

CSCI 241

Scott Wehrwein

Single Source Shortest Paths:
Weighted Graphs
Dijkstra's Algorithm - Intuition

Goals

Know what a **weighted graph** is.

Understand the intuition and high-level pseudocode for **Dijkstra's single-source shortest paths algorithm**.

Be able to execute Dijkstra's algorithm on paper.

Weighted Graphs

Like a normal graph, but edges have **weights**.

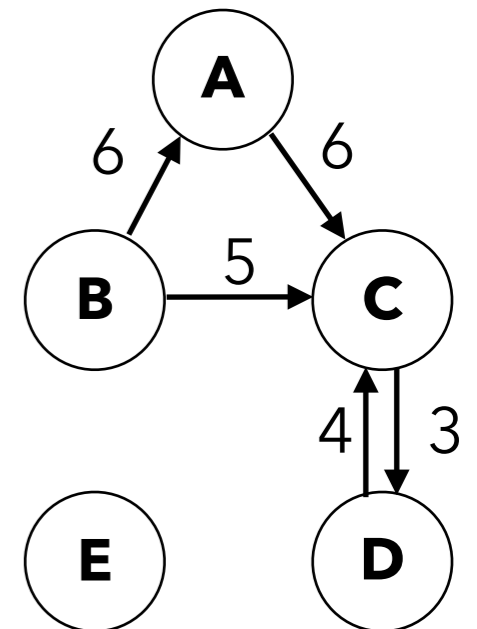
Formally: a graph (V,E) with an accompanying *weight function* $w : E \rightarrow \mathbb{R}$

- may be directed or undirected.

Informally: label edges with their weights

Representation:

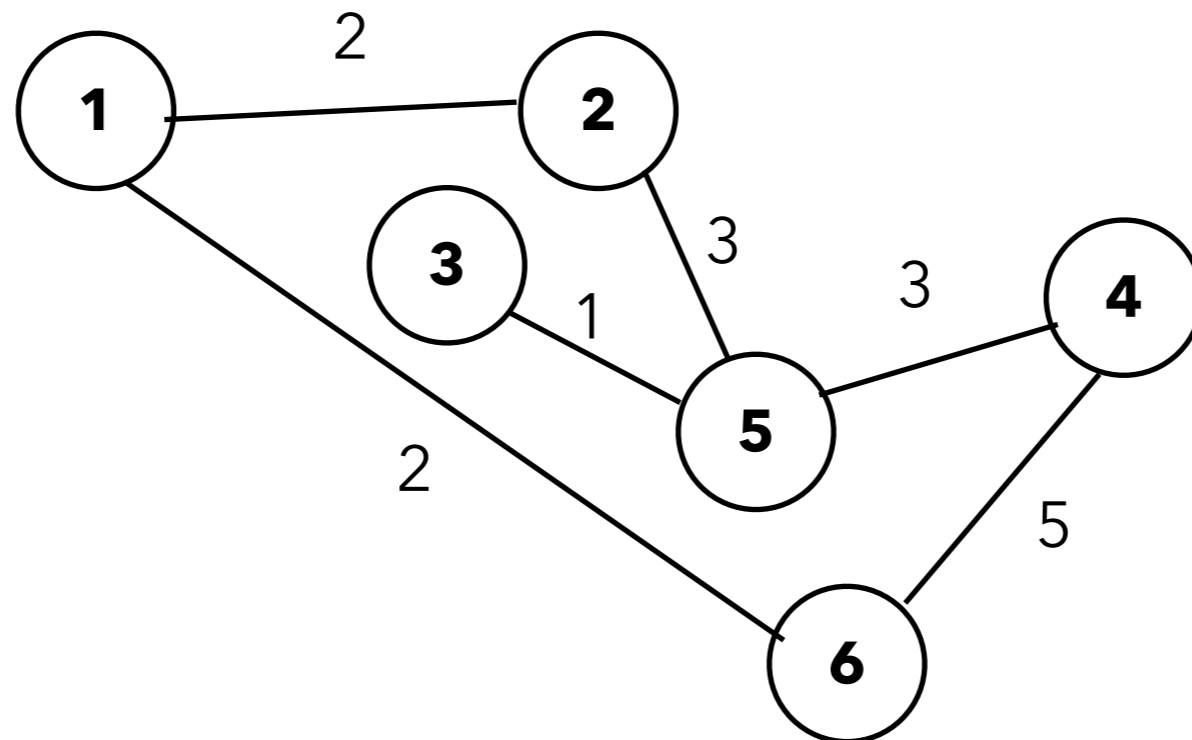
- adjacency list - store weight of (u,v) with v the node in u 's list
- adjacency matrix - store weight in matrix entry for (u,v)



Paths in Weighted Graphs

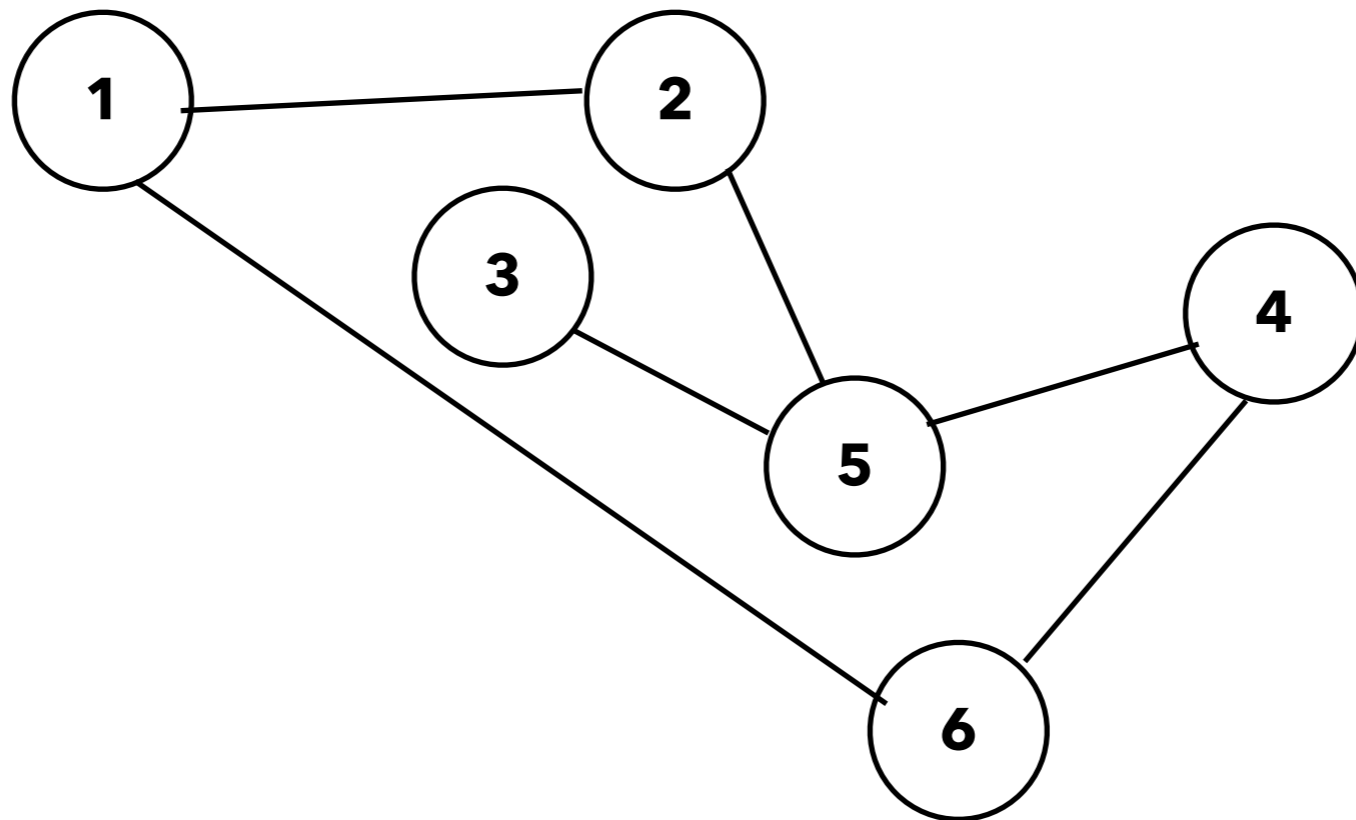
The **length** (or **weight**) of a path in a weighted graph is the sum of the edge weights along that path.

Example: the path (1, 6, 4) has weight 7.



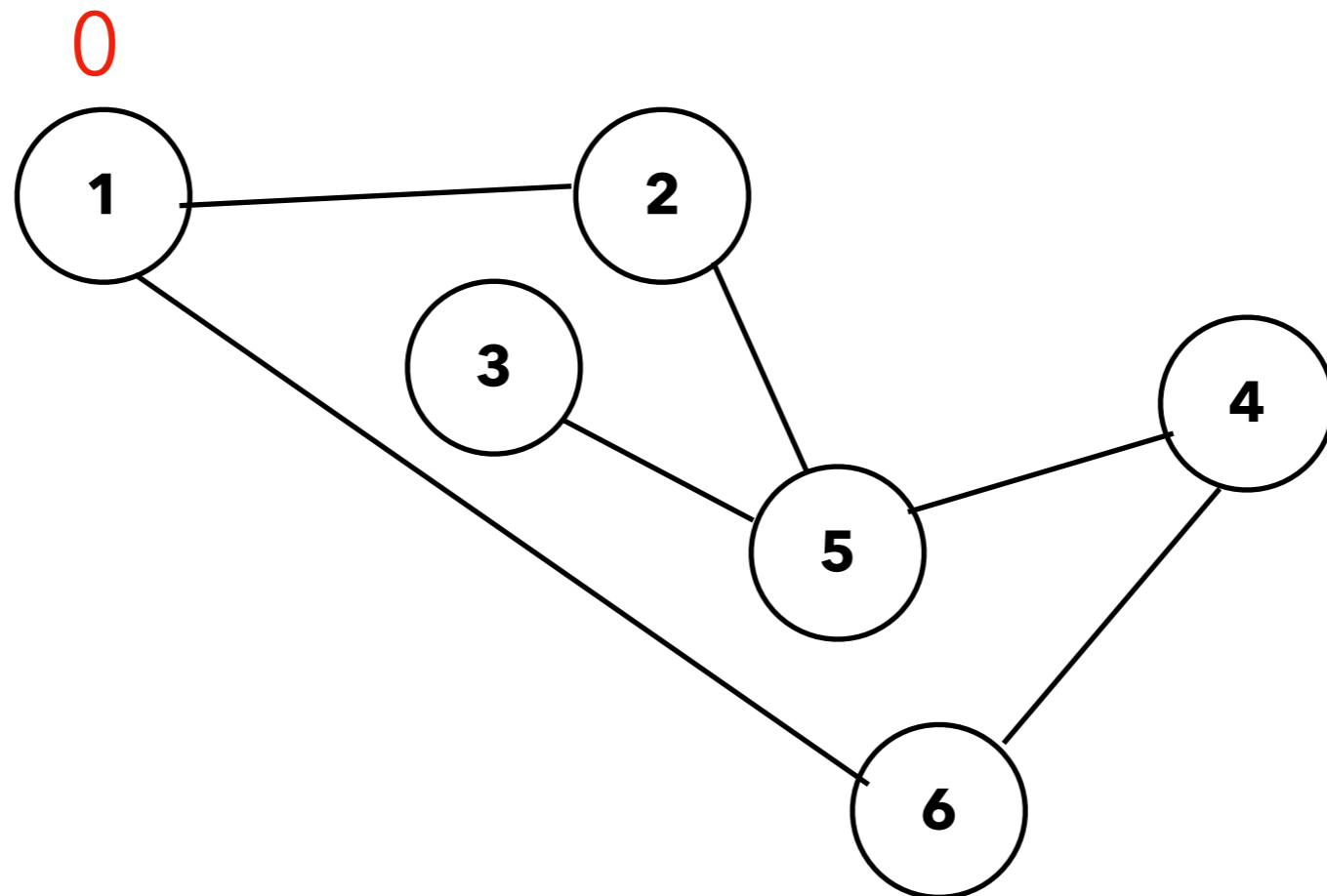
Computing Shortest Paths in Unweighted Graphs

- Perform a breadth-first search (that's it!)
- BFS visits nodes in order of "hop distance", or path length!
- BFS(1):



