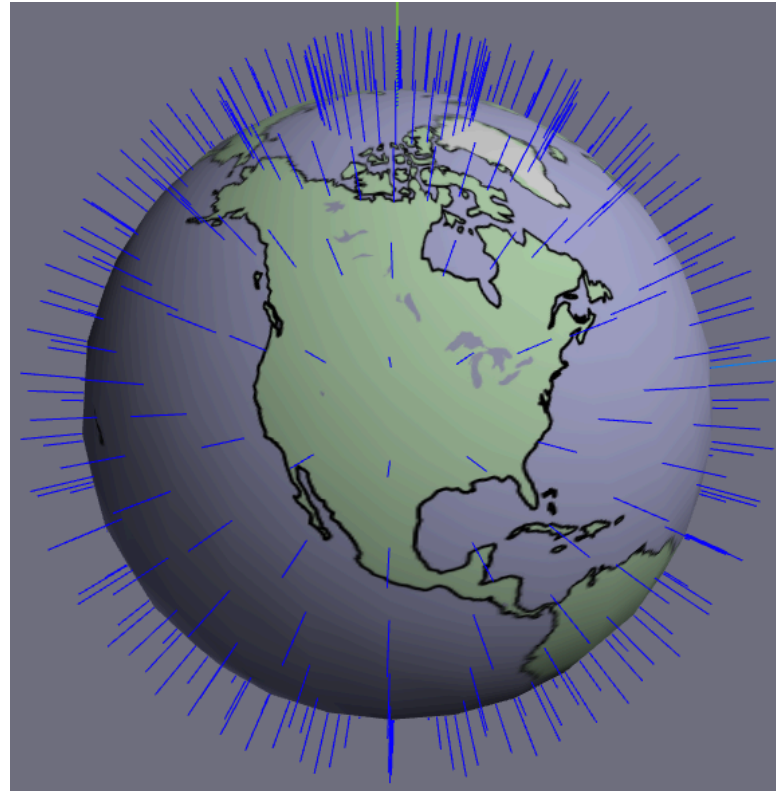


# Computer Graphics



## Lecture 3

### **Triangle Meshes: Surface Normals**

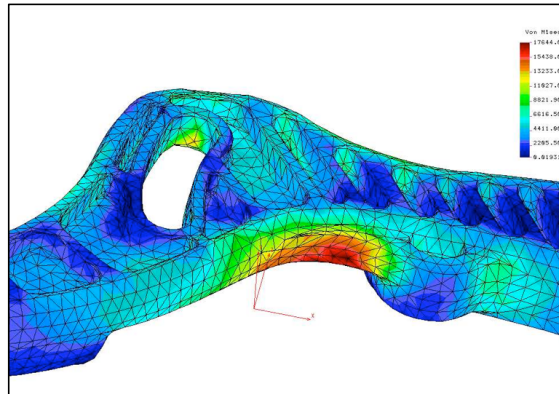
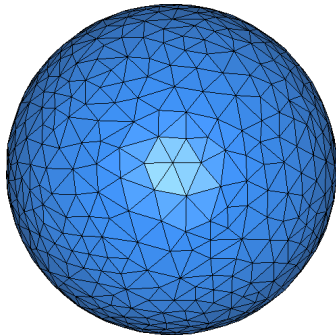
# Where are we?

Pseudocode for 3D graphics:

Create a model of a scene

Render an image of the model

Triangle meshes - one way to approximate arbitrary surfaces



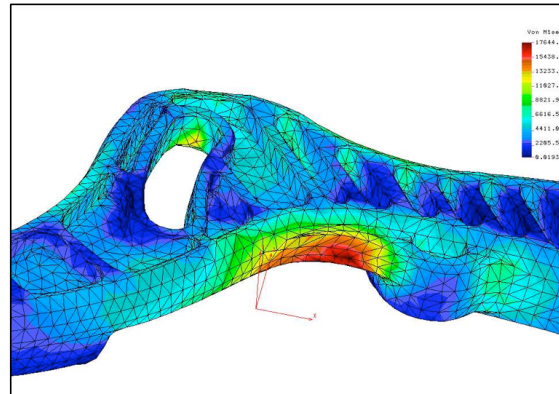
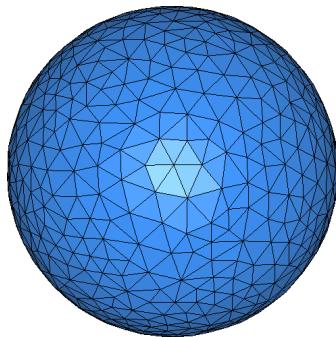
# Where are we?

