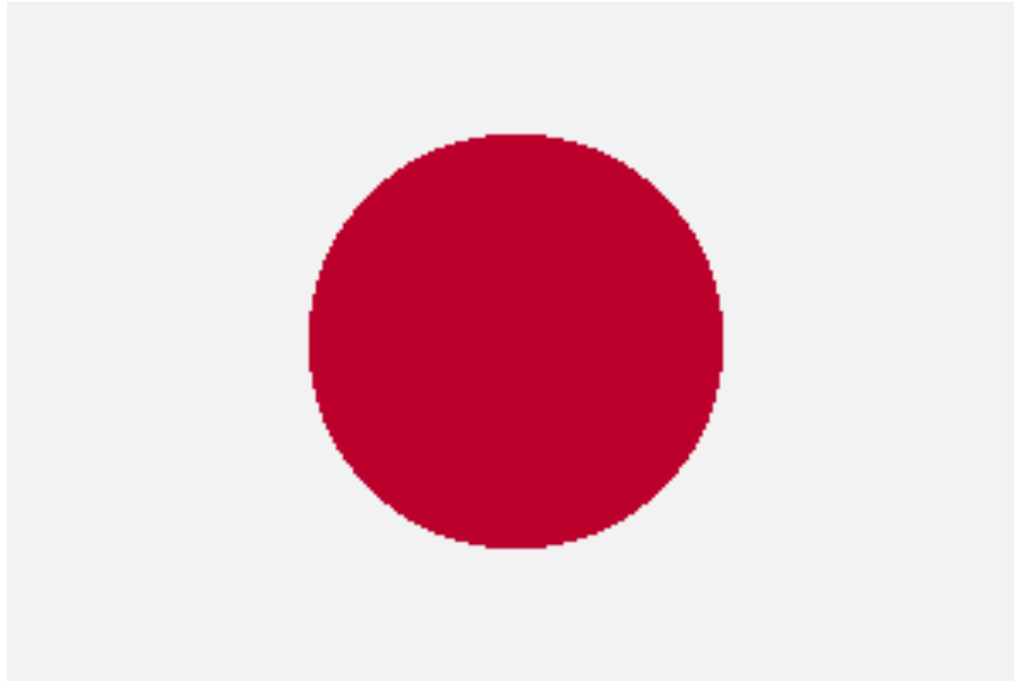


# Computer Graphics

Lecture 8

**Ray-Sphere Intersection**



# Computer Graphics

Lecture 8

**Ray-Sphere Intersection**

# Announcements

- A1 is done in pairs - if you don't have a partner yet, let's do some pairing at the end of class.
  - Partners must be in the same section (480 or 580)

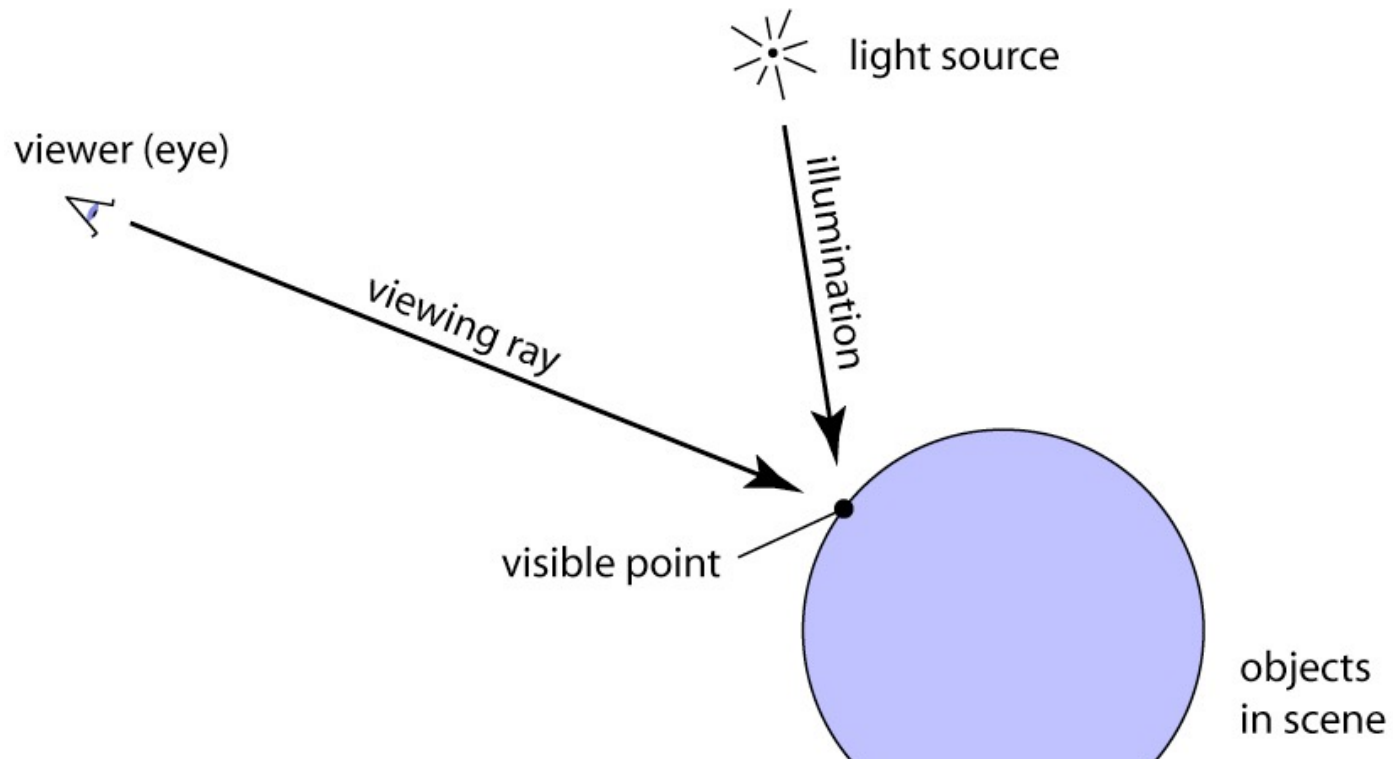
# Ray Tracing: Pseudocode

for each pixel:

