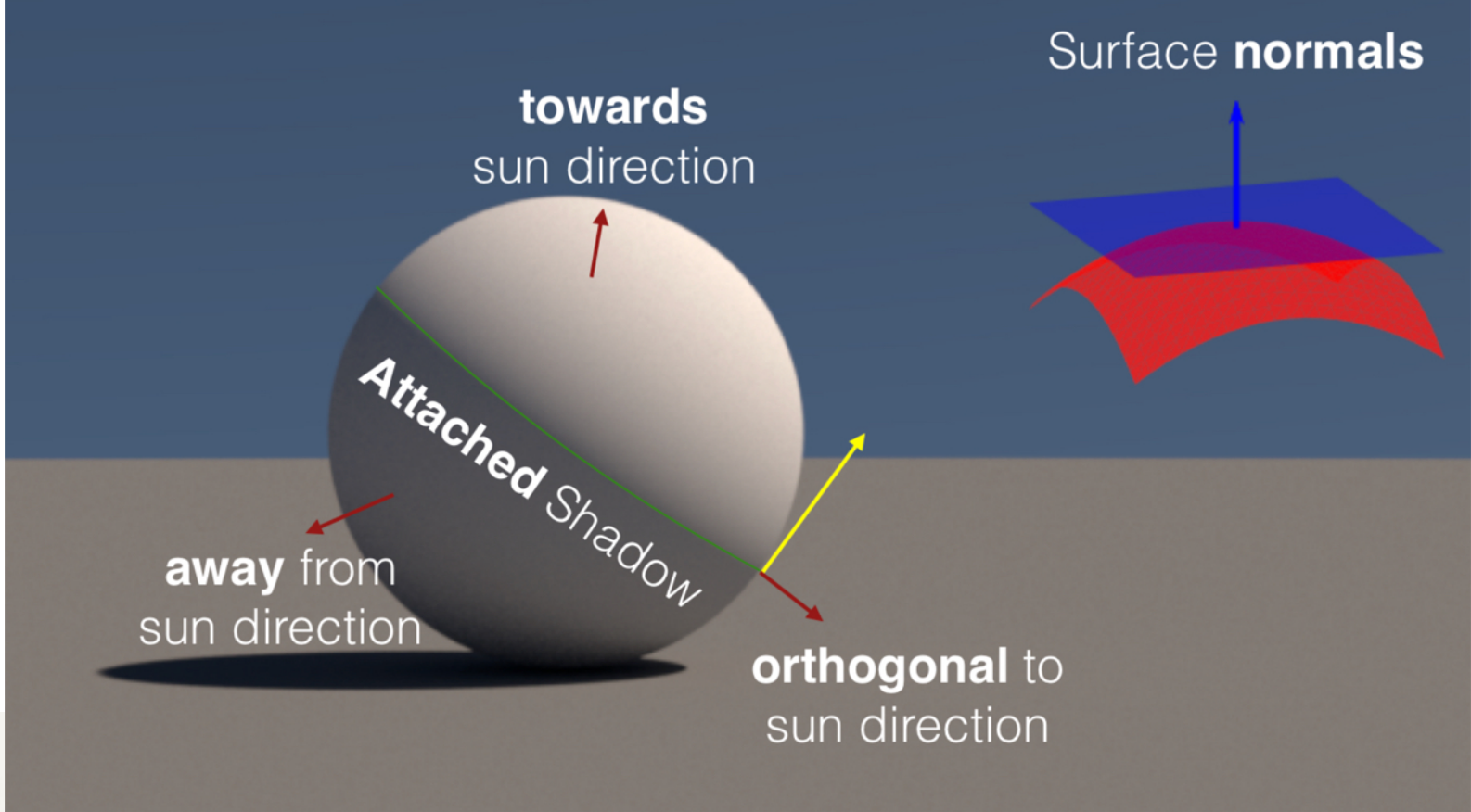
Shadowed

My Work: Illumination Estimation



-  Sunlit
-  Shadowed

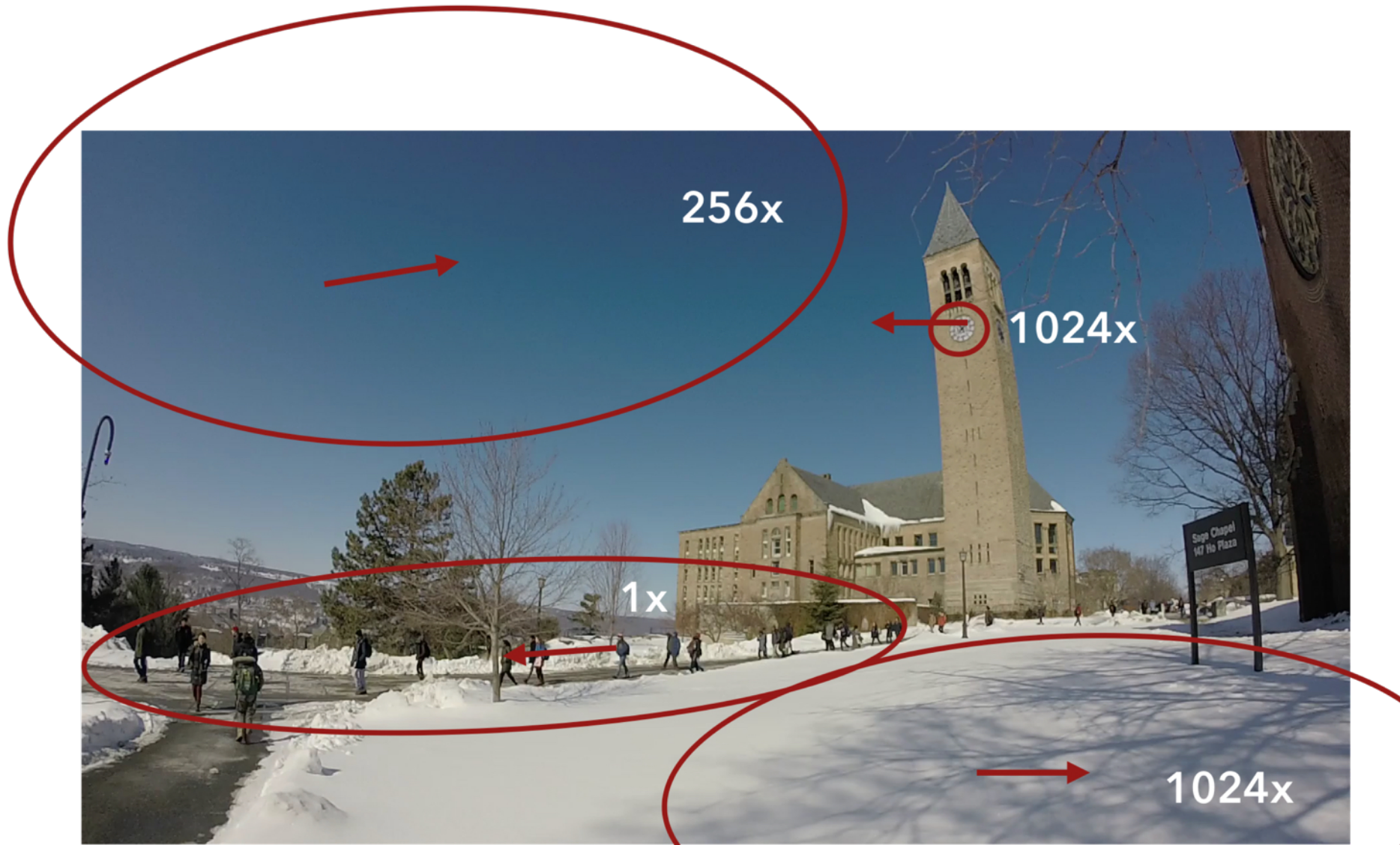