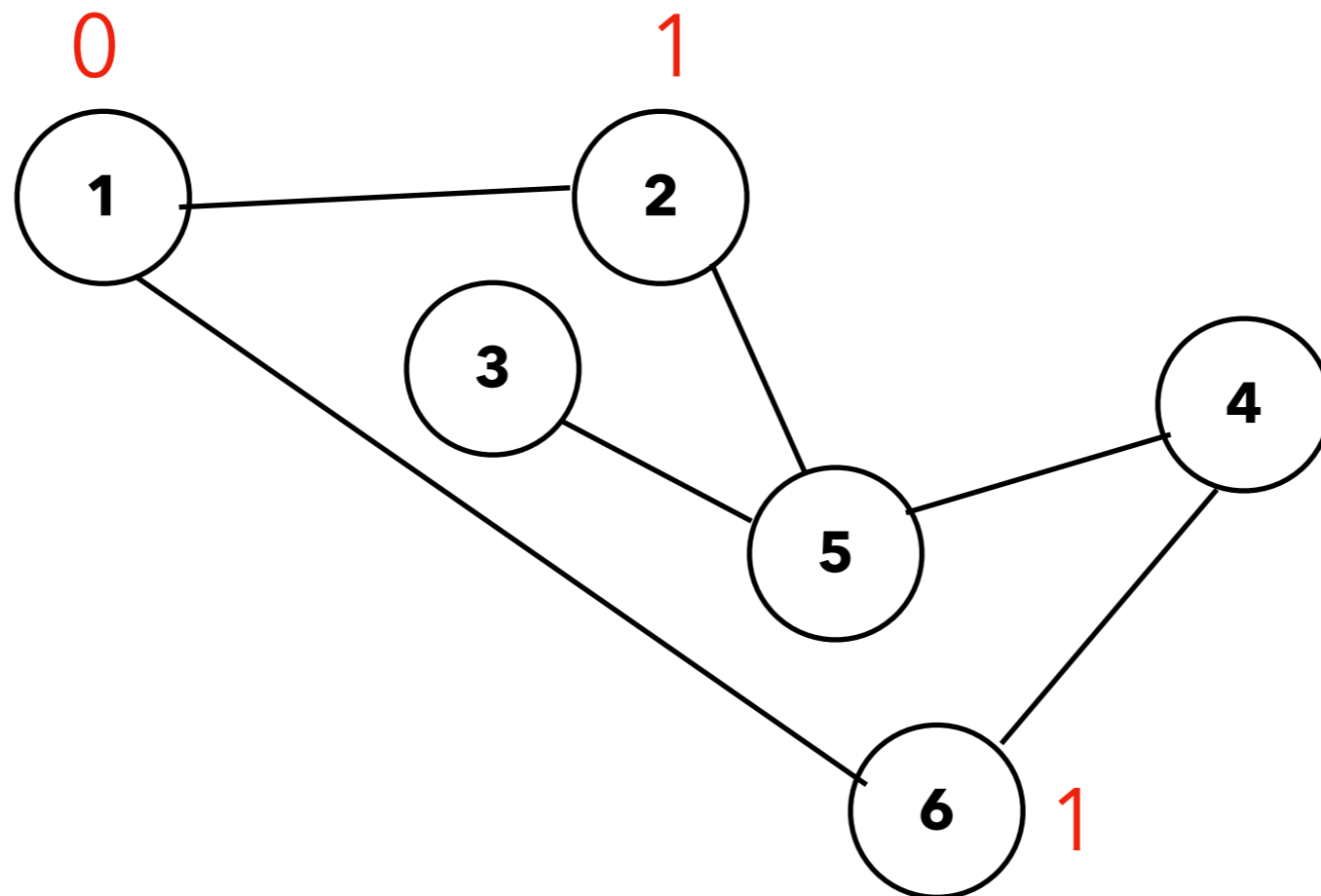
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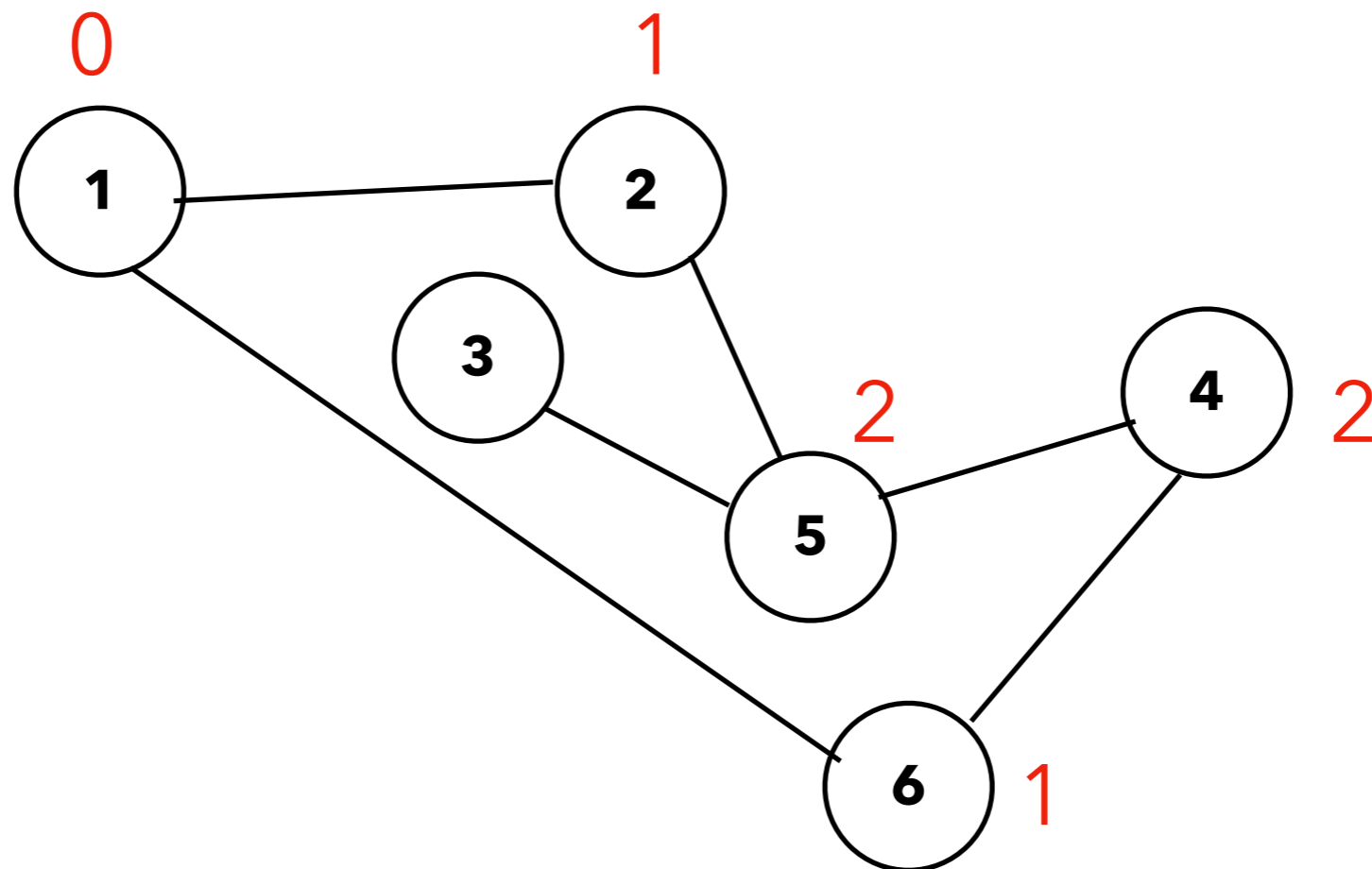
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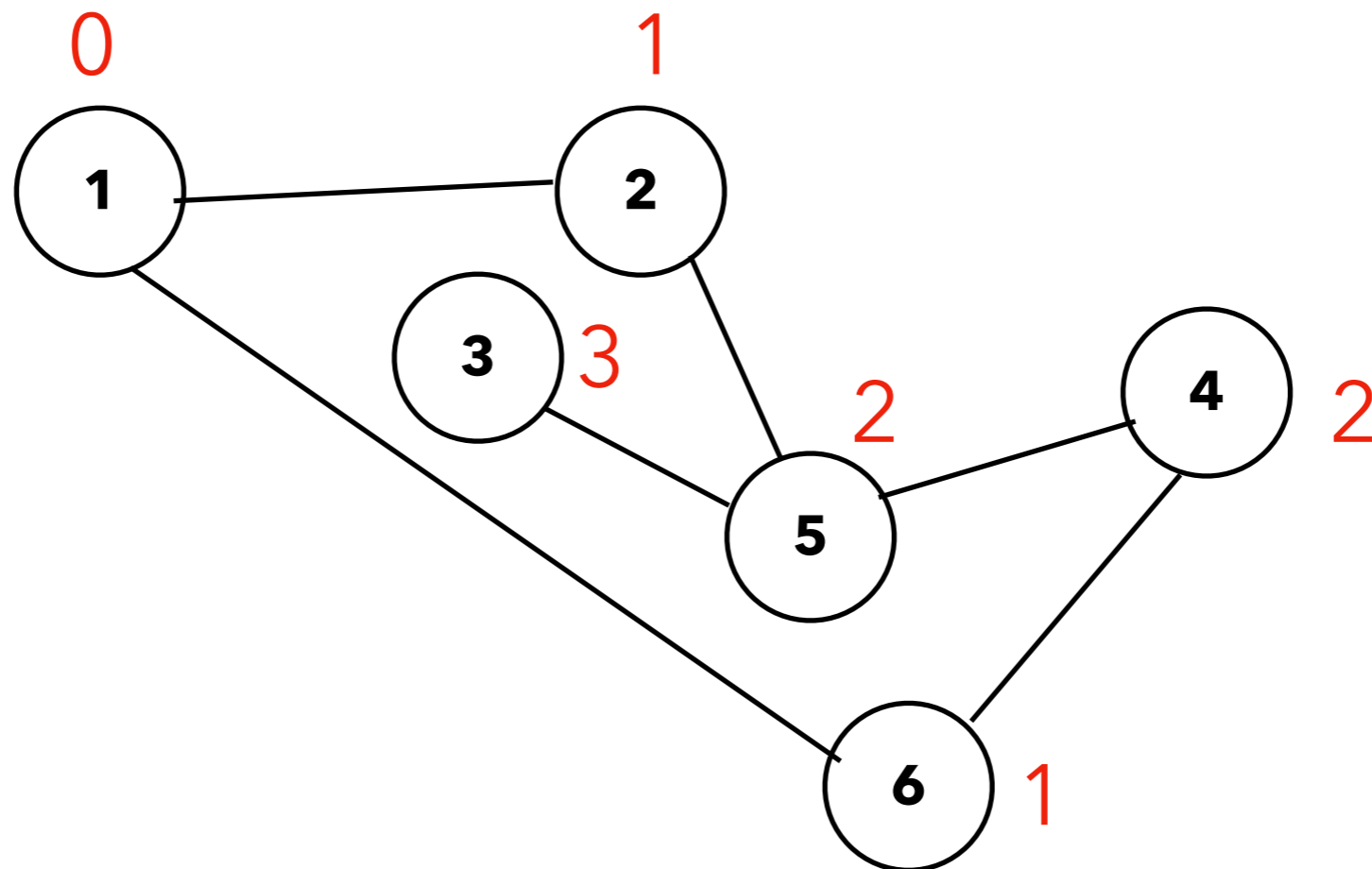
Computing Shortest Paths in Unweighted Graphs