generate a viewing ray for the pixel

find the closest object it intersects

determine the color of the object



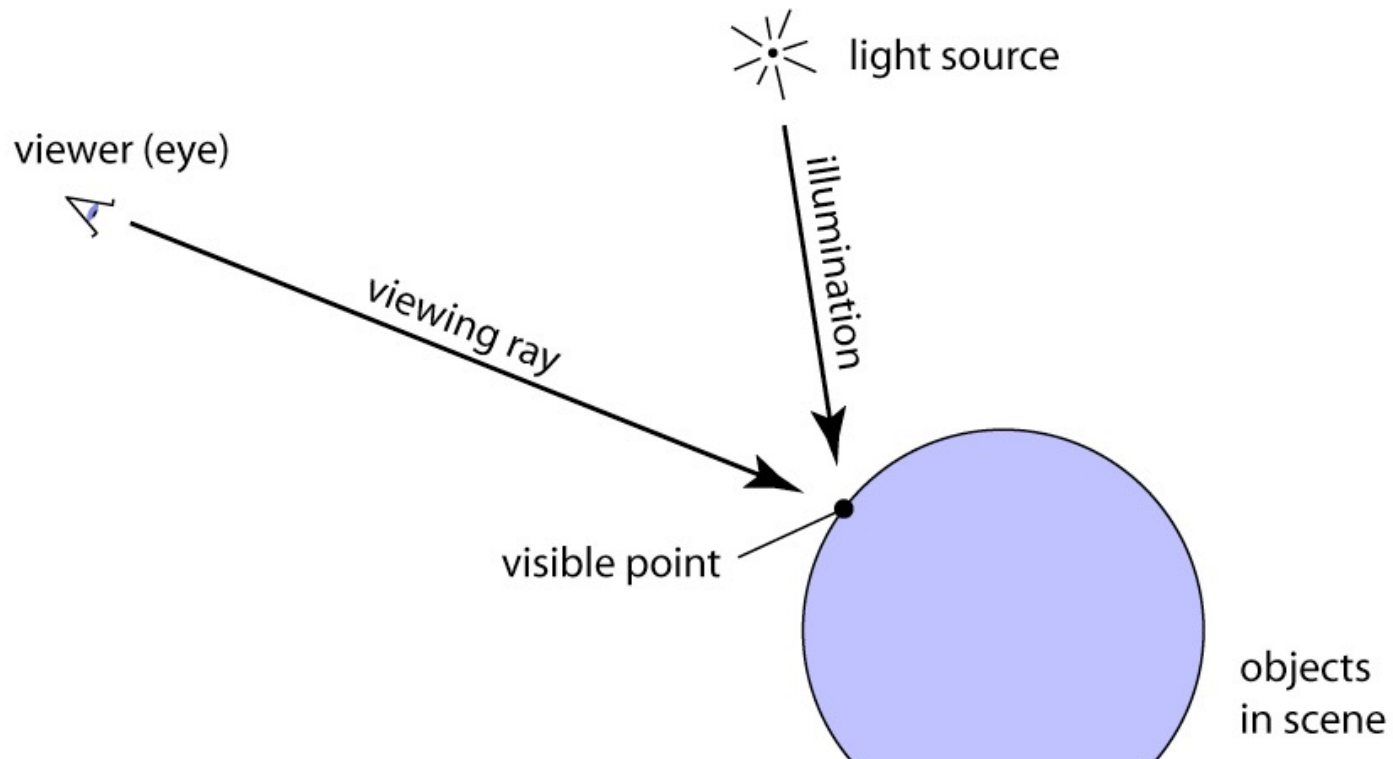
# Ray Tracing: Pseudocode

for each pixel:

generate a viewing ray for the pixel

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# Reminder: Implicit vs Parametric

- Implicit equations: a property true at all points
  - e.g.,  $ax + by + c = 0$  for a line
- Parametric equations: use a free parameter variable to *generate* all points:
  - e.g.,  $\mathbf{r}(t) = \mathbf{p} + t\mathbf{d}$ , for a line

# Ray-Sphere Intersection

Ray (parametric):  $\mathbf{p} + t\mathbf{d} = \begin{bmatrix} p_x + td_x \\ p_y + td_y \\ p_z + td_z \end{bmatrix}$

Sphere (parametric):  $\begin{bmatrix} \cos \theta \sin \phi \\ \sin \theta \\ \cos \theta \cos \phi \end{bmatrix}$

In principle: set these equal and solve for  $t, \theta, \phi$

In practice: math is cleanest when intersecting **implicit** with **parametric**.

# Ray-Sphere Intuition: Geometric

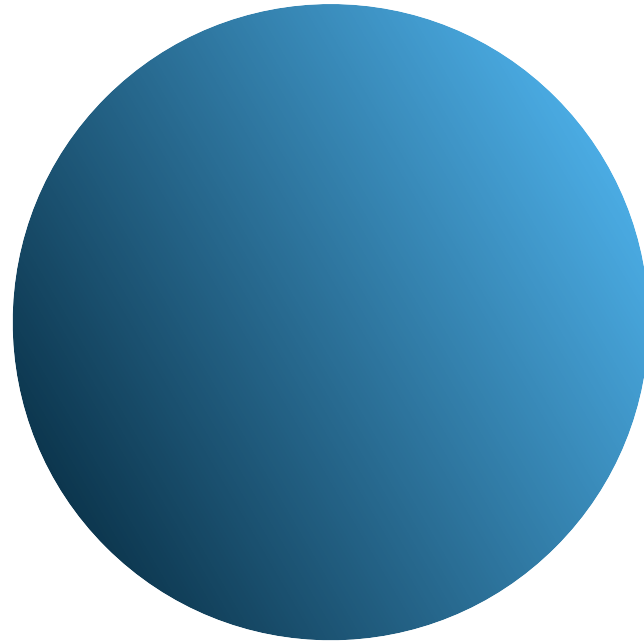
Ponder:

1. How many times might a ray intersect a sphere? What are the possibilities?
2. What's an implicit equation for a sphere?  
or: What's true of all points on a sphere?
  - For now, assume a unit sphere at the origin.