Pseudocode for 3D graphics:

```
Create a model of a scene
```

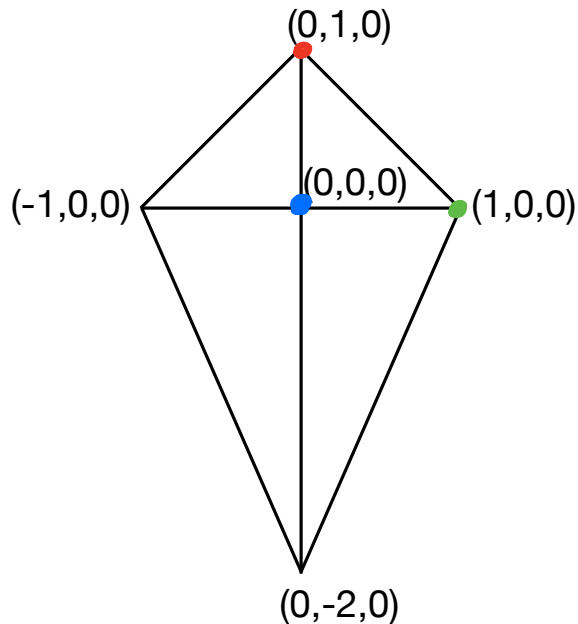
```
Render an image of the model
```

Triangle meshes - one way to approximate arbitrary surfaces



# OBJ Format: Positions

A file format for indexed triangle meshes



*positions*

```
1 v 0.0 0.0 0.0
2 v 1.0 0.0 0.0
3 v 0.0 1.0 0.0
v -1.0 0.0 0.0
v 0.0 -2.0 0.0
```

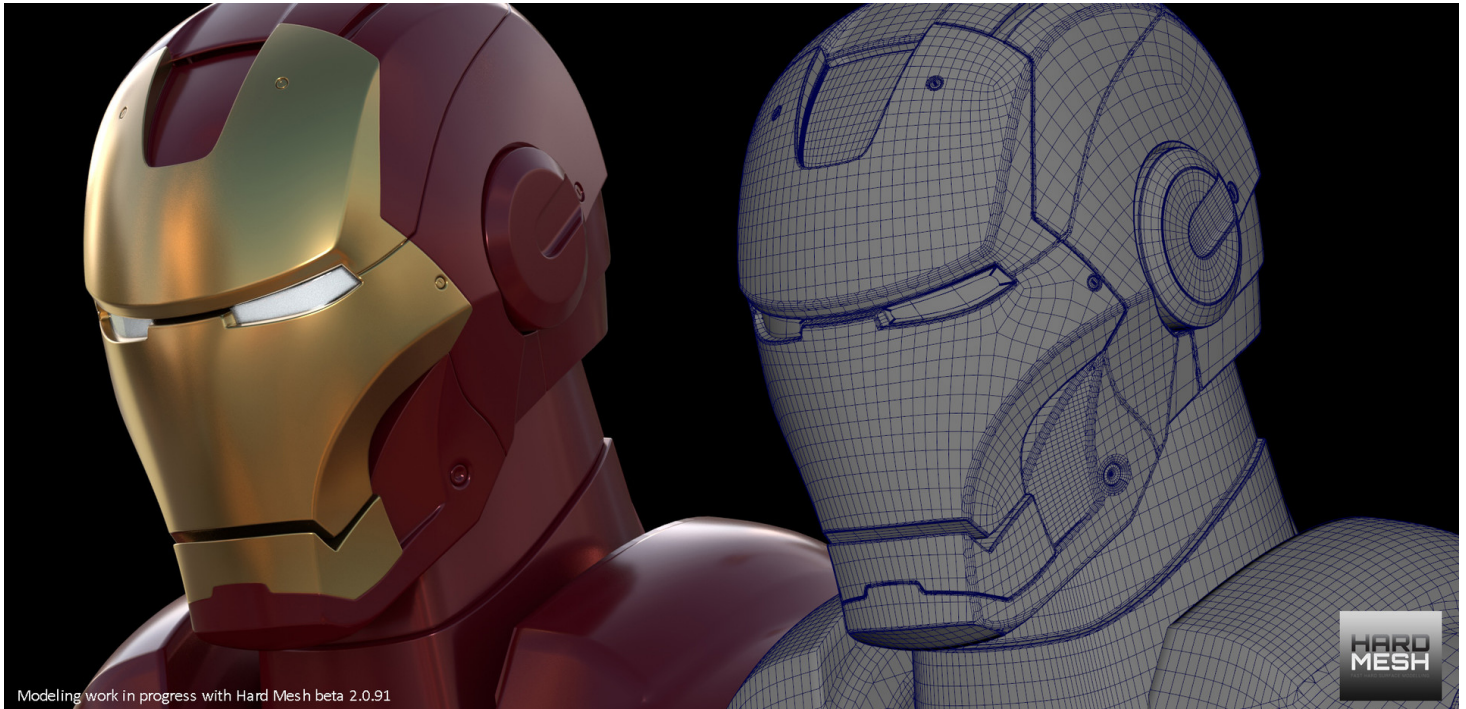
*faces  
triangles*

```
f 1 2 3
f 1 3 4
f 1 4 5
f 1 5 2
```