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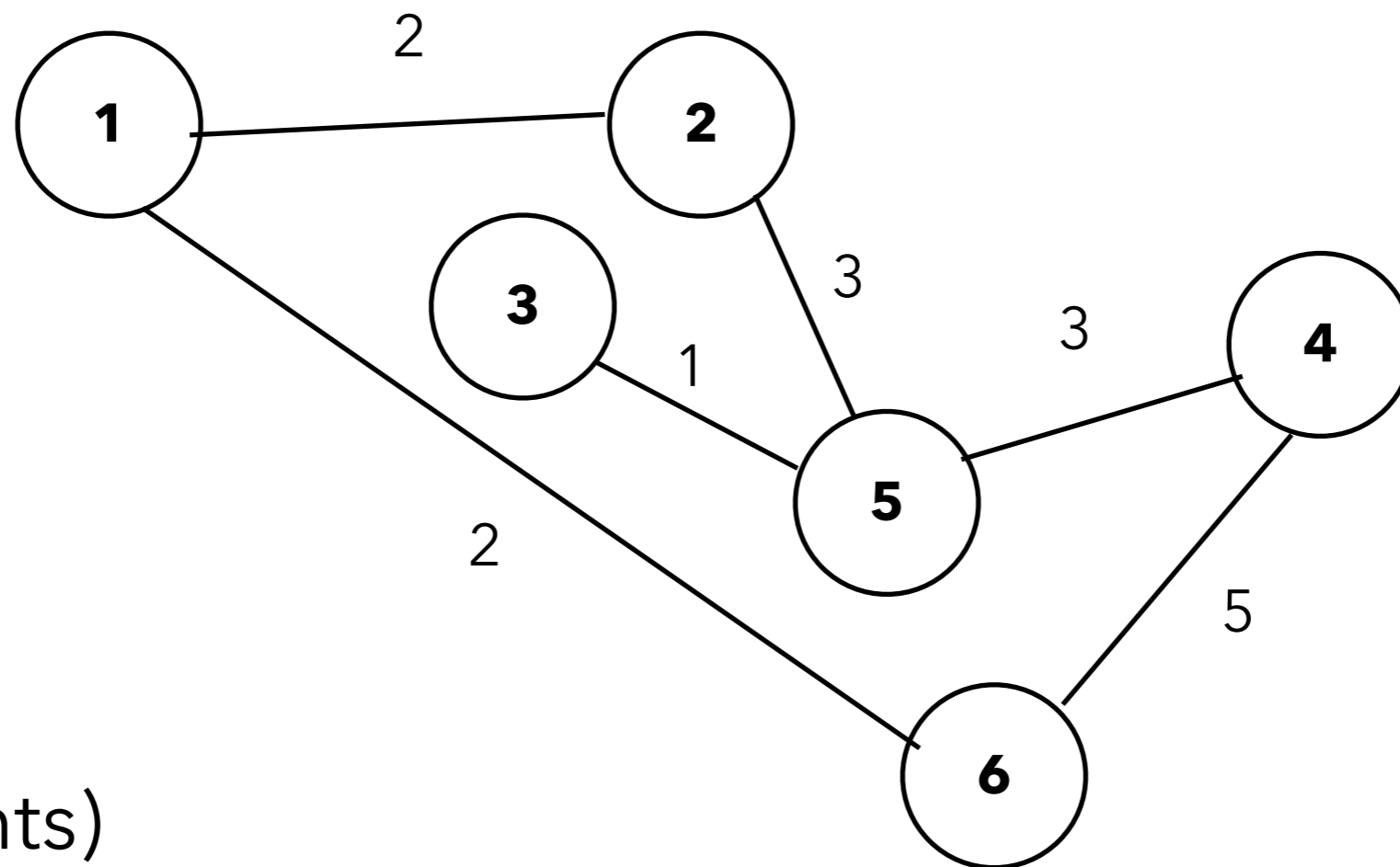
Computing Shortest Paths in Unweighted Graphs

- Perform a breadth-first search (that's it!)
- BFS visits nodes in order of "hop distance", or path length!
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Computing Shortest Paths in Weighted Graphs

BFS doesn't visit nodes in order of shortest path length:

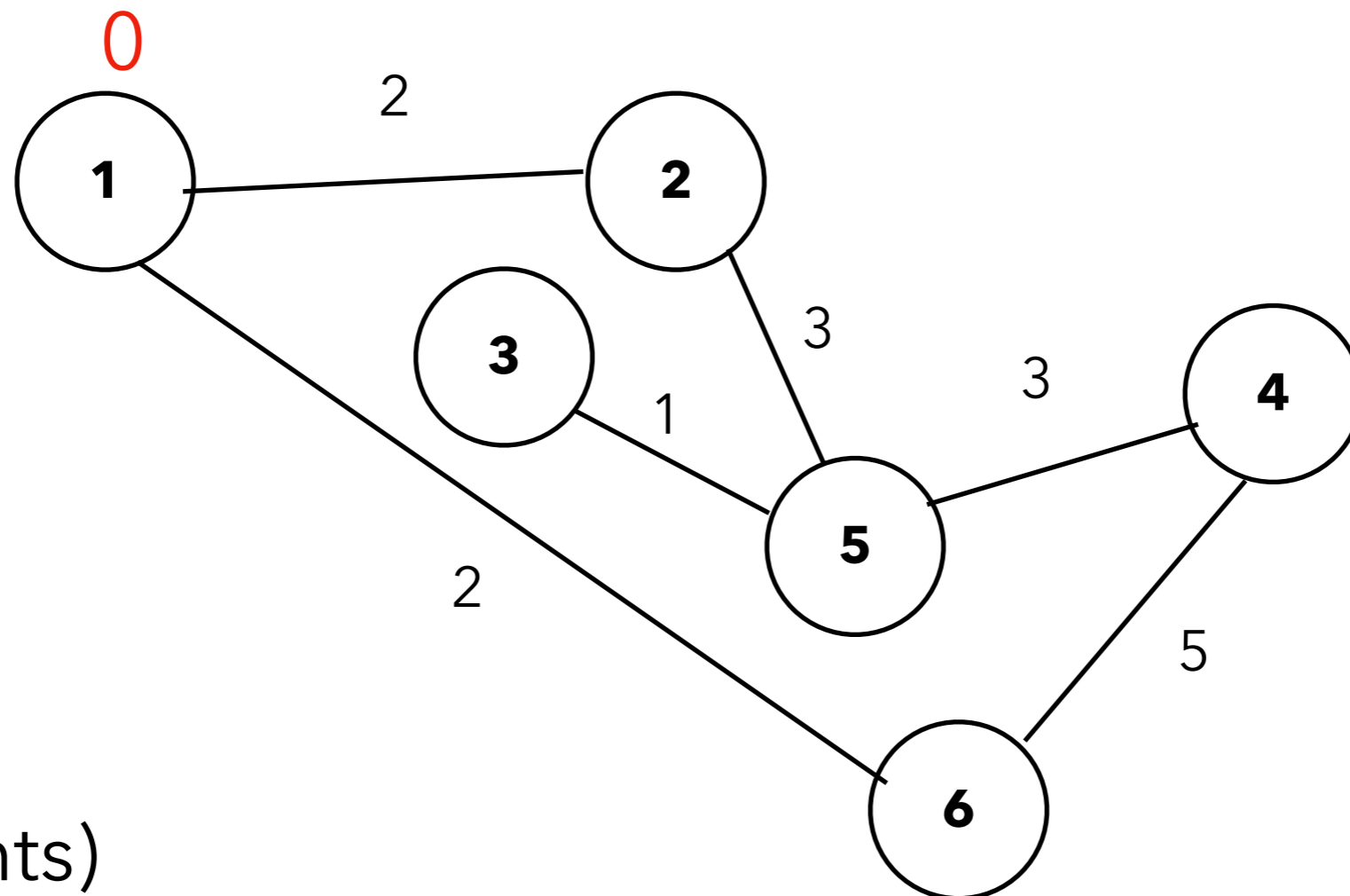


(edge weights)

(shortest path length from node 1)

Computing Shortest Paths in Weighted Graphs

BFS doesn't visit nodes in order of shortest path length:

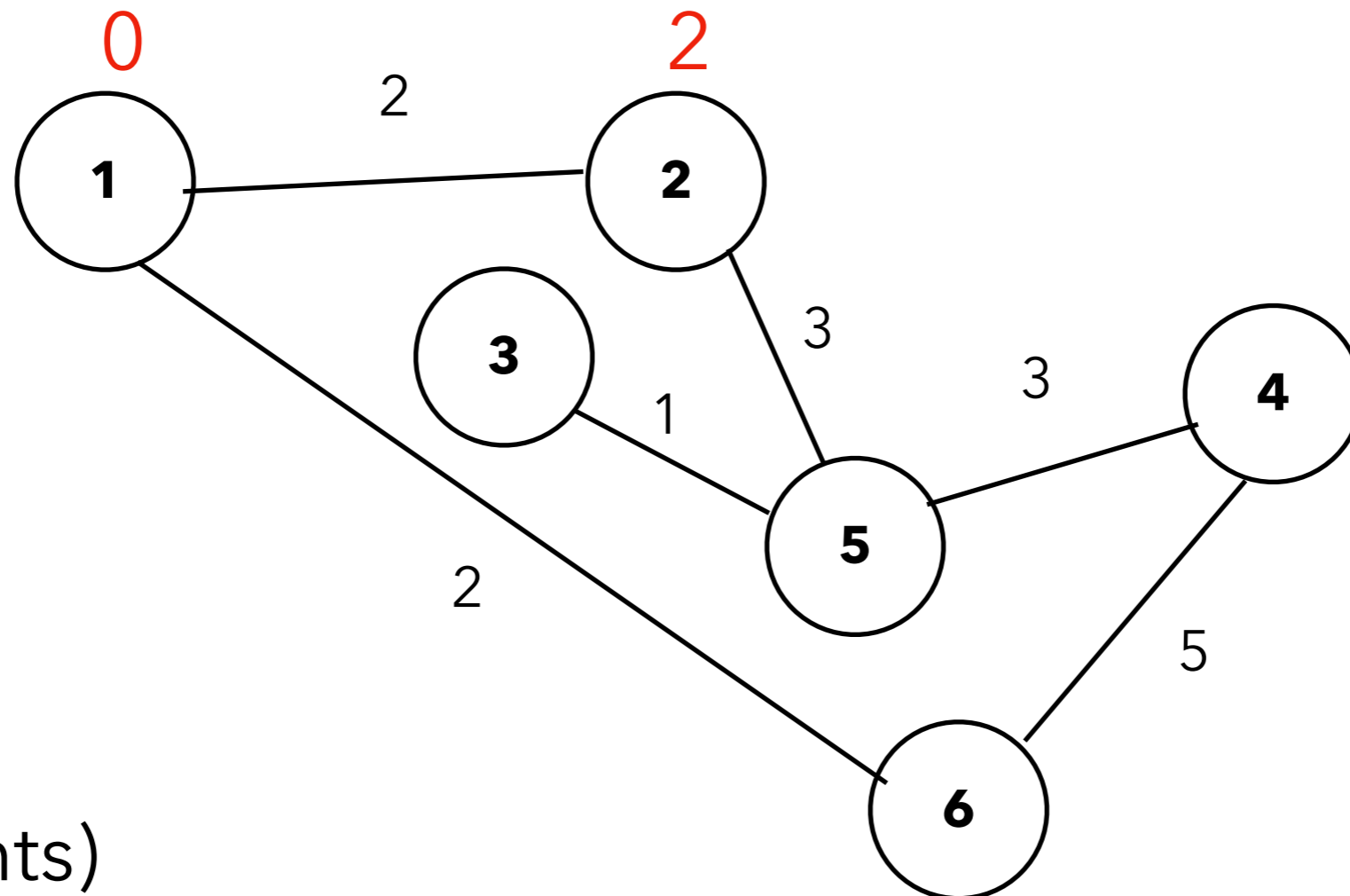


(edge weights)

(shortest path length from node 1)

Computing Shortest Paths in Weighted Graphs

BFS doesn't visit nodes in order of shortest path length:

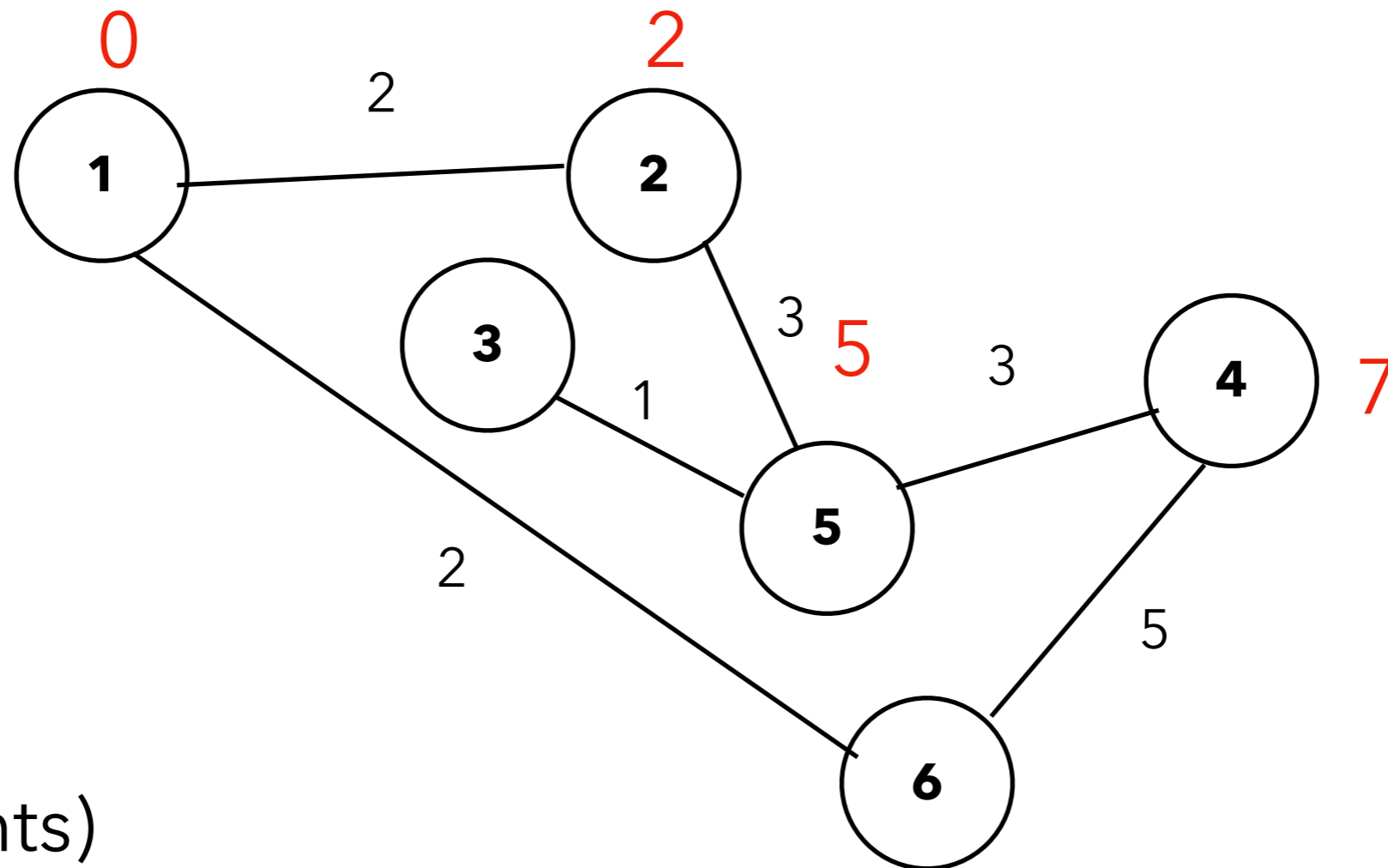


(edge weights)

(shortest path length from node 1)

Computing Shortest Paths in Weighted Graphs

BFS doesn't visit nodes in order of shortest path length:

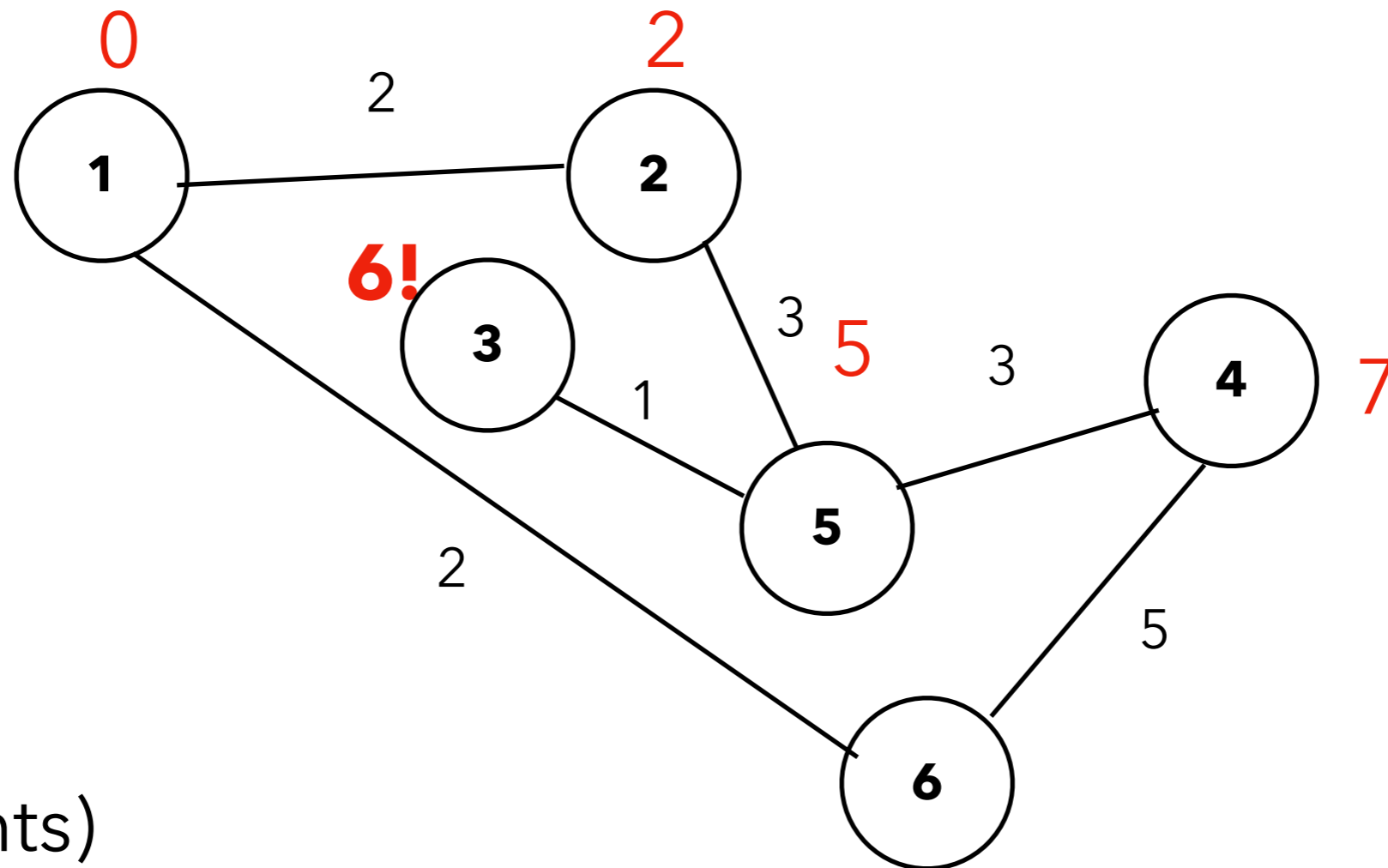


(edge weights)

(shortest path length from node 1)

Computing Shortest Paths in Weighted Graphs

BFS doesn't visit nodes in order of shortest path length:

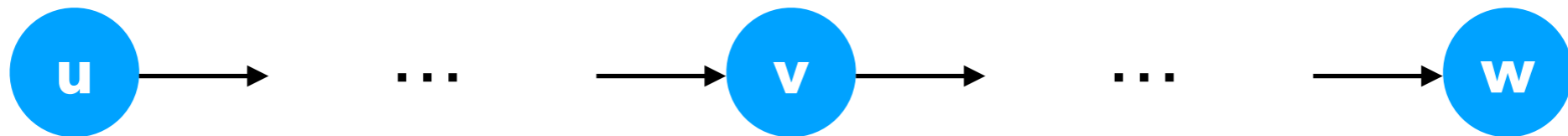


(edge weights)

(shortest path length from node 1)

Dijkstra's Shortest Paths: Subpaths

Fact: **subpaths** of shortest paths are shortest paths



Example: if the shortest path from **u** to **w** goes through **v**, then:

- the part of that path from **u** to **v** is the shortest path from **u** to **v**.
- if there were some better path **u..v**, that would also be part of a better way to get from **u** to **w**.

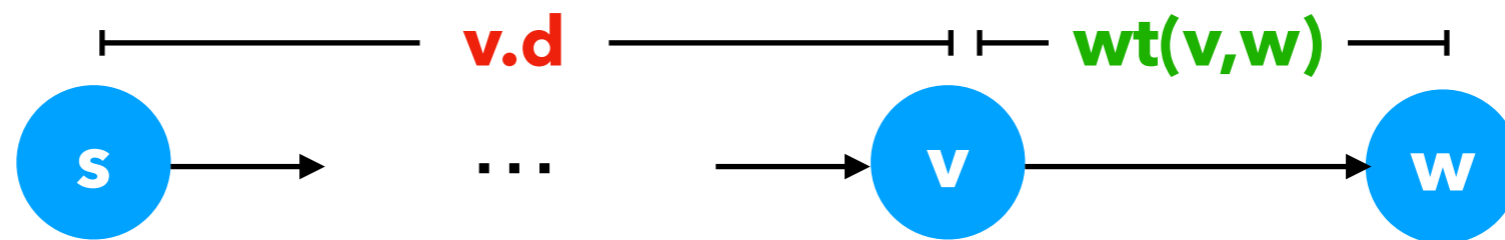
Dijkstra's Shortest Paths: Subpaths

Fact: **subpaths** of shortest paths are shortest paths

Consequence: a **candidate** shortest path from start node **s** to some node **v**'s neighbor **w** is the shortest path from **s** to **v** + the edge weight from **v** to **w**.

Shorthand:

- **v.d** is the shortest (known) distance from the start to **v**
- **wt(v, w)** is the weight of the edge from **v** to **w**



Dijkstra's Shortest Paths: Intuition

Intuition: **explore nodes like BFS, but in order of path length instead of number of hops.**

There are three kinds of nodes:

- **Settled** - nodes for which we know the actual shortest path.
- **Frontier** - nodes that have been visited but we don't necessarily have their actual shortest path
- **Unexplored** - all other nodes.

Each node **n** keeps track of **n.d**, the length of the shortest known known path from start.

We may discover a shorter path to a **frontier** node than the one we've found already - if so, update **n.d**.

Dijkstra's Shortest Paths: Cartoon

settled

frontier

unexplored

Before:

During:

After:

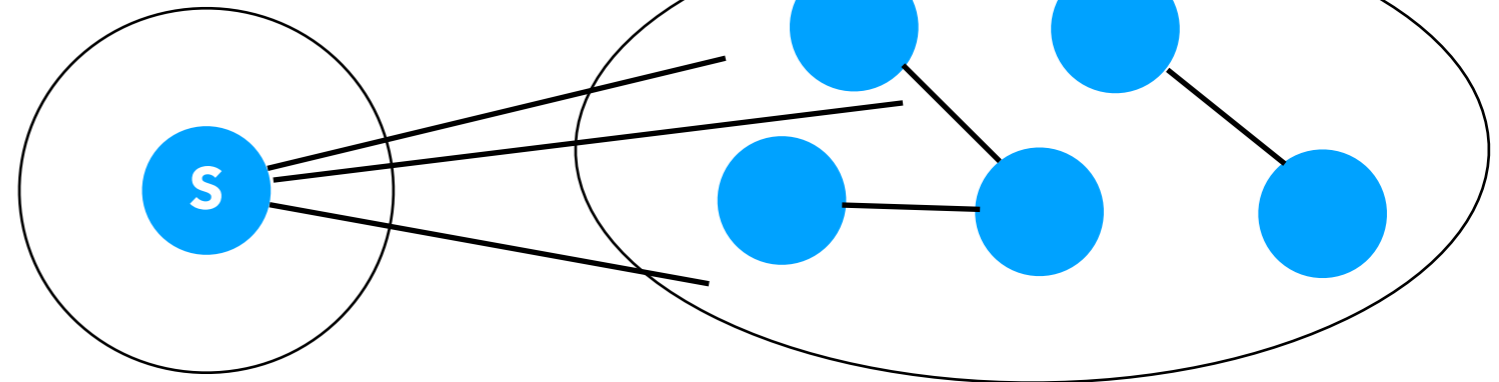
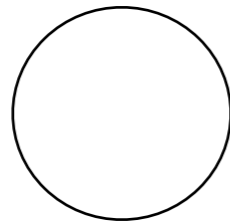
Dijkstra's Shortest Paths: Cartoon

settled

frontier

unexplored

Before:



During:

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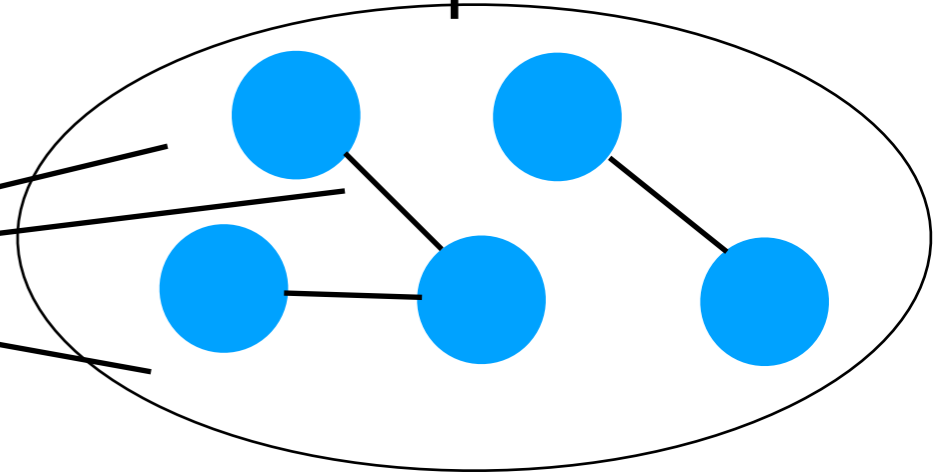
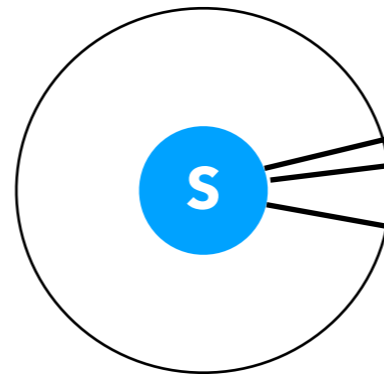
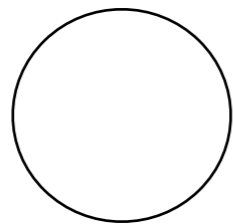
Dijkstra's Shortest Paths: Cartoon

settled

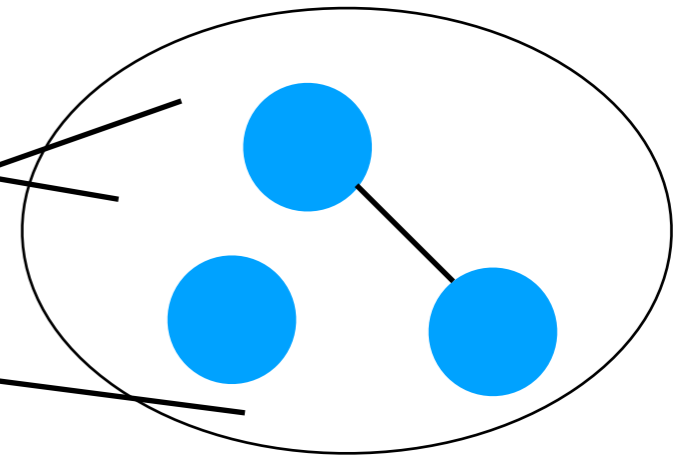
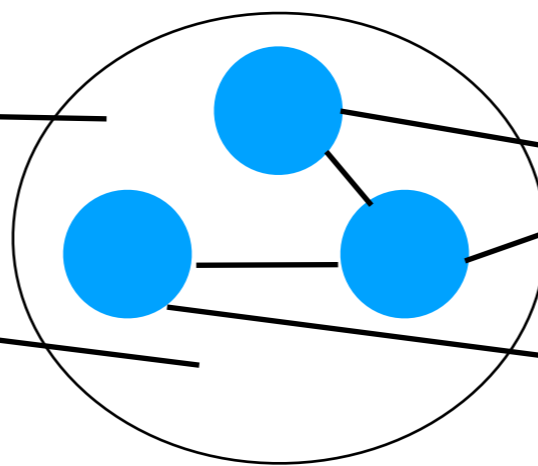
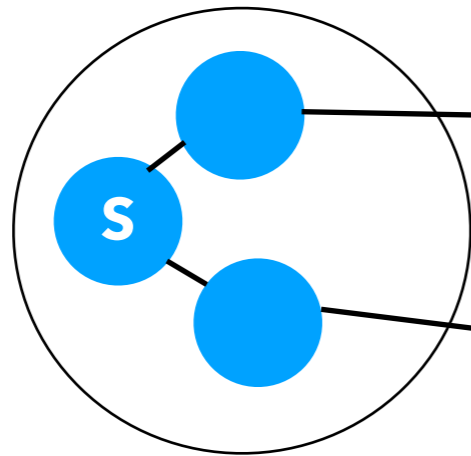
frontier

unexplored

Before:



During:



After:

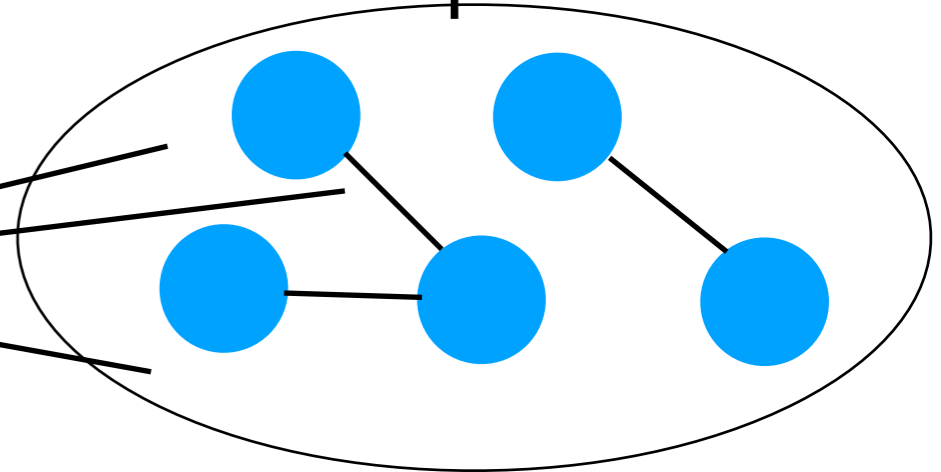
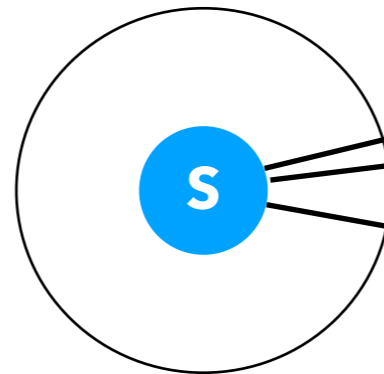
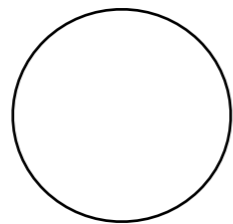
Dijkstra's Shortest Paths: Cartoon

settled

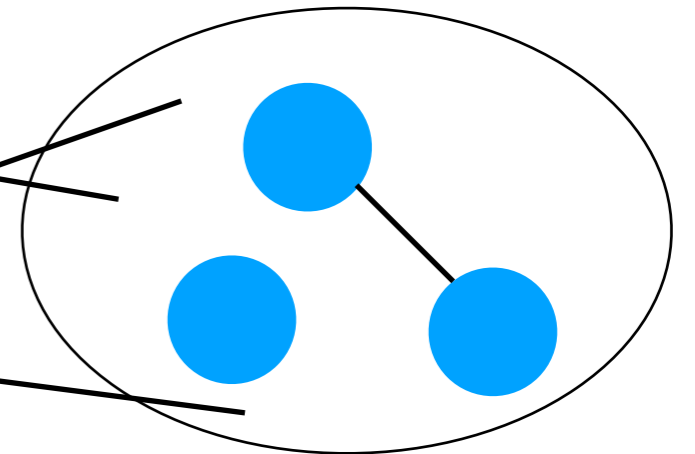
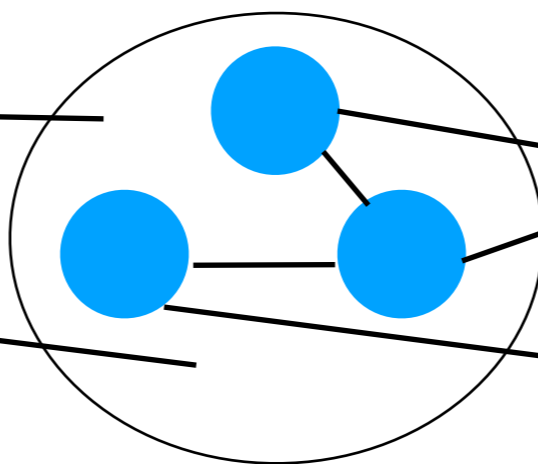
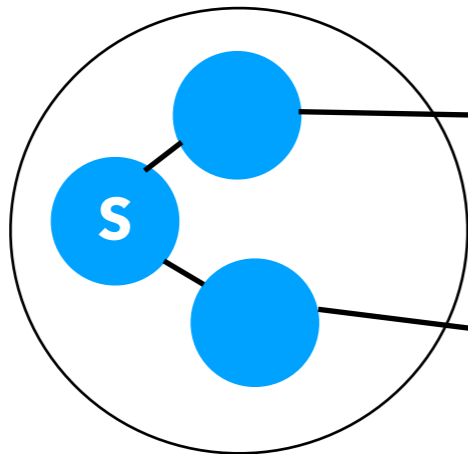
frontier

unexplored

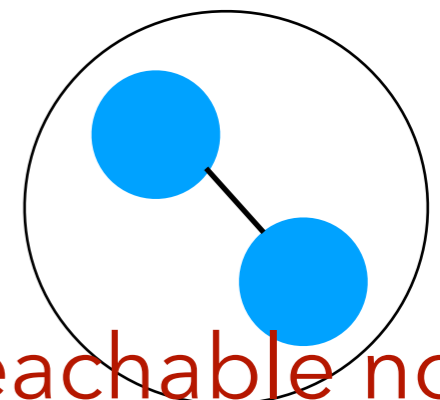
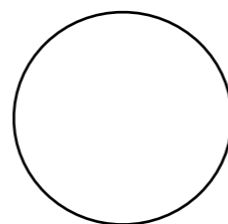
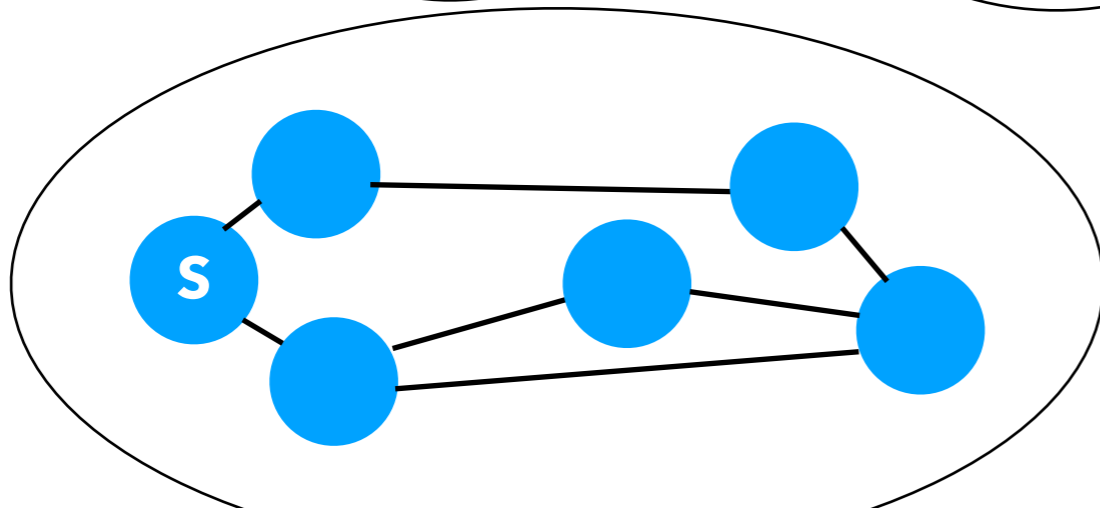
Before:



During:



After:



unreachable nodes

Dijkstra's Shortest Paths: High-Level Algorithm

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

 move the node f with smallest d from F to S

 For each neighbor w of f :

 if we've never seen w before:

 set its path length

 add it to frontier

 else if the path to w via f is shorter:

 update w 's shortest path length

Dijkstra's Shortest Paths: High-Level Algorithm

Initialize Settled to empty

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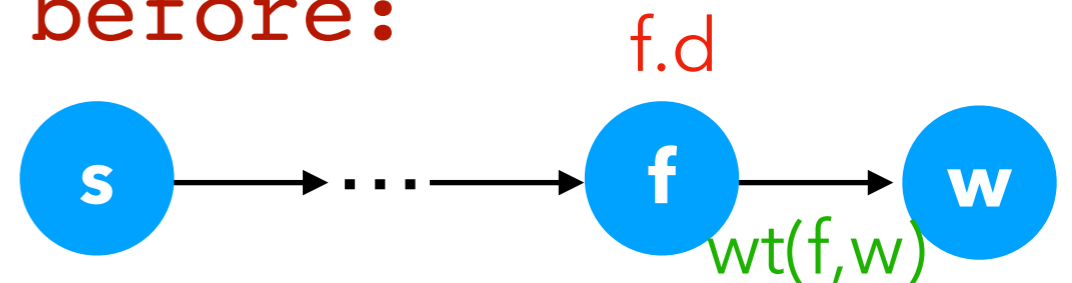
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Dijkstra's Shortest Paths: High-Level Algorithm