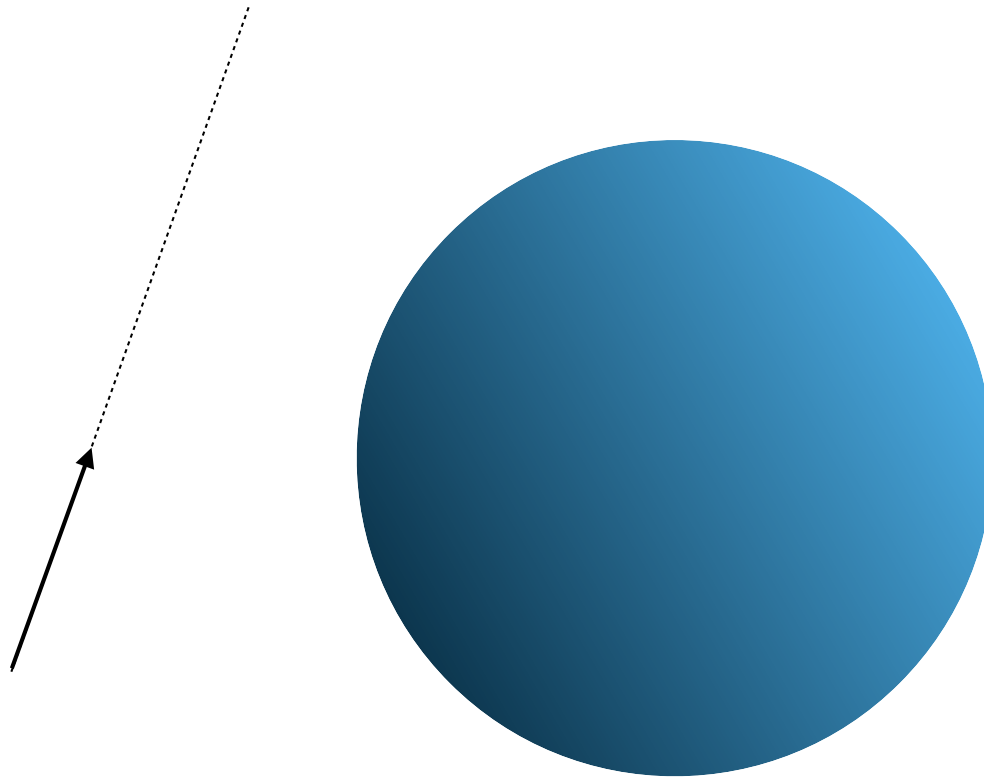
# Ray-Sphere Intuition: Geometric

How many times can ray intersect a sphere?



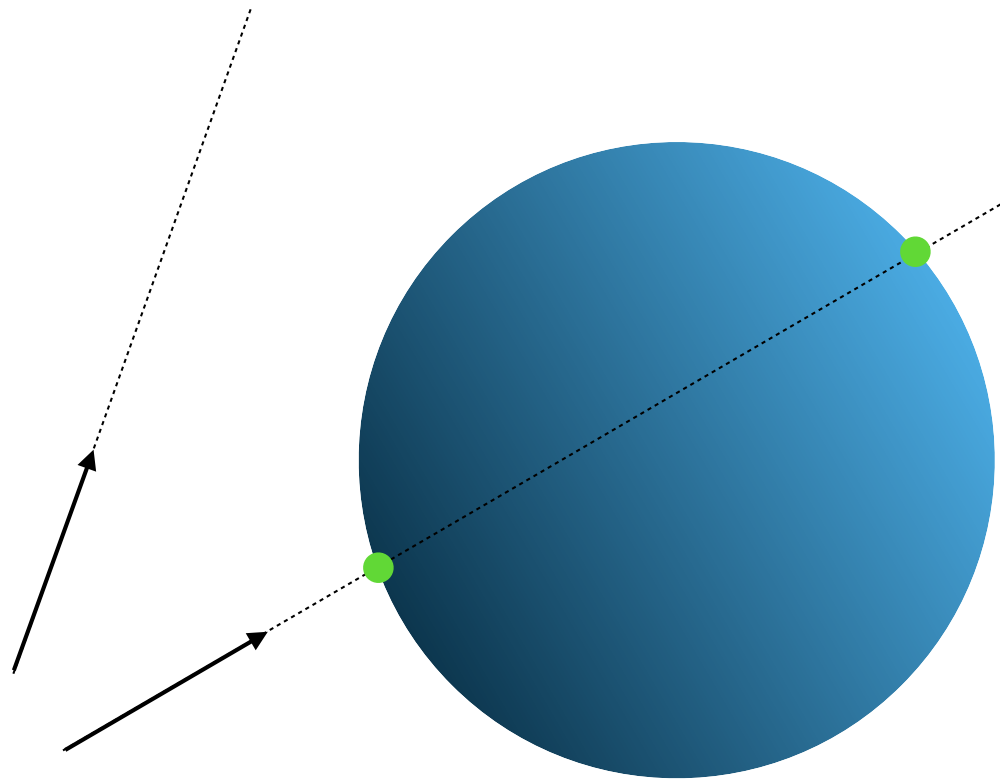
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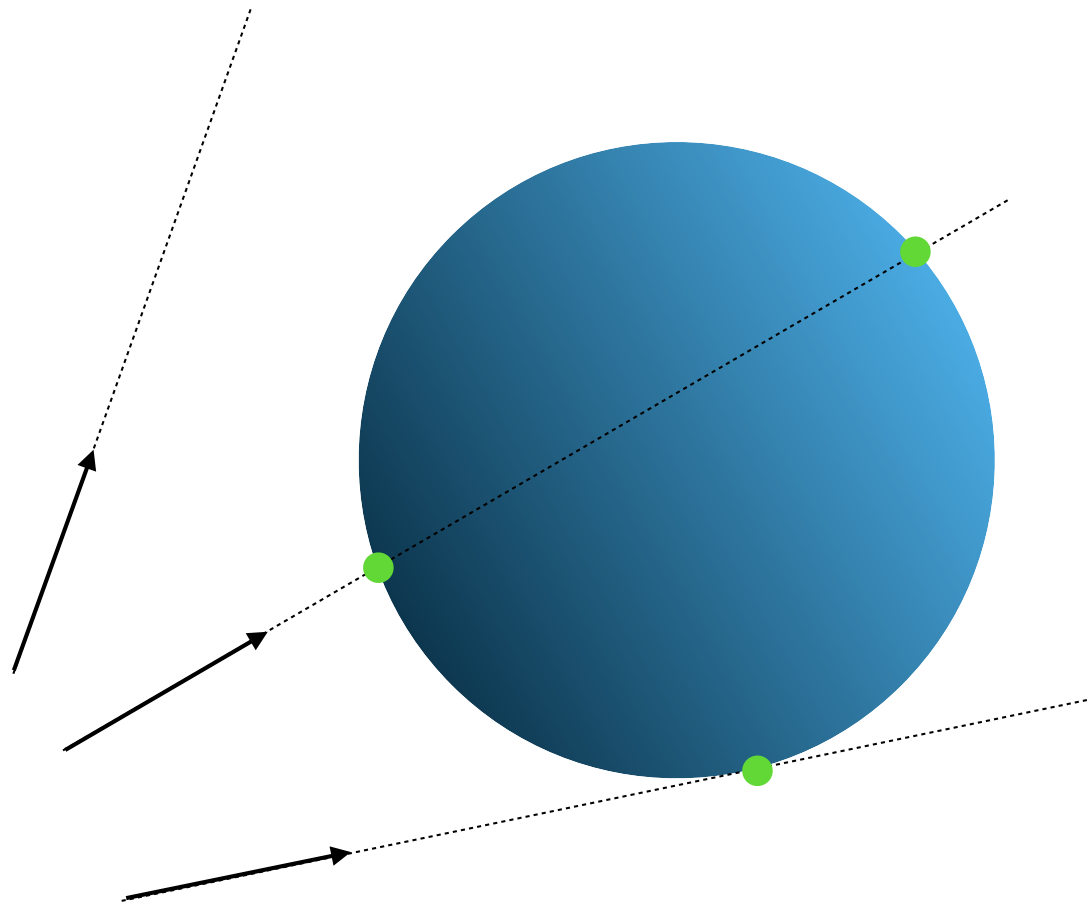
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How many times can ray intersect a sphere?