Demo: kite.obj, cube.obj

# Data on Meshes

To render realistic images, we'll need more than just the geometry.



# Data on Meshes

- We need more than just geometry.
- Where do we store it: **Vertices?** ~~Edges?~~ **Faces?**
- Examples:
  - colors stored on face, for faceted objects
  - information about sharp creases stored at edges
  - anything that varies continuously is stored at vertices

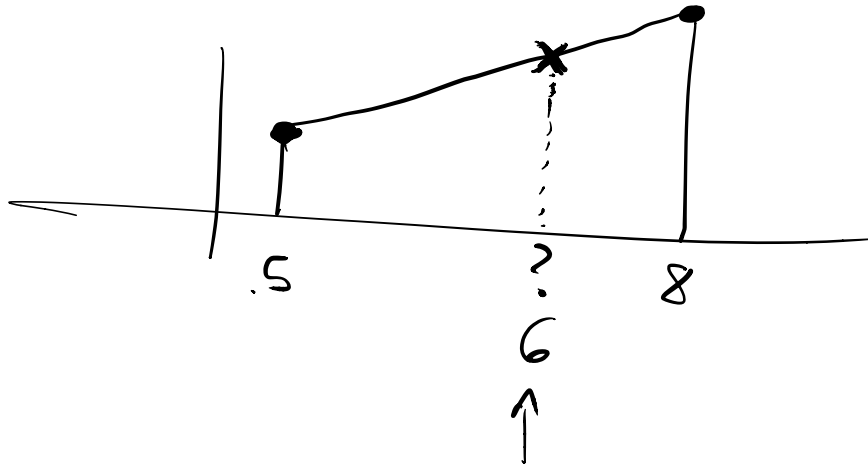
# Data on Meshes

- We need more than just geometry.
- Where do we store it: **Vertices**? Edges? **Faces**?
- Examples:
  - colors stored on face, for faceted objects
  - information about sharp creases stored at edges
  - anything that varies continuously is stored at vertices

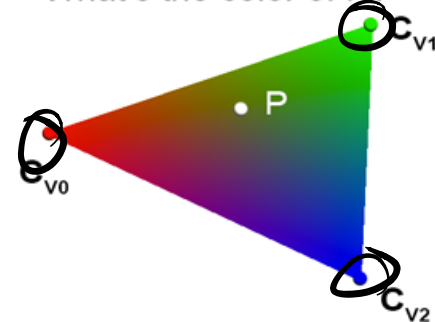
*when rendering, **interpolate** values in between*

# Interpolation - Intuition

Fill in missing values between known values



What's the color of P?

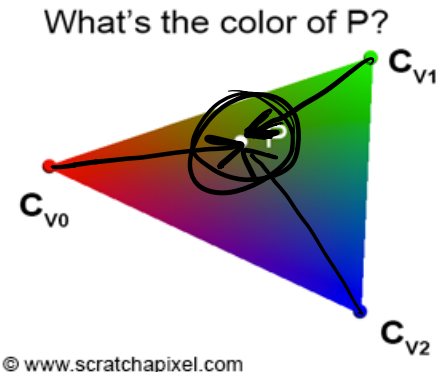




# Interpolation - Intuition

Fill in missing values between known values

How? This is a question for rendering.  
We'll talk about the specifics later.