My Work: Timelapse Visualization



My Work: Timelapse Visualization



My Work: Timelapse Visualization



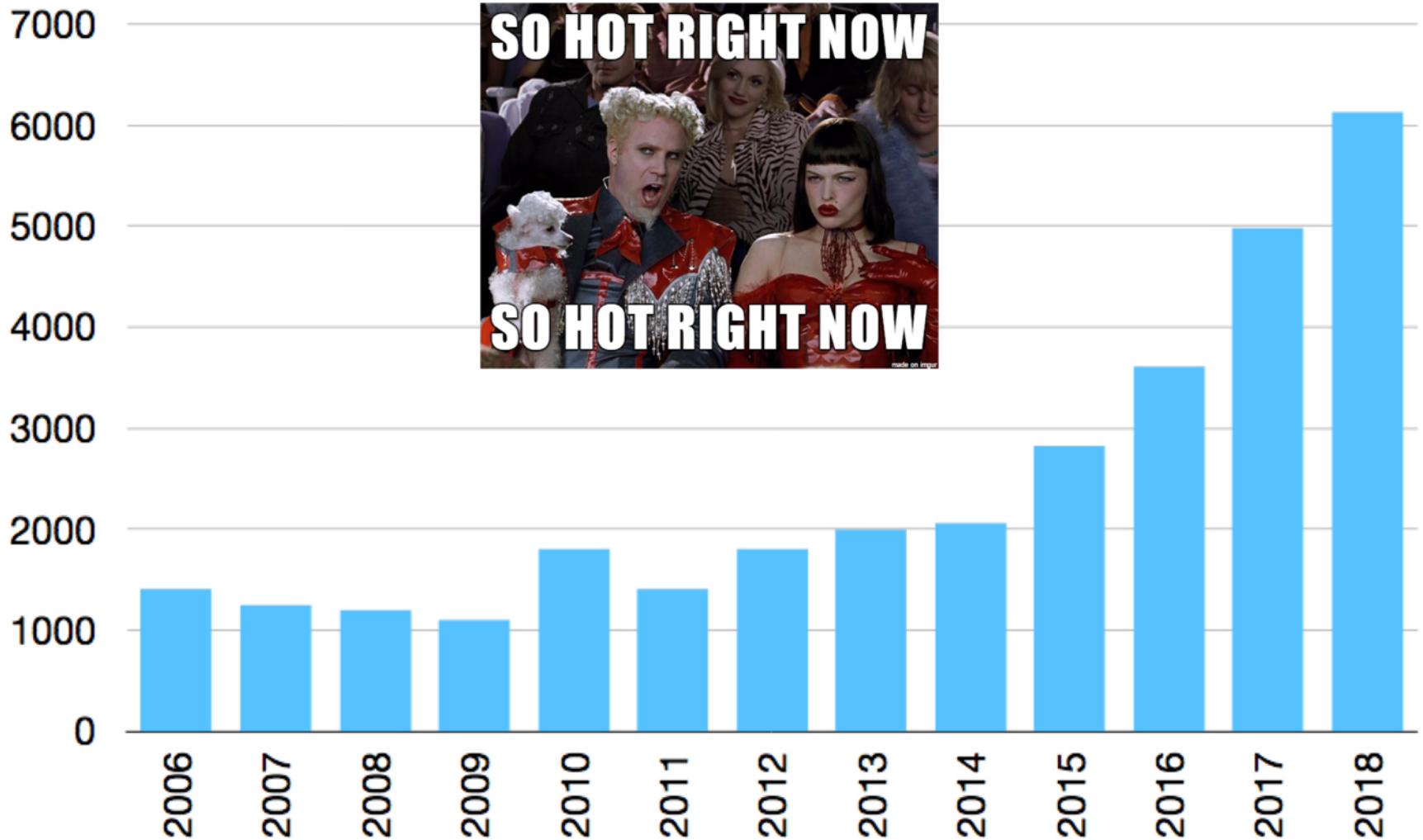
My Work: Timelapse Visualization



My Work: Timelapse Visualization



CVPR Attendance





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AND THE VIRTUALLY IMPOSSIBLE.