# Ray-Sphere Intuition: Geometric

How many times can ray intersect a sphere?

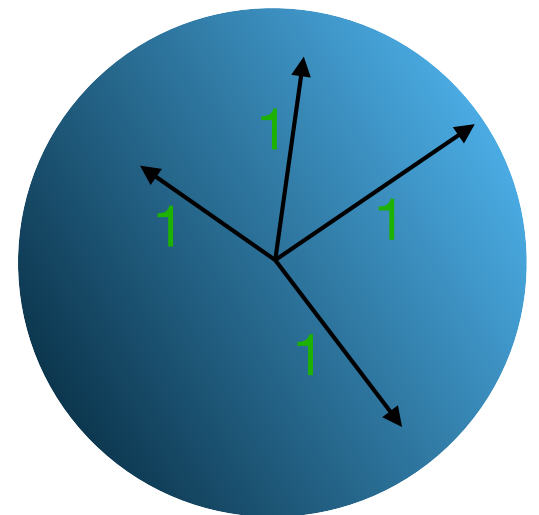


# Ray-Sphere Intuition: Geometric

1. How many times can ray intersect a sphere? 0, 1, or 2.
2. What's an implicit equation for a sphere?  
or: What's true of all points on a sphere?

They're all equidistant from the center.

For a unit sphere at the origin,  
they're all distance **1** from  $(0, 0, 0)$



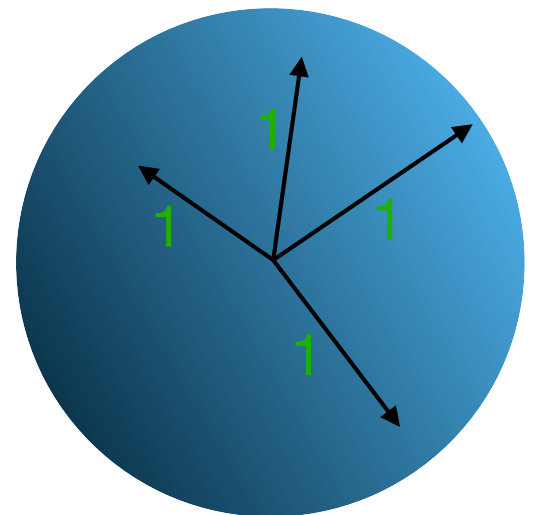
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For a unit sphere at the origin,  
they're all distance **1** from (0, 0, 0)

$$\sqrt{x^2 + y^2 + z^2} = 1$$



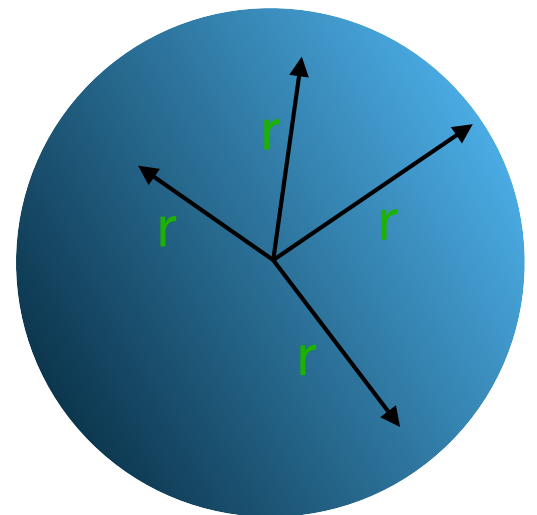
# Ray-Sphere Intuition: Geometric

1. How many times can ray intersect a sphere? 0, 1, or 2.
2. What's an implicit equation for a sphere?  
or: What's true of all points on a sphere?

They're all equidistant from the center.