# Data on Meshes

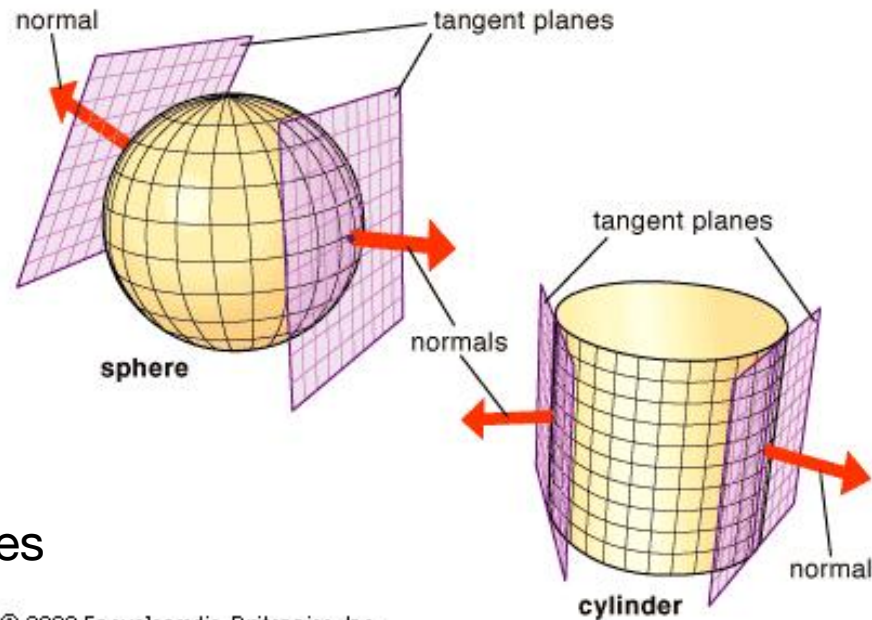
What do we need to store at vertices?

- **Surface Normals**  
to more accurately portray geometry
- **Texture Coordinates**  
to paste image data onto surfaces
- **Positions!?** (last lecture)  
just another piece of per-vertex data!



# Surface Normals - Formally

- A point on a smooth surface has a **tangent plane**
- A **normal vector** is orthogonal to the surface (i.e., its tangent plane).



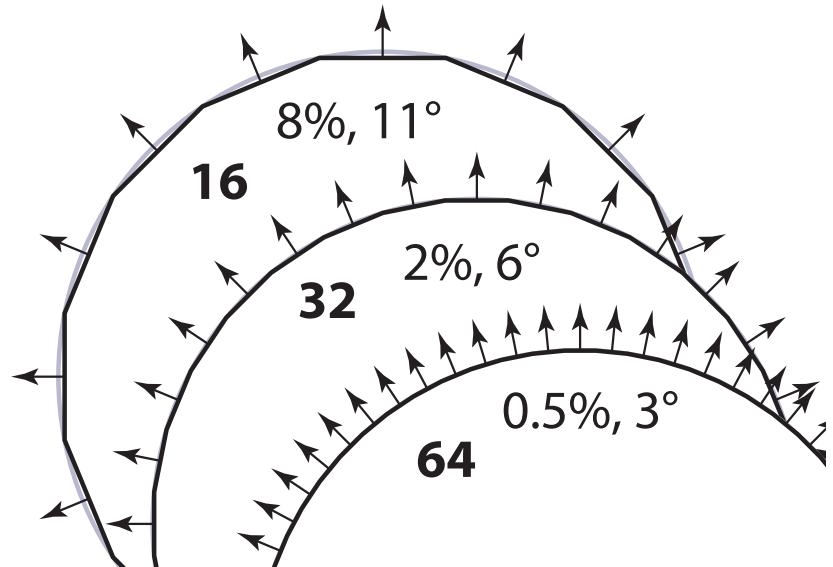
Only unique for smooth surfaces (i.e., not at corners or edges).