xkcd

9/24/2014

Introducing: Flickr P*ARK* or B*IRD*

flickr

10/20/2014

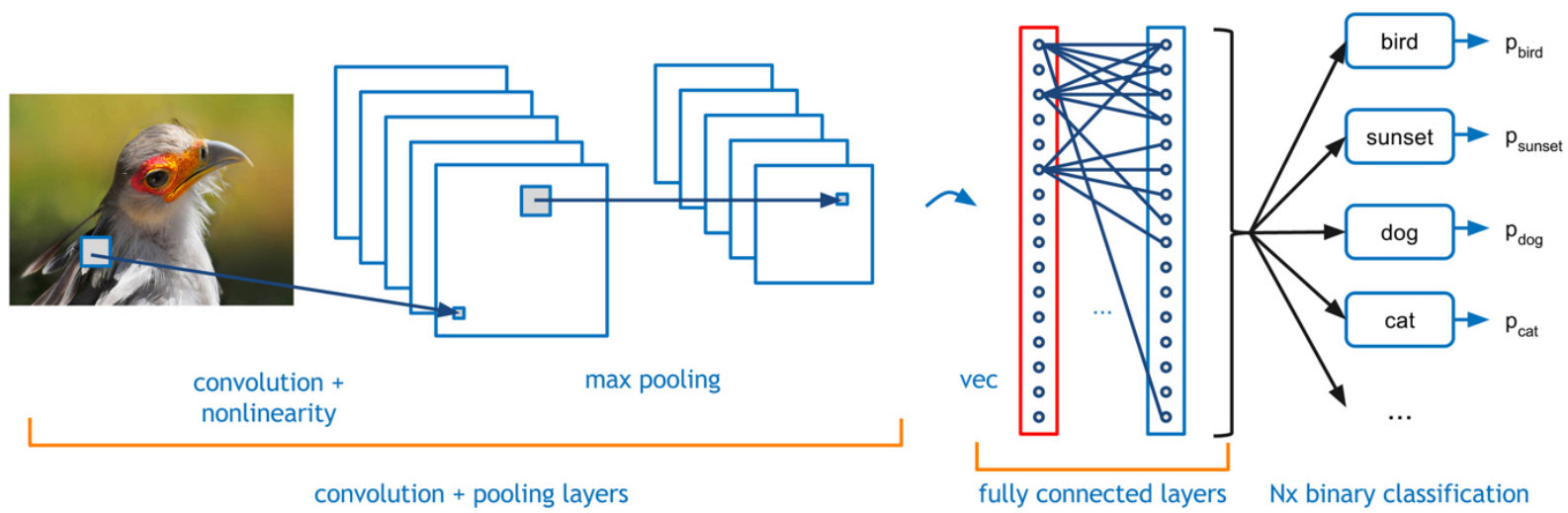


Zion National Park Utah by Les Haines

OR



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Motion (Source: S. Lazebnik)

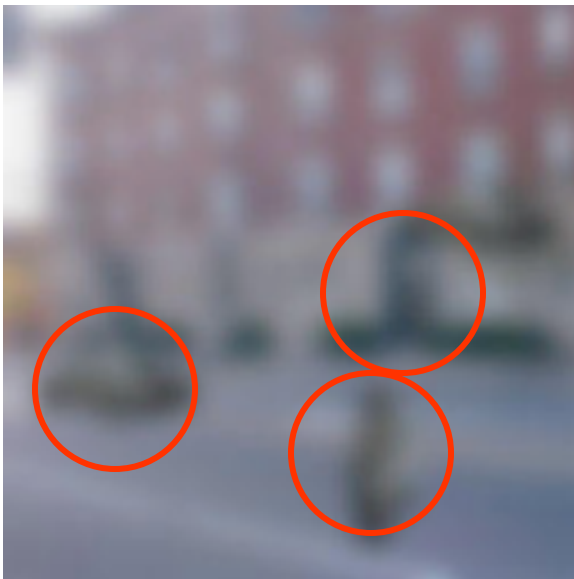
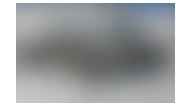
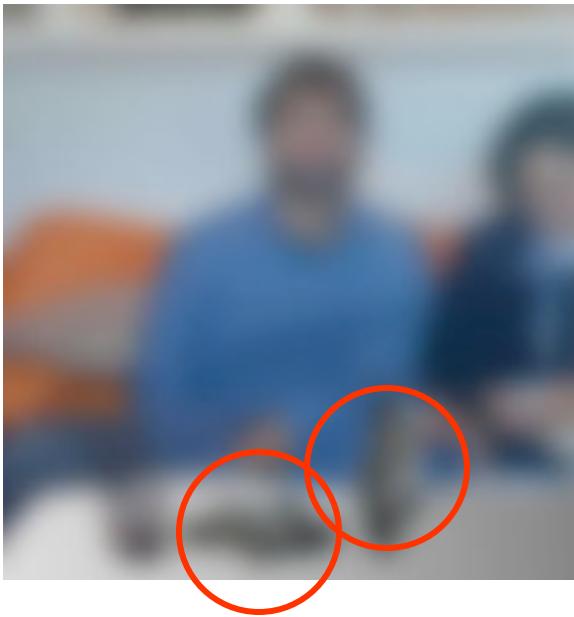