For **any** sphere at the origin,  
they're all distance  $r$  from  $(0, 0, 0)$

$$\sqrt{x^2 + y^2 + z^2} = r$$



# Ray-Sphere Intersection: Algebraic

$$\vec{a} \cdot \vec{a} = \vec{a}^T \vec{a}$$



Ray:  $\vec{p} + t\vec{d}$

Sphere:  $\sqrt{x^2 + y^2 + z^2} = 1$

$$x^2 + y^2 + z^2 = 1^2$$

$$x^2 + y^2 + z^2 - 1 = 0$$

Let  $\vec{a} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ . Then:

$$x^2 + y^2 + z^2 - 1 = 0$$

$$\vec{a} \cdot \vec{a} - 1 = 0$$



Substitute:

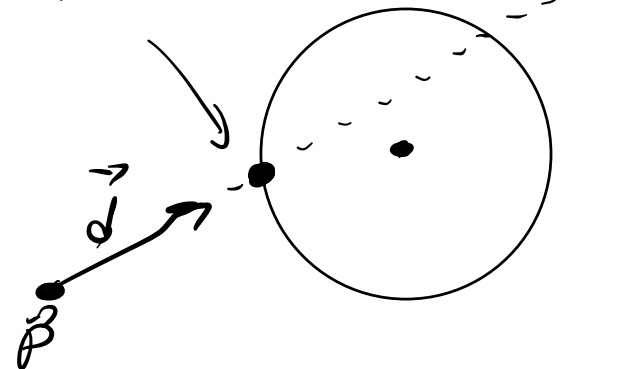
$$(\vec{p} + t\vec{d})^T (\vec{p} + t\vec{d}) - 1 = 0$$

LOZF:

$$d \cdot d t^2 + (2p \cdot d)t + p \cdot p - 1 = 0$$

$$A t^2 + B t + C = 0$$

$$\vec{p} + t\vec{d}$$





$$t = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$$

$$t = \frac{-d \cdot p \pm \sqrt{(d \cdot p)^2 - (d \cdot d)(p \cdot p - 1)}}{d \cdot d}$$

$$p + t \vec{d}$$

# Number of Intersections

$$t = \frac{-\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - (\mathbf{d} \cdot \mathbf{d})(\mathbf{p} \cdot \mathbf{p} - 1)}}{\mathbf{d} \cdot \mathbf{d}}$$

Given only  $\mathbf{d}$  and  $\mathbf{p}$ , how can you tell how many intersections the ray has with the sphere?

# Ray-Sphere intersection

For now, assume unit sphere centered at the origin. See 4.4.1 for general derivation.

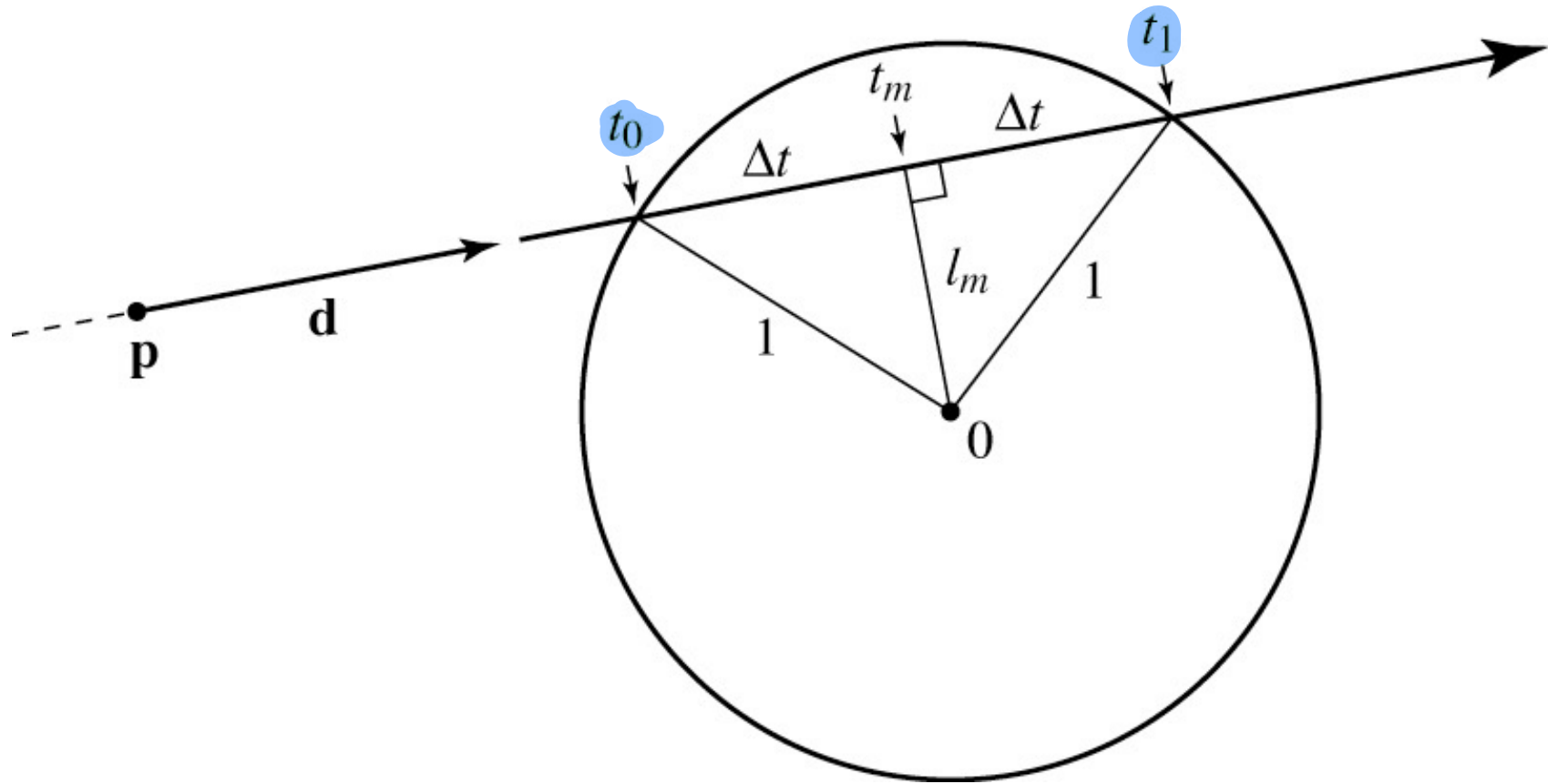
$$t = \frac{-\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - (\mathbf{d} \cdot \mathbf{d})(\mathbf{p} \cdot \mathbf{p} - 1)}}{\mathbf{d} \cdot \mathbf{d}}$$