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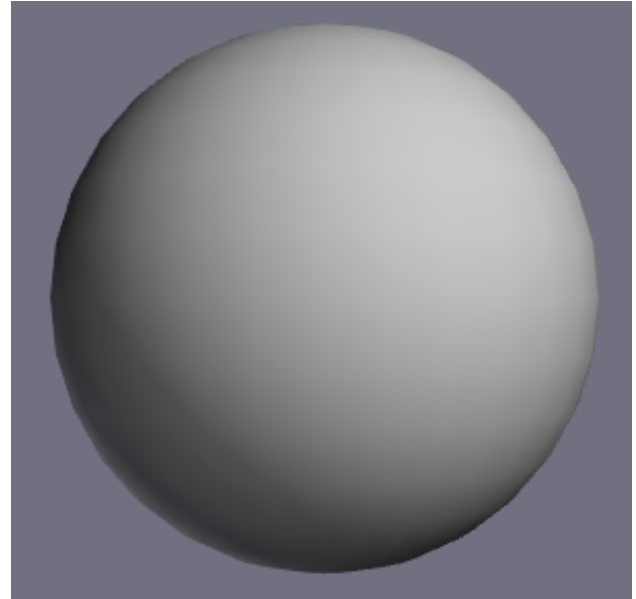
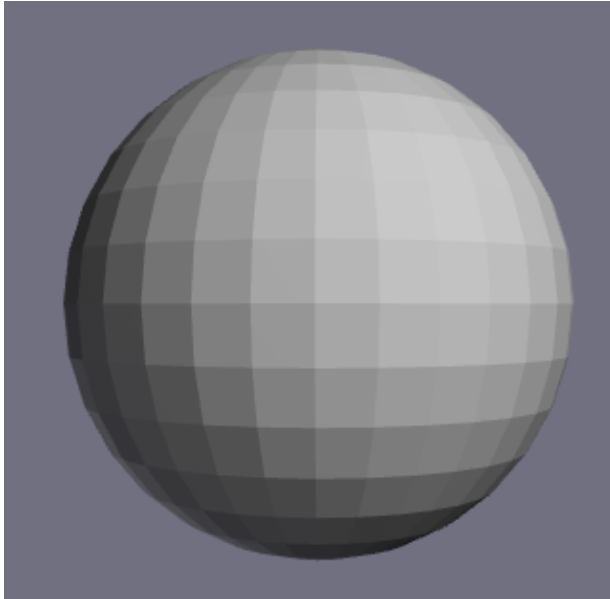
By convention, normal vectors are (usually) **unit length**.

# Why are normals important?

- Can't we just use more triangles?
- Error in surface normal shrinks slower than geometry
- Intuition - circle:

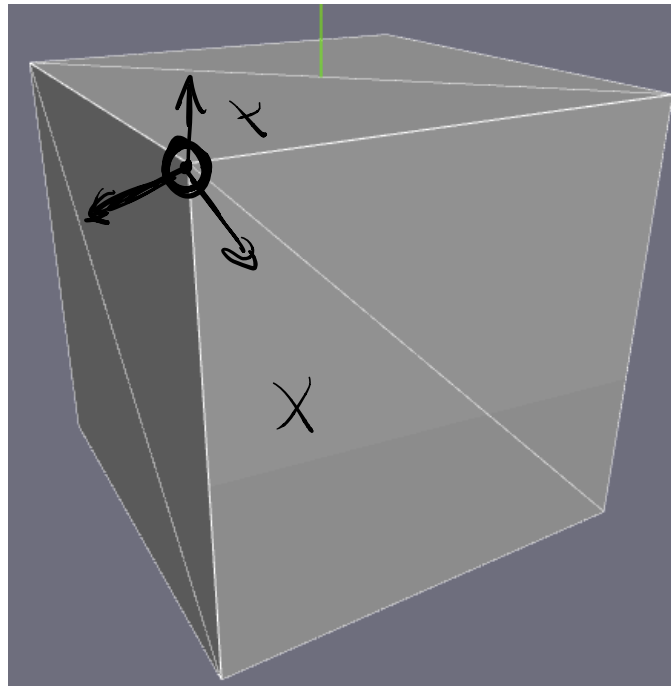


# Surface Normals: Visual Intuition

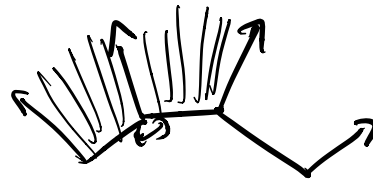
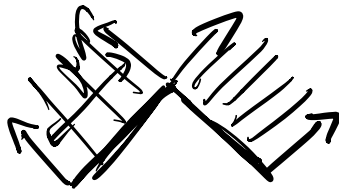
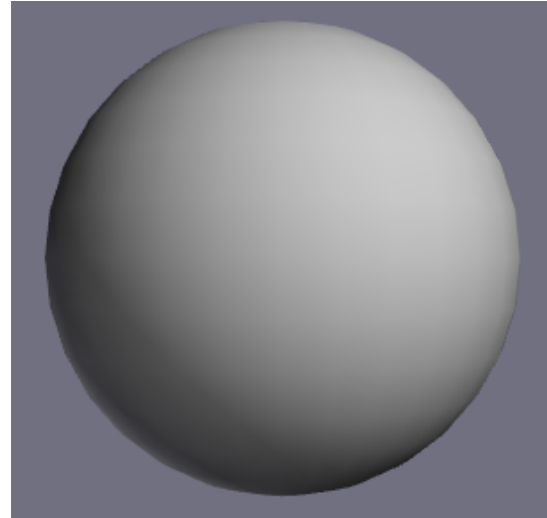
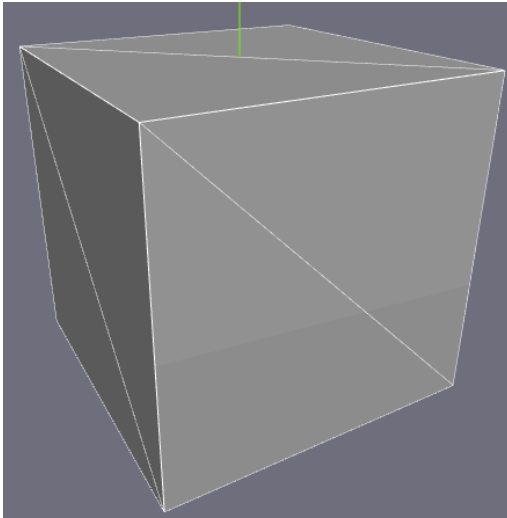


# Normals at Discontinuities

- What is the vertex normal at the corner of a cube?

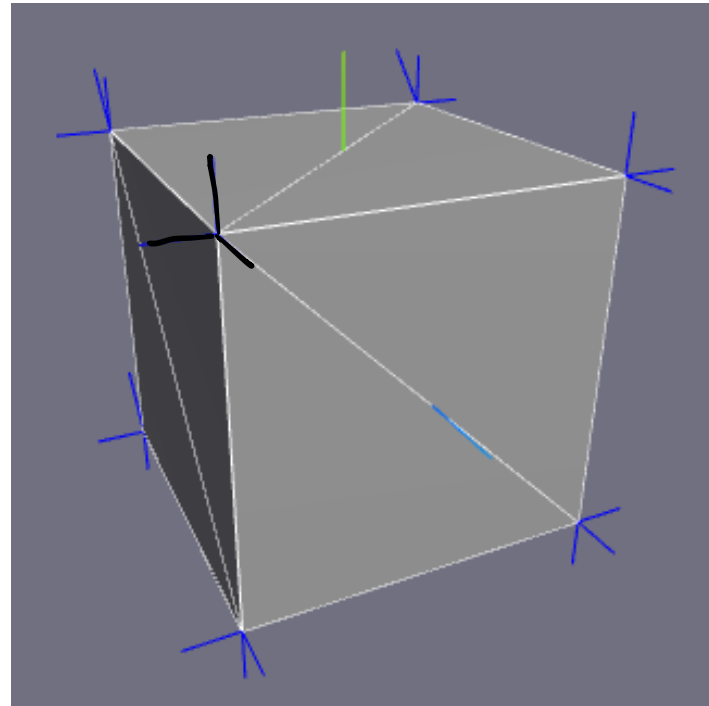


# Surface Normals: Smooth vs Faceted Surfaces



# Normals at Discontinuities

- Vertex normal is not **unique**
- Depends which triangle!
- Idea: just like positions:
  - store normals in a list
  - each corner of a triangle has a position index and a normal index