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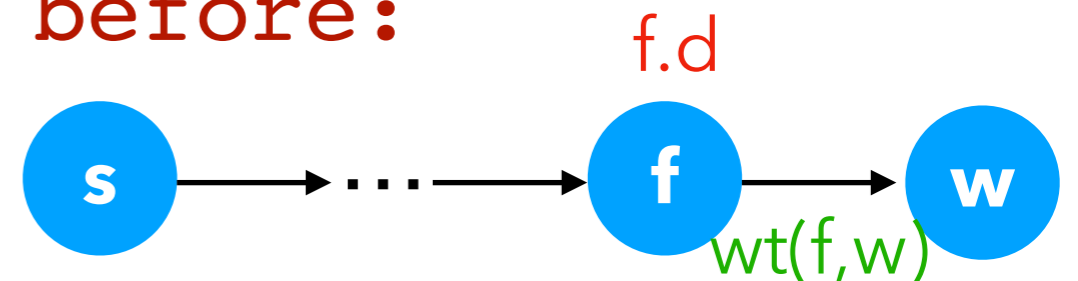
move the node f with smallest d from F to S

For each neighbor w of f :

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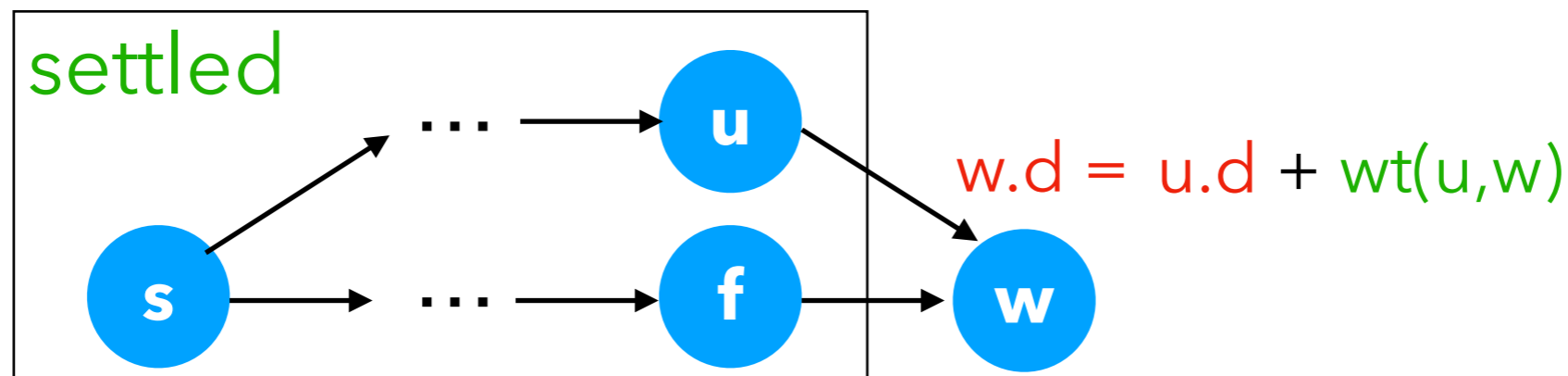
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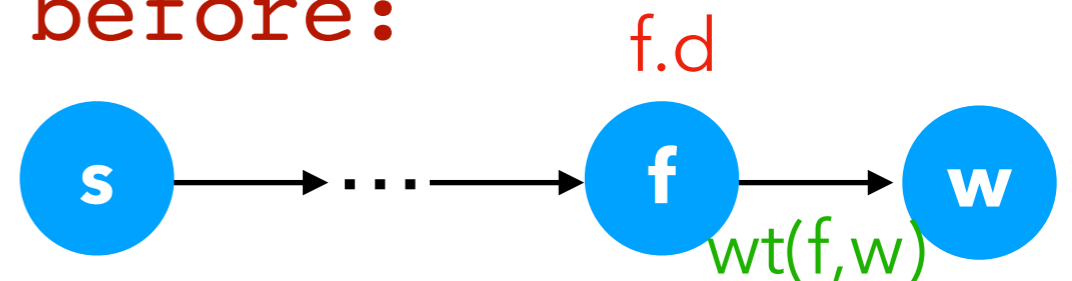
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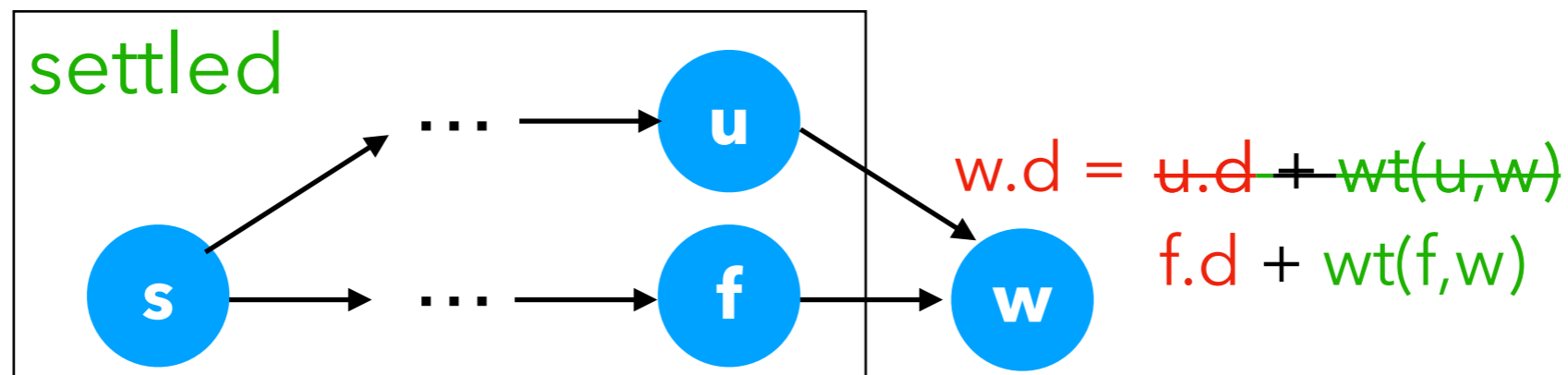
set its path length

add it to frontier



else if the path to w via f is shorter:

update w 's shortest path length



Dijkstra's Shortest Paths:

Execution

Best
known
distances:

Node	d
0	?
1	?
2	?
3	?
4	?

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

set its path length to $f.d + wt(f,w)$

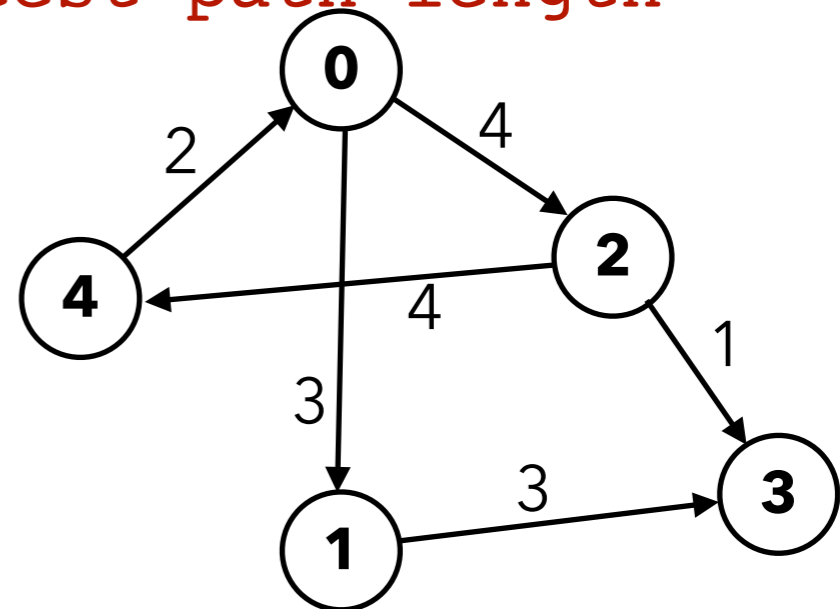
add w to the frontier

else if the path to w via f is shorter:

update w 's shortest path length

Settled set:

Frontier set:



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

```
Initialize Settled to empty  
Initialize Frontier to the start node
```

While the frontier isn't empty:

move the node f with smallest d from F to S

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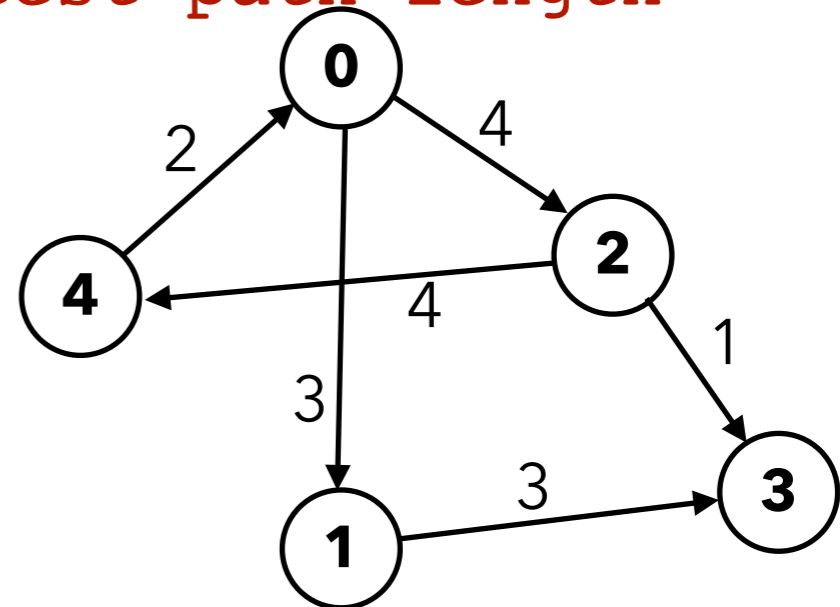
else if the path to w via f is shorter:

update w 's shortest path length

Node	d
0	?
1	?
2	?
3	?
4	0

Settled set: {}

Frontier set: {4}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

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While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

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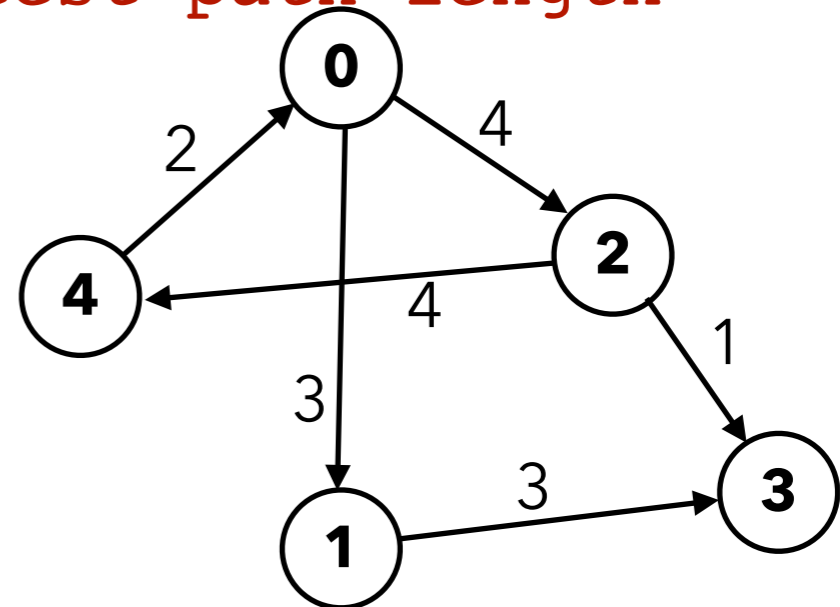
update w 's shortest path length

Node	d
0	?
1	?
2	?
3	?
4	0

f: 4

Settled set: {4}

Frontier set: {}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

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update w 's shortest path length