If  $\mathbf{d}$  were normalized to unit-length, this reduces to:

$$t = -\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$

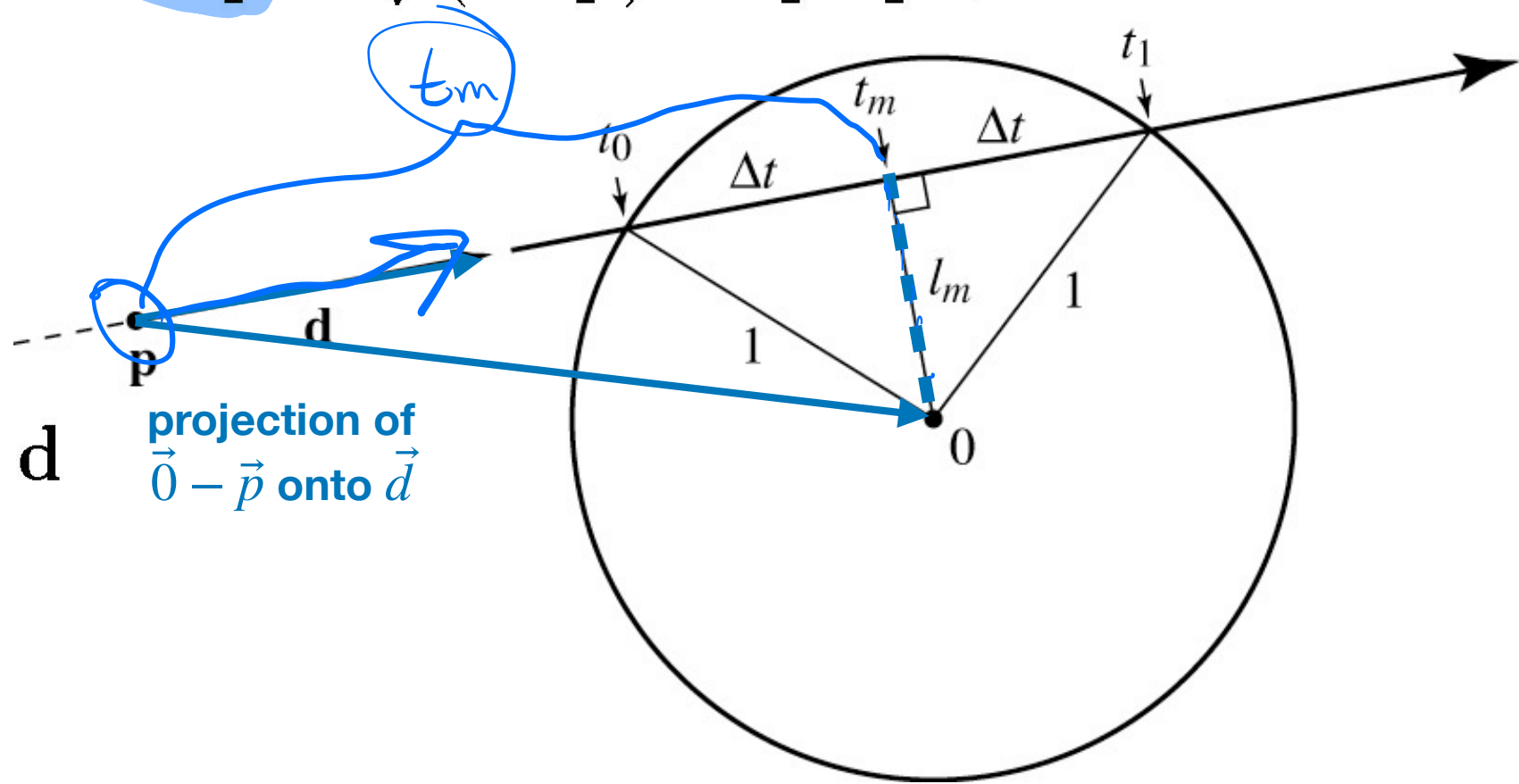
# Geometric Intuition

$$t = -\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$



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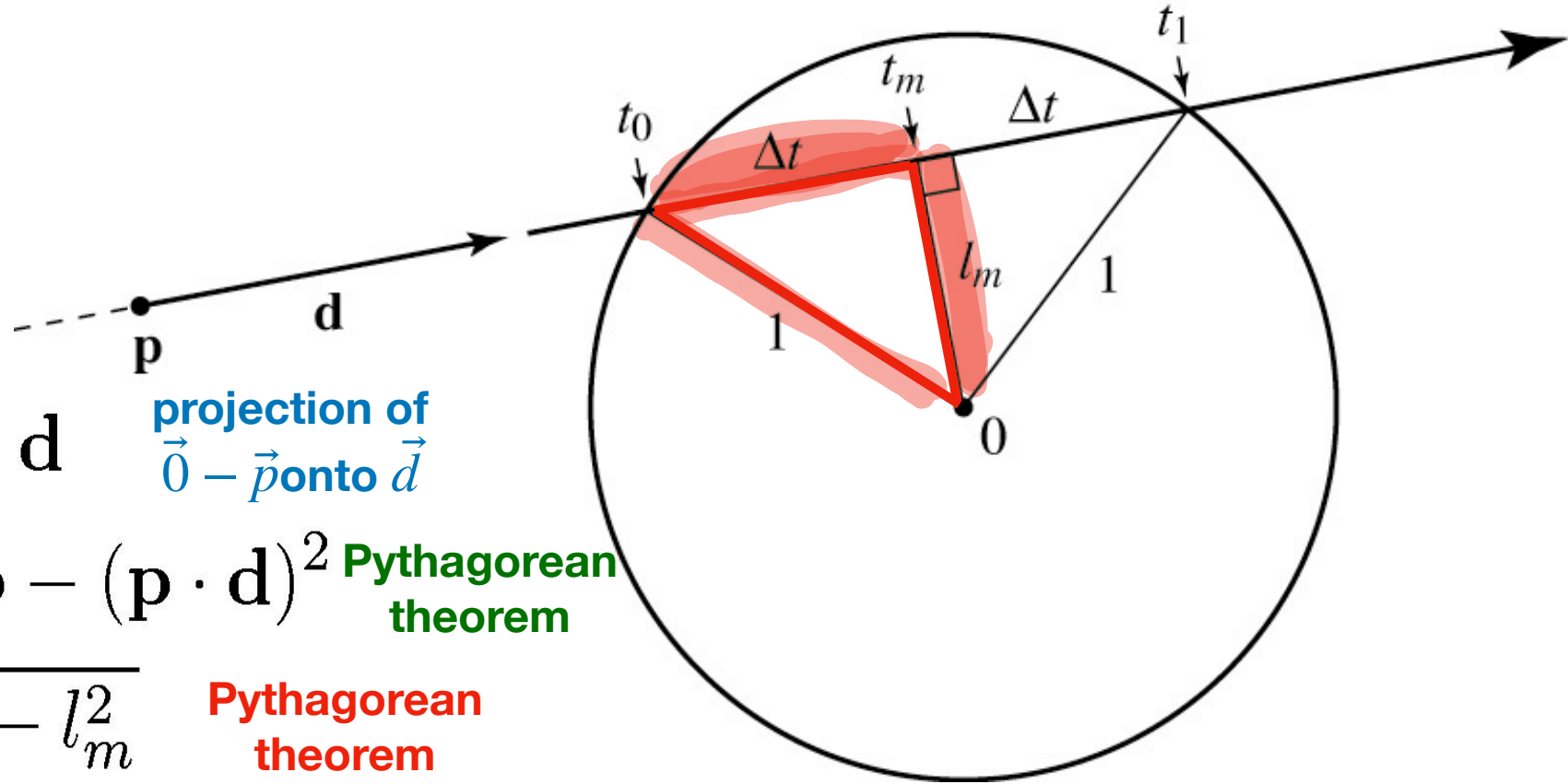