# OBJ Format: Triangle Vertices

A face's vertex is specified by 1, 2, or 3 **indices**:

- • position index (required)
- • texture coordinate index (optional) ← (more later)
- normal index (optional)

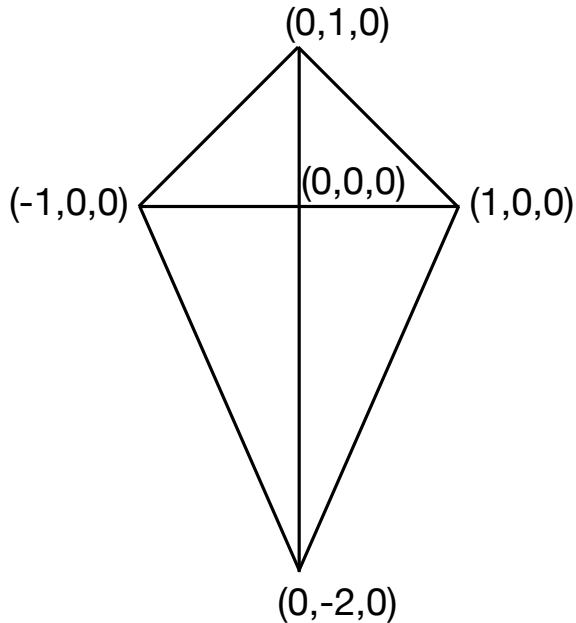
position only: f 1 2 3

all 3: f 1/1/1 2/2/1 3/3/1

position and texture: f <sup>pos/tex</sup> 1/1 2/2 3/3

position and normal: f <sup>pos/nor</sup> 1//1 2//1 3//1

# OBJ Format: Normals



```
v 0.0 0.0 0.0  
v 1.0 0.0 0.0  
v 0.0 1.0 0.0  
v -1.0 0.0 0.0  
v 0.0 -2.0 0.0
```

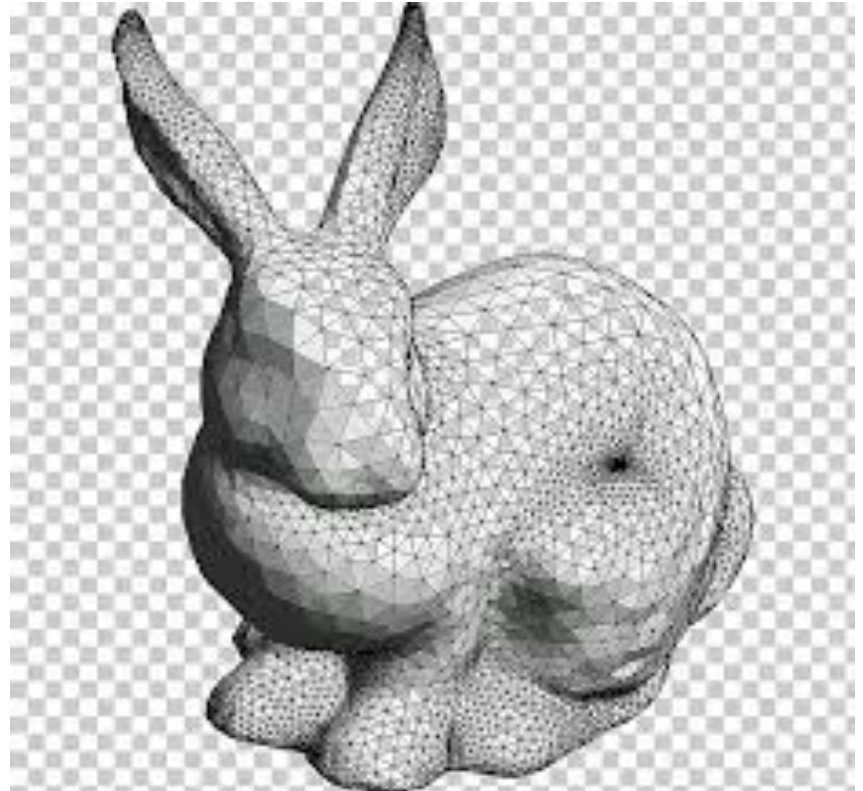
→ vn 0.0 0.0 1.0

↓  
↪ f 1//1 2//1 3//1  
f 1//1 3//1 4//1  
f 1//1 4//1 5//1  
f 1//1 5//1 2//1



# Estimating Surface Normals

- In shapes like a sphere and a cube, the normal is easy to calculate.
- What if the "true" surface isn't known?