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Oct 22, 2012



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- You recognize Obama from the few pixels that make up his face. It helps that he is in his suit and that he is surrounded by other people with suits.
- You recognize that there's a person standing on a scale, even though the scale occupies only very few white pixels that blend with the background. But, you've used the person's pose and knowledge of how people interact with objects to figure it out.
- You recognize that Obama has his foot positioned just slightly on top of the scale. Notice the language I'm using: It is in terms of the 3D structure of the scene, not the position of the leg in the 2D coordinate system of the image.
- You know how physics works: Obama is leaning in on the scale, which applies a force on it. Scale measures force that is applied on it, that's how it works => it will over-estimate the weight of the person standing on it.
- The person measuring his weight is not aware of Obama doing this. You derive this because you know his pose, you understand that the field of view of a person is finite, and you understand that he is not very likely to sense the slight push of Obama's foot.
- You understand that people are self-conscious about their weight. You also understand that he is reading off the scale measurement, and that shortly the over-estimated weight will confuse him because it will probably be much higher than what he expects. In other words, you reason about implications of the events that are about to unfold seconds after this photo was taken, and especially about the thoughts and how they will develop inside people's heads. You also reason about what pieces of information are available to people.
- There are people in the back who find the person's imminent confusion funny. In other words you are reasoning about state of mind of people, and their view of the state of mind of another person. That's getting frighteningly meta.
- Finally, the fact that the perpetrator here is the president makes it maybe even a little more funnier. You understand what actions are more or less likely to be undertaken by different people based on their status and identity.

Course Logistics

Course webpage / Syllabus:

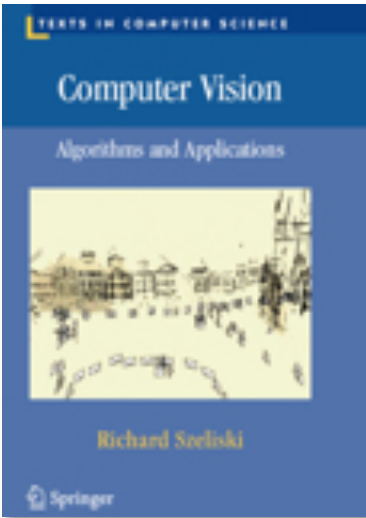
https://facultyweb.cs.wvu.edu/~wehrwes/courses/csci497_19w/

(link is also available on Syllabus page of Canvas)

Textbook:

Rick Szeliski, *Computer Vision: Algorithms and Applications*

online at: <http://szeliski.org/Book/>



Course Logistics

Announcements/grades via Canvas

Q&A via [Piazza](#) – you'll get an email invite to join

Assessment (tentative)

- 5(?) programming projects, all in Python
 - Distributed and submitted via Github
 - Some will be done in pairs, some individually
- Midterm and final exams
- Possible written homeworks
- Possible quick quizzes at the beginning of class