$t_m = -\mathbf{p} \cdot \mathbf{d}$  projection of  $\vec{0} - \vec{p}$  onto  $\vec{d}$



# Geometric Intuition

$$t = -\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$



$$t_m = -\mathbf{p} \cdot \mathbf{d} \quad \text{projection of } \vec{0} - \vec{p} \text{ onto } \vec{d}$$

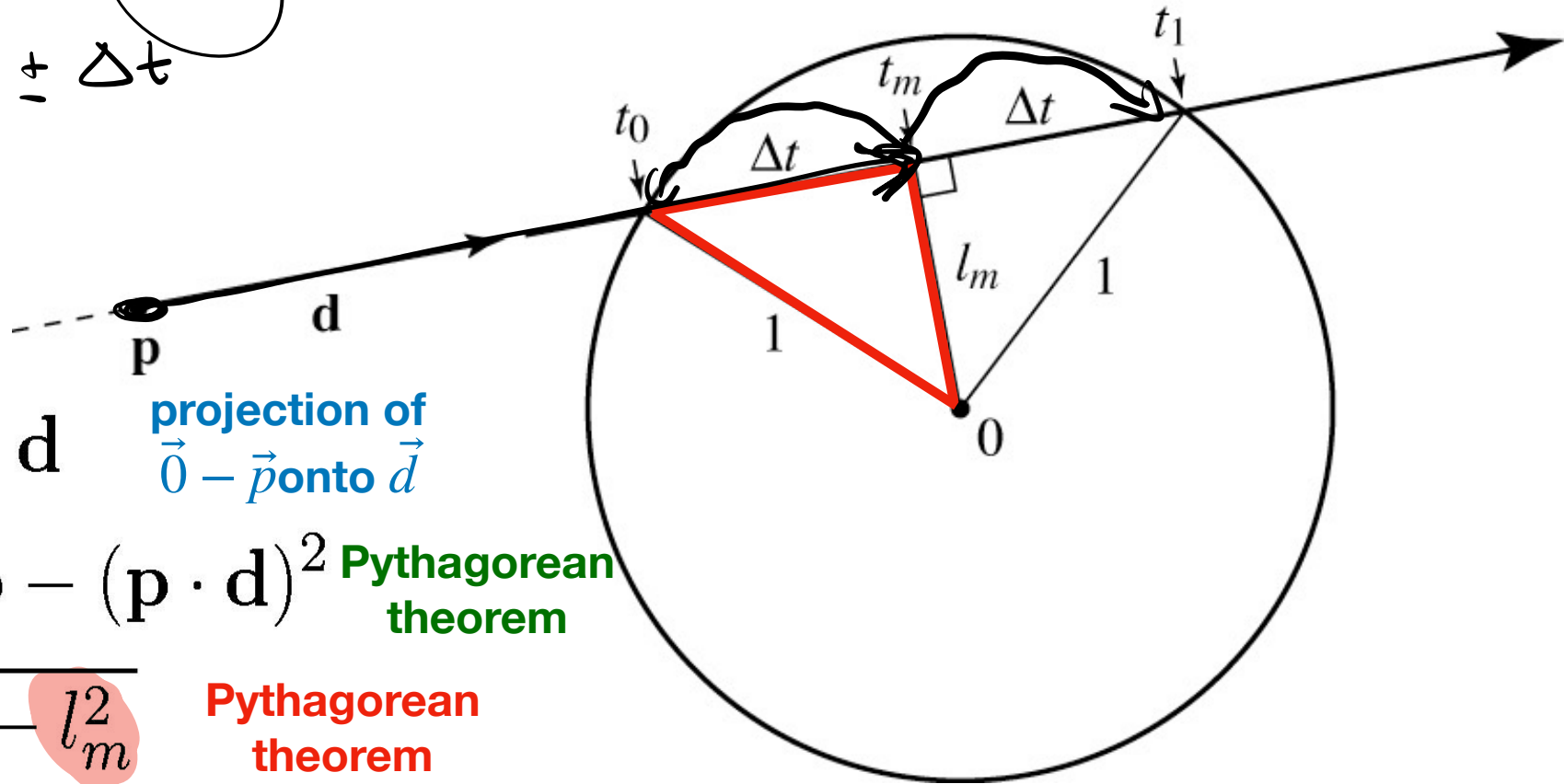
$$l_m^2 = \mathbf{p} \cdot \mathbf{p} - (\mathbf{p} \cdot \mathbf{d})^2 \quad \text{Pythagorean theorem}$$