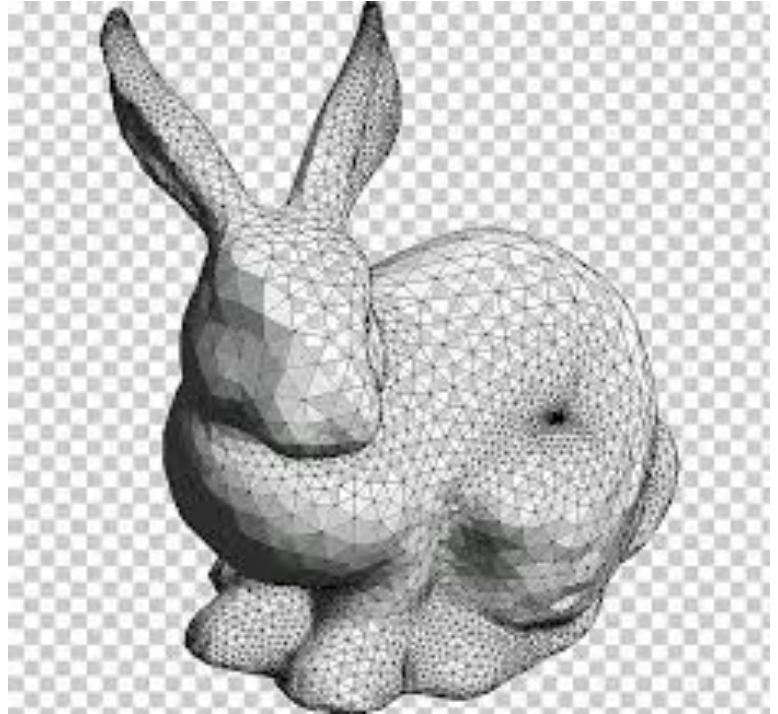


# Estimating Surface Normals

## Faceted Objects

Triangles represent geometry exactly.

Like the cube, all normals are normal to their triangles.



# Estimating Surface Normals

## Faceted Objects

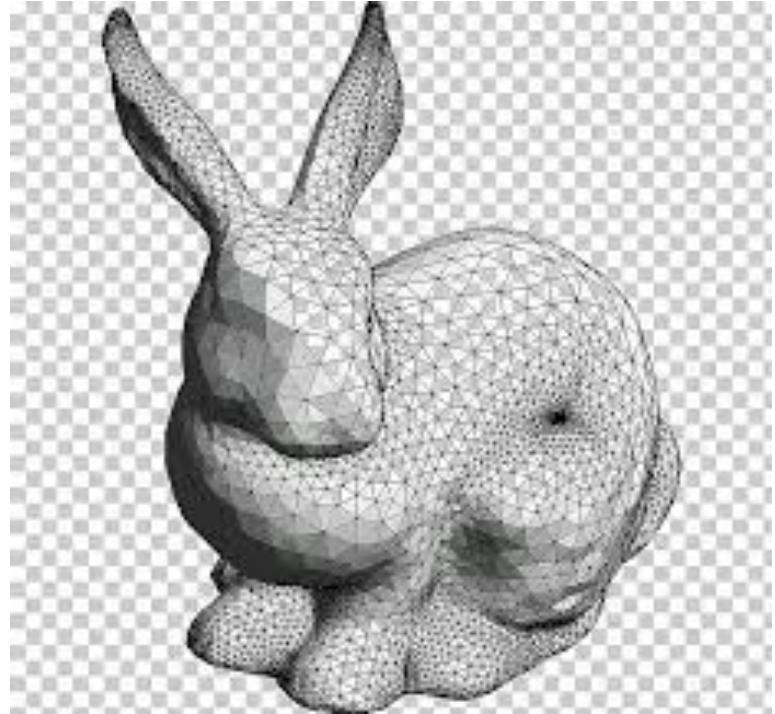
Triangles represent geometry exactly.

Like the cube, all normals are normal to their triangles.

## Smooth Objects

Triangles approximate smooth geometry.

Vertex normal is the average of all surrounding triangle normals.



← This is the last part of A1.