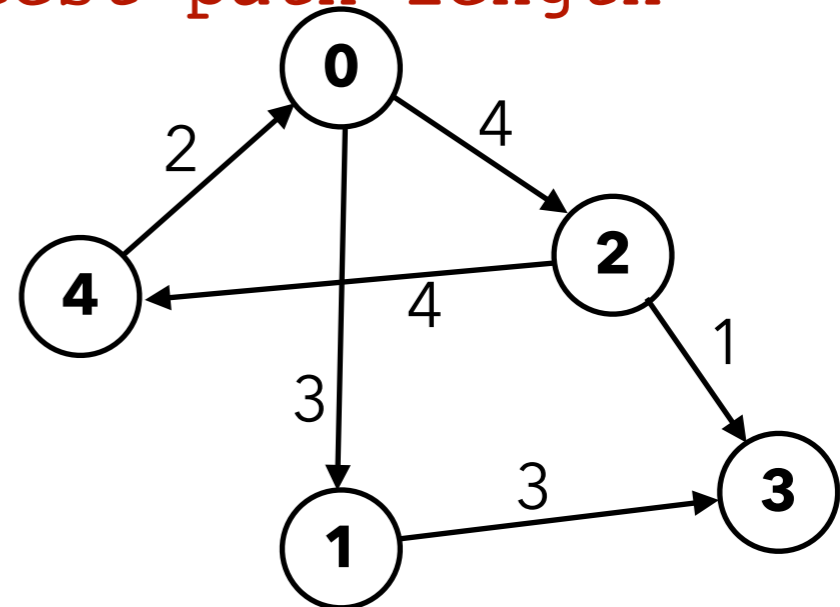
$f: 4$

$w: 0$

Node	d
0	2
1	?
2	?
3	?
4	0

Settled set: {4}

Frontier set: {0}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

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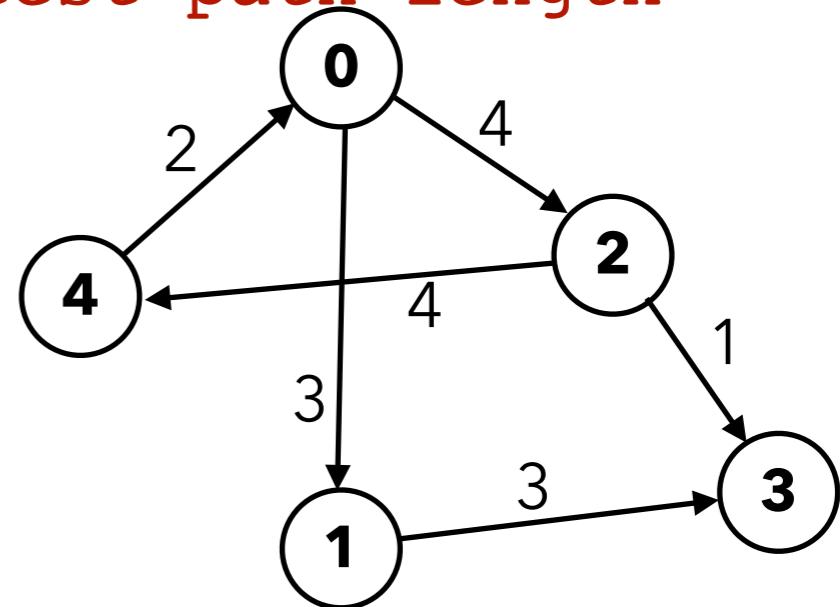
update w 's shortest path length

Node	d
0	2
1	?
2	?
3	?
4	0

f: 0

Settled set: {4, 0}

Frontier set: {}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

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While the frontier isn't empty:

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add w to the frontier

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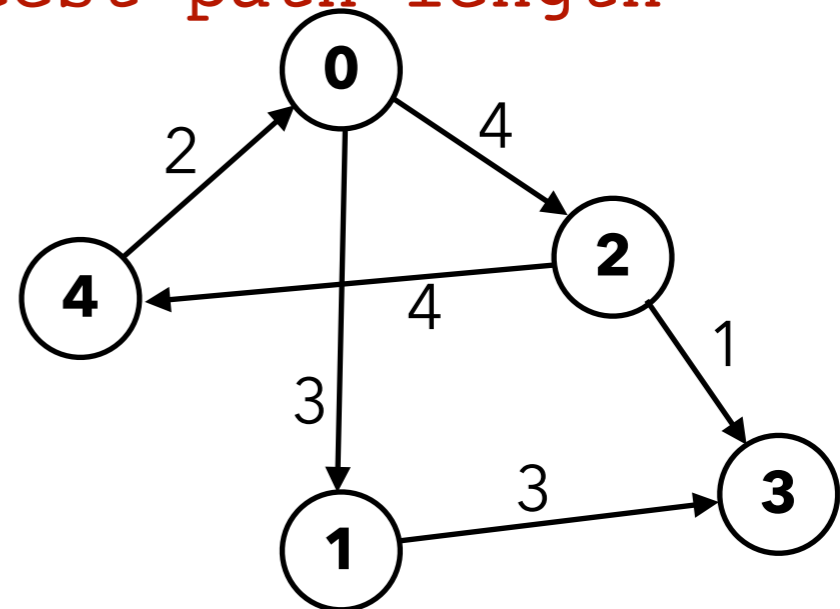
$f: 0$

$w: 1$

Node	d
0	2
1	5
2	?
3	?
4	0

Settled set: {4, 0}

Frontier set: {1}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

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add w to the frontier

else if the path to w via f is shorter:

update w 's shortest path length

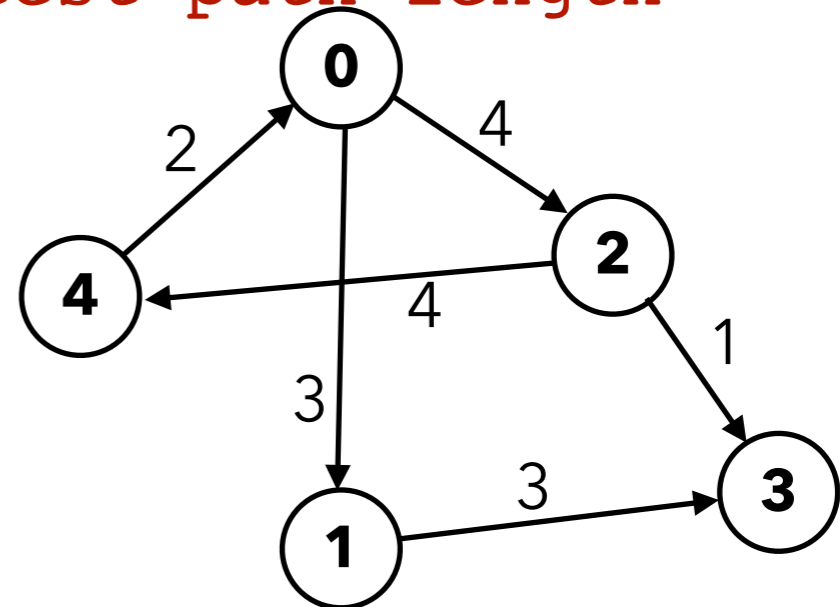
$f: 0$

$w: 2$

Node	d
0	2
1	5
2	6
3	?
4	0

Settled set: {4, 0}

Frontier set: {1, 2}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

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add w to the frontier

else if the path to w via f is shorter:

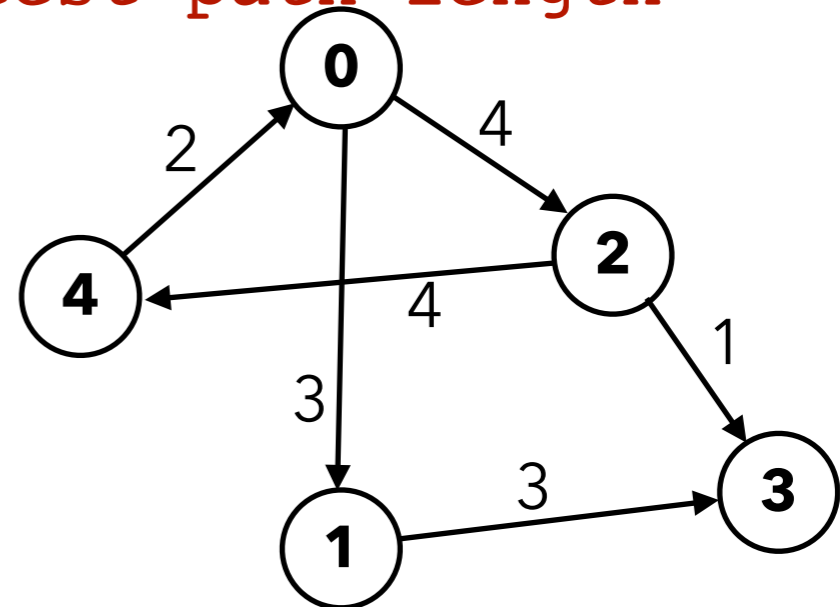
update w 's shortest path length

Node	d
0	2
1	5
2	6
3	8
4	0

f: 1

Settled set: {4, 0, 1}

Frontier set: {2}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

set its path length to $f.d + wt(f, w)$

add w to the frontier

else if the path to w via f is shorter:

update w 's shortest path length

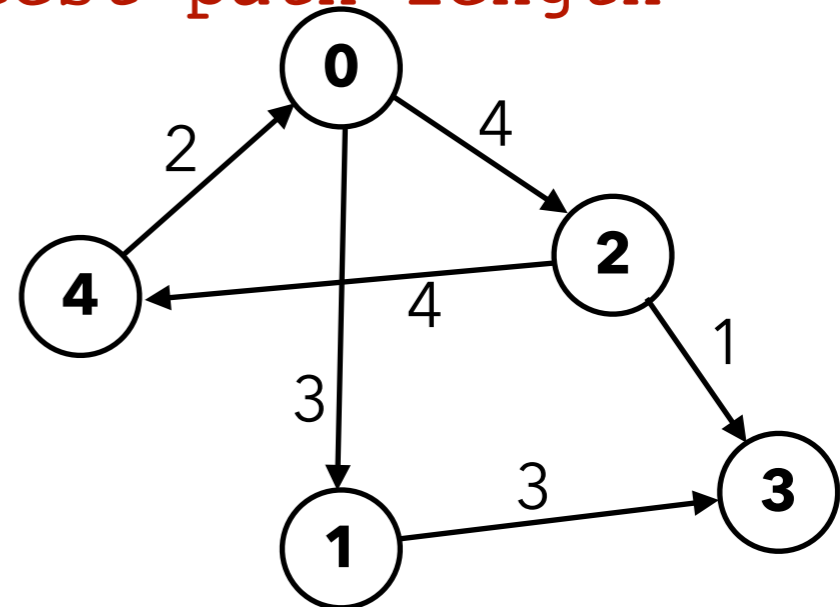
$f: 1$

$w: 3$

Node	d
0	2
1	5
2	6
3	8
4	0

Settled set: {4, 0, 1}

Frontier set: {2, 3}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

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add w to the frontier

else if the path to w via f is shorter:

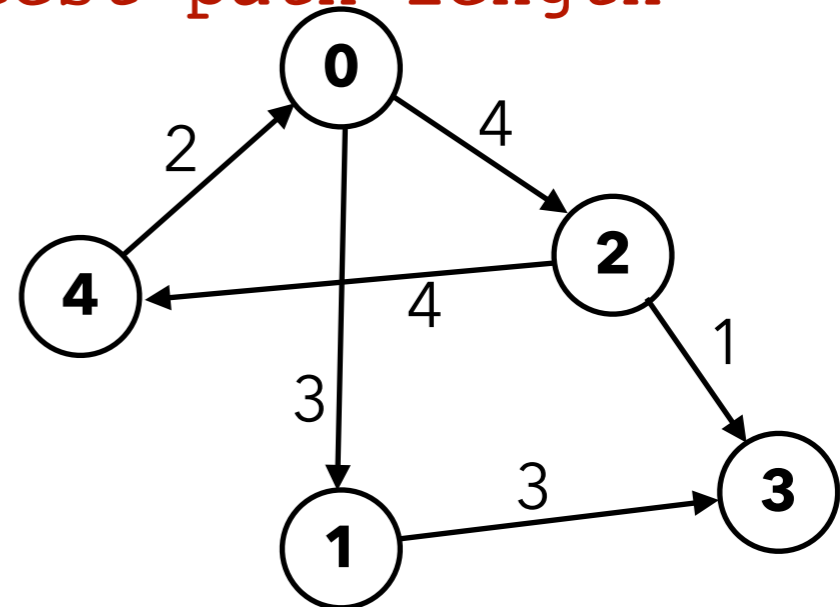
update w 's shortest path length

Node	d
0	2
1	5
2	6
3	8
4	0

f: 2

Settled set: {4, 0, 1, 2}

Frontier set: {3}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

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else if the path to w via f is shorter:

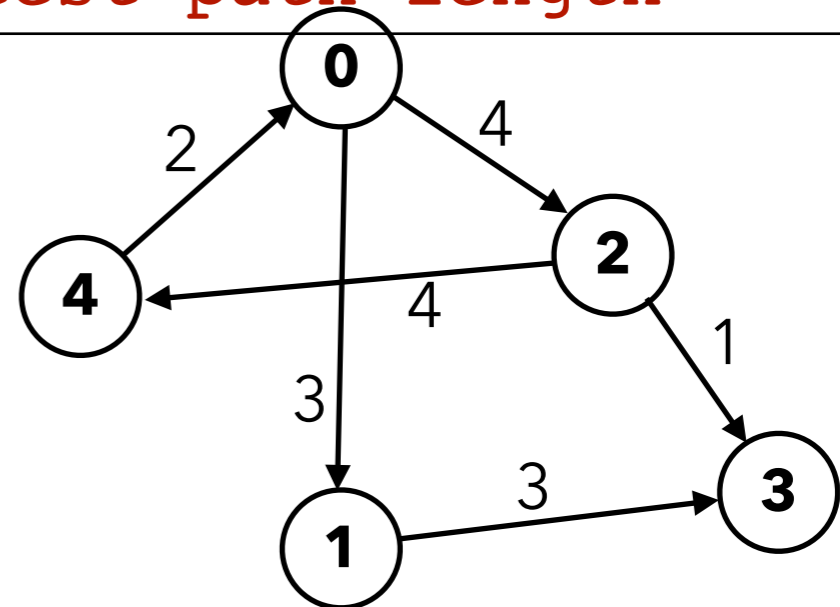
update w 's shortest path length

Node	d
0	2
1	5
2	6
3	8
4	0

$f: 2$
 $w: 3$

Settled set: {4, 0, 1, 2}

Frontier set: {3}



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

set its path length to $f.d + wt(f,w)$

add w to the frontier

else if the path to w via f is shorter:

update w 's shortest path length

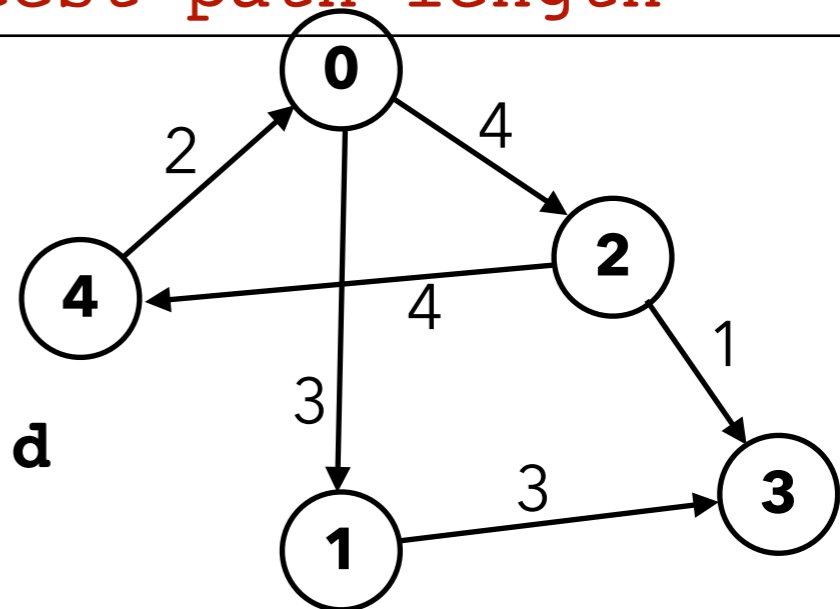
$f: 2$
 $w: 3$

Node	d
0	2
1	5
2	6
3	8
4	0

Settled set: {4, 0, 1, 2}

Frontier set: {3}

$$2.d + wt(2,3) \stackrel{?}{<} 3.d$$



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

set its path length to $f.d + wt(f,w)$

add w to the frontier

else if the path to w via f is shorter:

update w 's shortest path length

$f: 2$
 $w: 3$

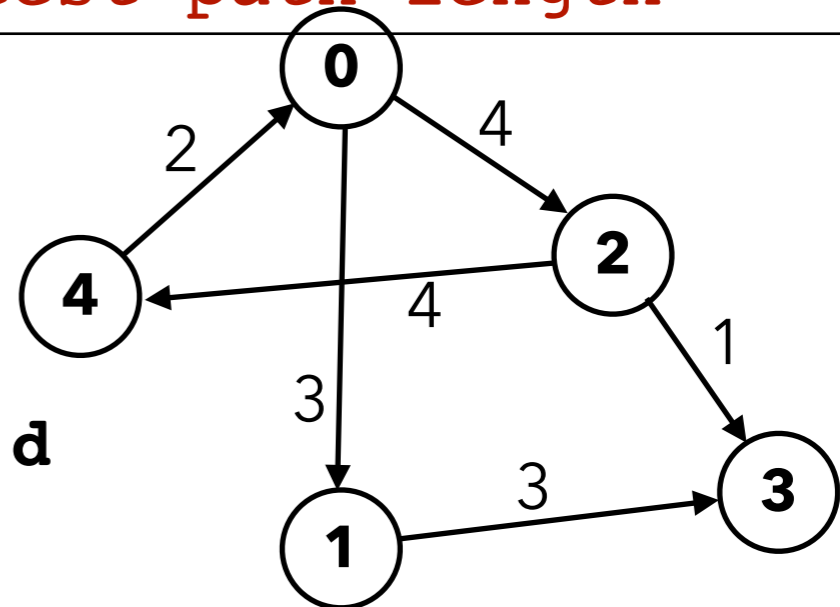
Node	d
0	2
1	5
2	6
3	8
4	0

Settled set: {4, 0, 1, 2}

Frontier set: {3}

$$2.d + wt(2,3) \stackrel{?}{<} 3.d$$

$$6 + 1 < 8$$



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

set its path length to $f.d + wt(f,w)$

add w to the frontier

else if the path to w via f is shorter:

update w 's shortest path length

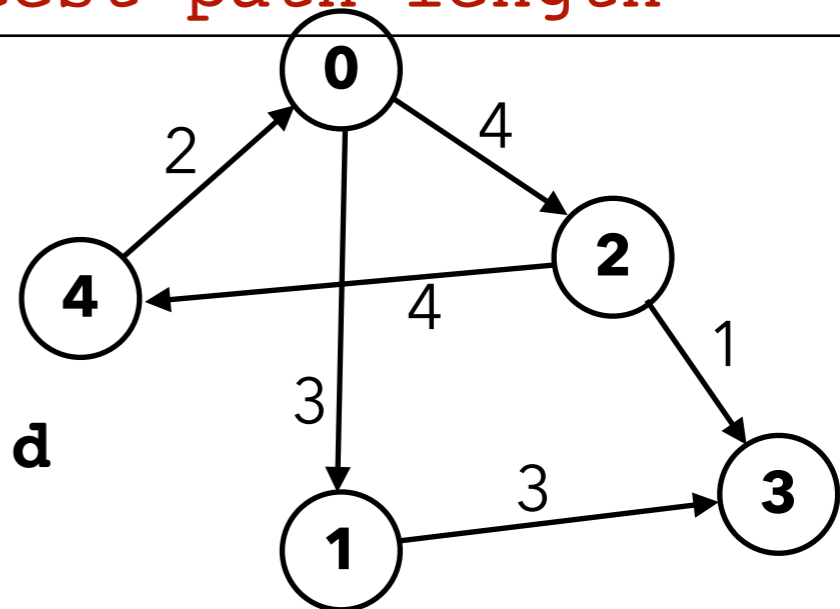
$f: 2$
 $w: 3$

Node	d
0	2
1	5
2	6
3	8
4	0

Settled set: {4, 0, 1, 2}

Frontier set: {3}

$$\begin{array}{rcl}
 2.d + wt(2,3) & ? & 3.d \\
 6 + 1 & < & 8 \\
 7 & < & 8
 \end{array}$$



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

set its path length to $f.d + wt(f,w)$

add w to the frontier

else if the path to w via f is shorter:

update w 's shortest path length

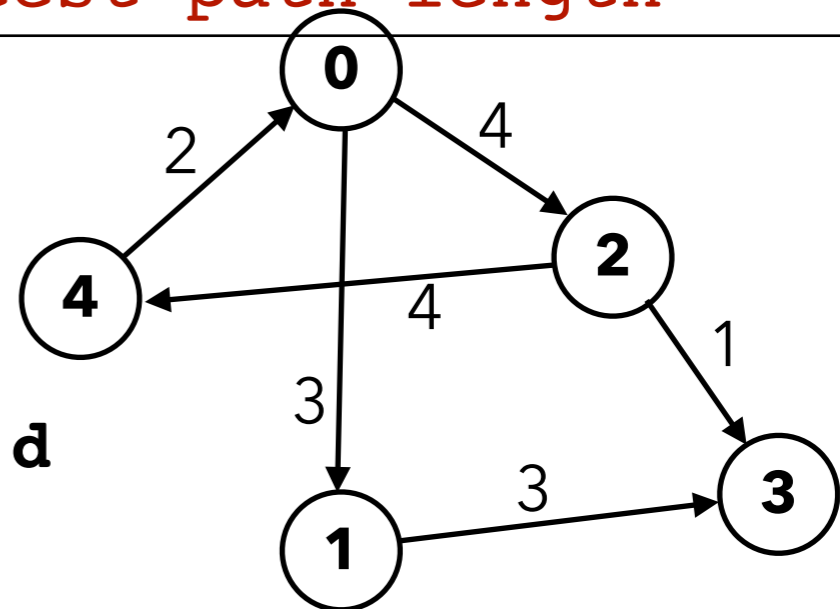
$f: 2$
 $w: 3$

Node	d
0	2
1	5
2	6
3	7
4	0

Settled set: {4, 0, 1, 2}

Frontier set: {3}

$$\begin{array}{rcl}
 2.d + wt(2,3) & ? & 3.d \\
 6 + 1 & < & 8 \\
 7 & < & 8
 \end{array}$$



shortest-paths(4)

Dijkstra's Shortest Paths: Execution

Initialize Settled to empty

Initialize Frontier to the start node

While the frontier isn't empty:

move the node f with smallest d from F to S

For each neighbor w of f :

if we've never seen w before:

set its path length to $f.d + wt(f, w)$

add w to the frontier

else if the path to w via f is shorter:

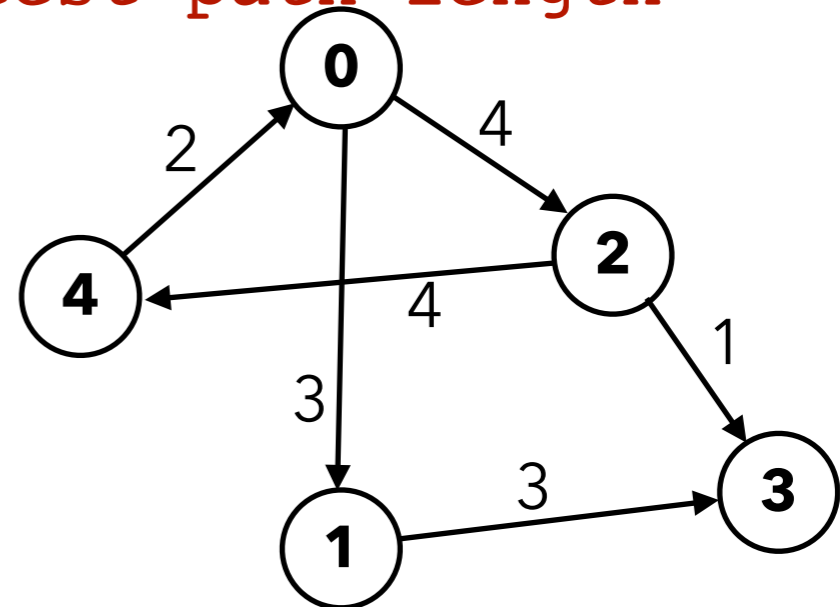
update w 's shortest path length

$f: 3$

Node	d
0	2
1	5
2	6
3	7
4	0

Settled set: {4, 0, 1, 2, 3}

Frontier set: {} Empty => done!



shortest-paths(4)