$$\Delta t = \sqrt{1 - l_m^2} \quad \text{Pythagorean theorem}$$

# Geometric Intuition

$$t = -\mathbf{d} \cdot \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \mathbf{p})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$

$$t = t_m \pm \Delta t$$



$$t_m = -\mathbf{p} \cdot \mathbf{d} \quad \text{projection of } \vec{0} - \vec{p} \text{ onto } \vec{d}$$

$$l_m^2 = \mathbf{p} \cdot \mathbf{p} - (\mathbf{p} \cdot \mathbf{d})^2 \quad \text{Pythagorean theorem}$$

$$\Delta t = \sqrt{1 - l_m^2} \quad \text{Pythagorean theorem}$$

$$= \sqrt{(\mathbf{p} \cdot \mathbf{d})^2 - \mathbf{p} \cdot \mathbf{p} + 1} \quad \text{plug and chug}$$

$$t_{0,1} = t_m \pm \Delta t = -\mathbf{p} \cdot \mathbf{d} \pm \sqrt{(\mathbf{p} \cdot \mathbf{d})^2 - \mathbf{p} \cdot \mathbf{p} + 1}$$



# Ray-Sphere: Code Sketch

```
function ray_intersect(ray, sphere, tmin, tmax):
```

- Use above math to find  $\pm t$   $0$   $\infty$   
 $\epsilon$
- If none, return nothing
- Otherwise, return closest  $t$  that lies between  $tmin$  and  $tmax$

# Ray-Scene: Code Sketch

**Brute force:** check all objects.

There are better ways - more on this later.

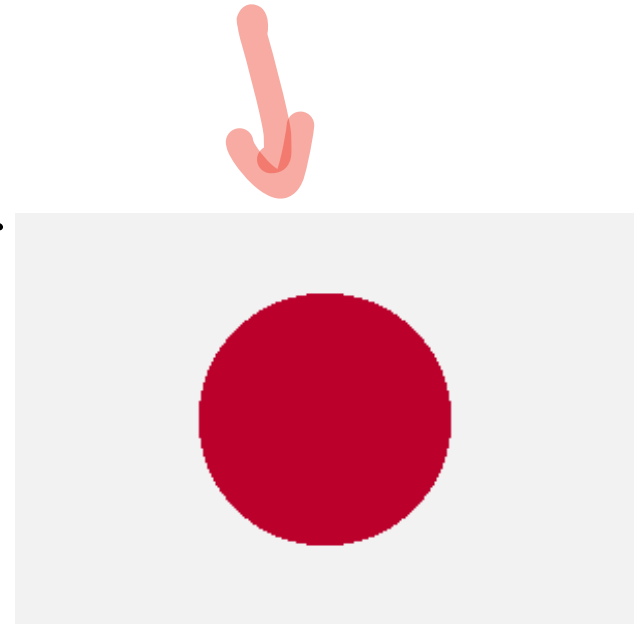
```
find_intersection(ray, scene):
    closest_t = Inf
    closest_obj = nothing
    for obj in scene:
        t = ray_intersect(ray, obj, 1, closest_t)
        if obj != nothing:
            closest_t = t
            closest_obj = surf
    return closest_t, closest_obj
```

# Ray Tracing: Code Sketch

```
scene = model_scene()
for each pixel (i,j):
    ray = get_view_ray(i, j)
    t, obj = find_intersection(ray, scene)
    if obj != nothing:
        canvas[i,j] = obj.color
    else:
        canvas[i,j] = scene.bgcolor
```

# Ray Tracing: Code Sketch

```
scene = model_scene()
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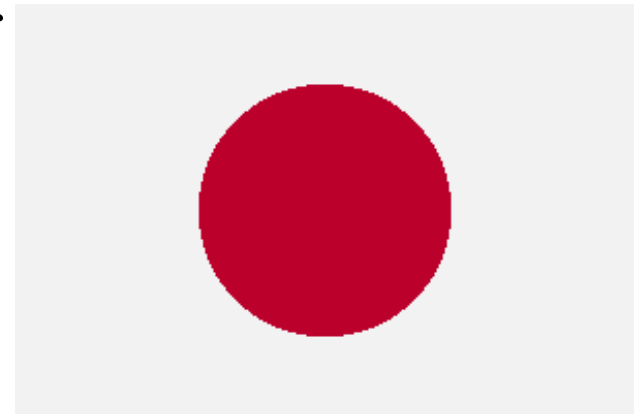


# Next time...

```
scene = model_scene()
for each pixel (i,j):
    ray = get_view_ray(i, j)
    t, obj = find_intersection(ray, scene)
    if obj != nothing:
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```

# Next time...

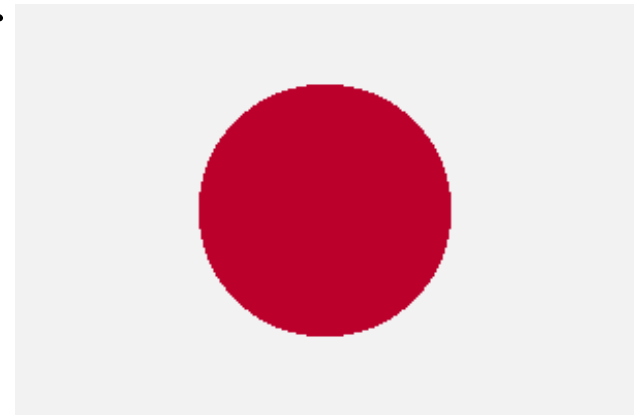
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    t, obj = find_intersection(ray, scene)  
    if obj != nothing:  
        canvas[i,j] = obj.color  
    else:  
        canvas[i,j] = scene.bgcolor
```

**Let's work on this.**



# Problems

- Write ray intersection code for axis-aligned rectangles.
- Model an empty Cornell box.

