

CSCI 241

Lecture 16: Heaps and Priority Queue, Continued

Announcements

- No quiz this Friday!

Announcements

- Midterm Exam is Friday
 - Covers material through today
 - Format similar to quizzes
 - Available 8am-11:59pm
 - 60 minute time limit
- No class meeting on Friday.
- No lab deliverable this week - use lab for review.
- A3 should be out later today. Implementing your heap is good review for the midterm!

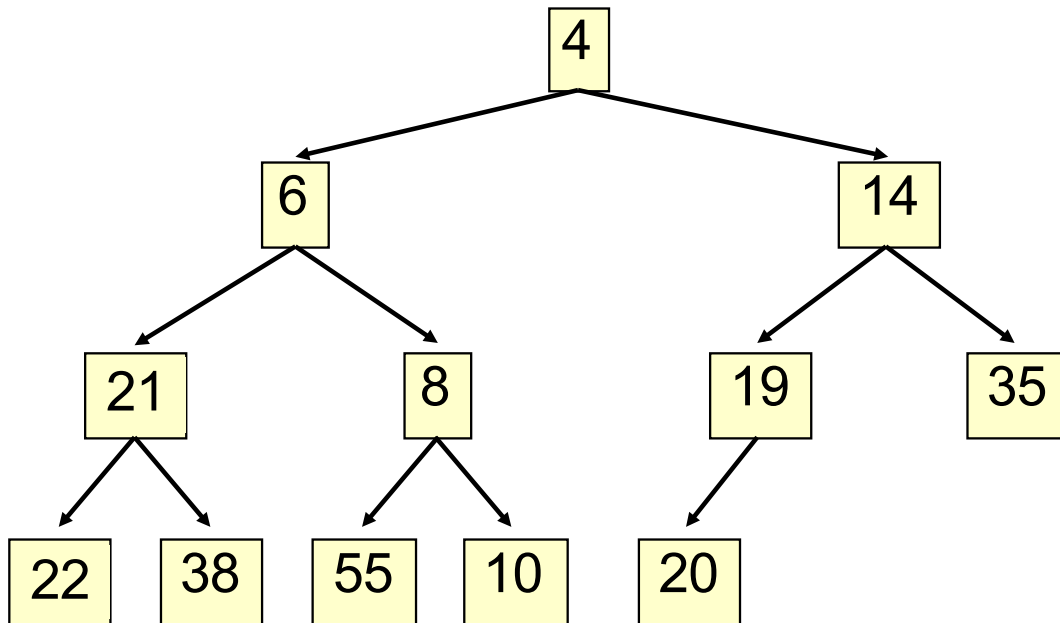
Goals

- Know the definition and properties of a heap.
- Know how heaps are stored in practice.
- Know how to implement the add, peek, and poll heap operations.
- Understand the purpose and interface of the Priority Queue ADT.
- Know how to implement a Priority Queue using a heap
- Know how to sort an array using **Heapsort**

A heap is a special binary tree.

1. **Heap Order Invariant:**

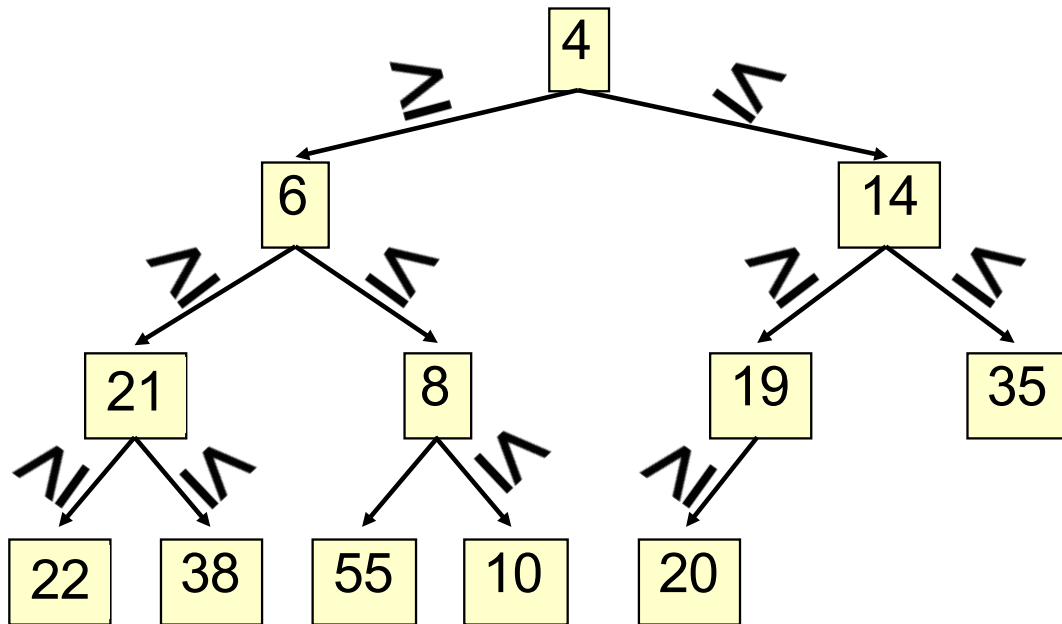
Each element \geq its parent.



A heap is a special binary tree.

1. **Heap Order Invariant:**

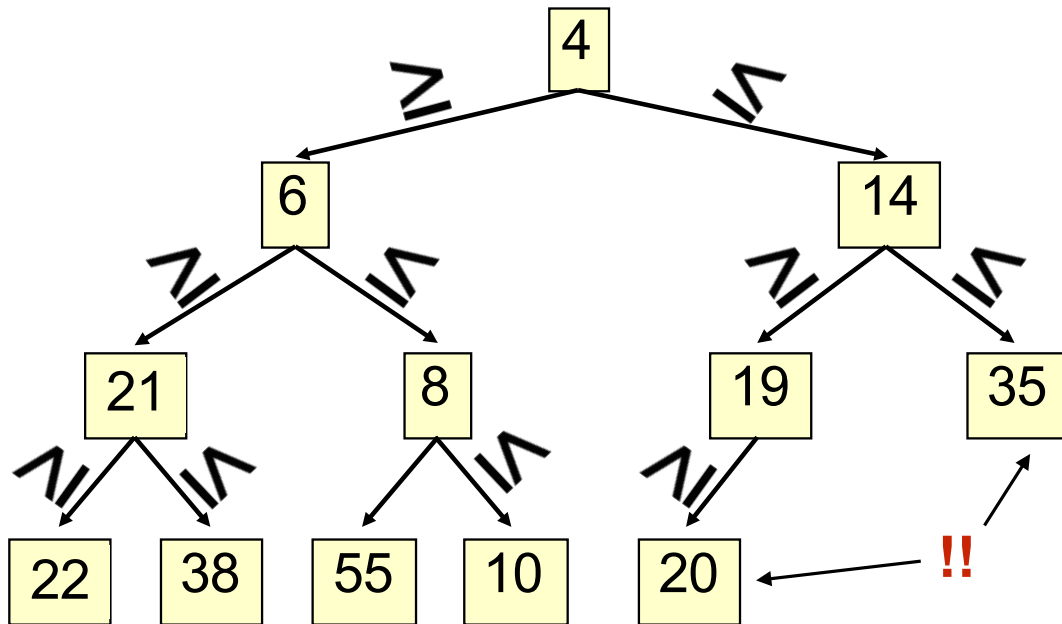
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A heap is a special binary tree.

1. **Heap Order Invariant:**

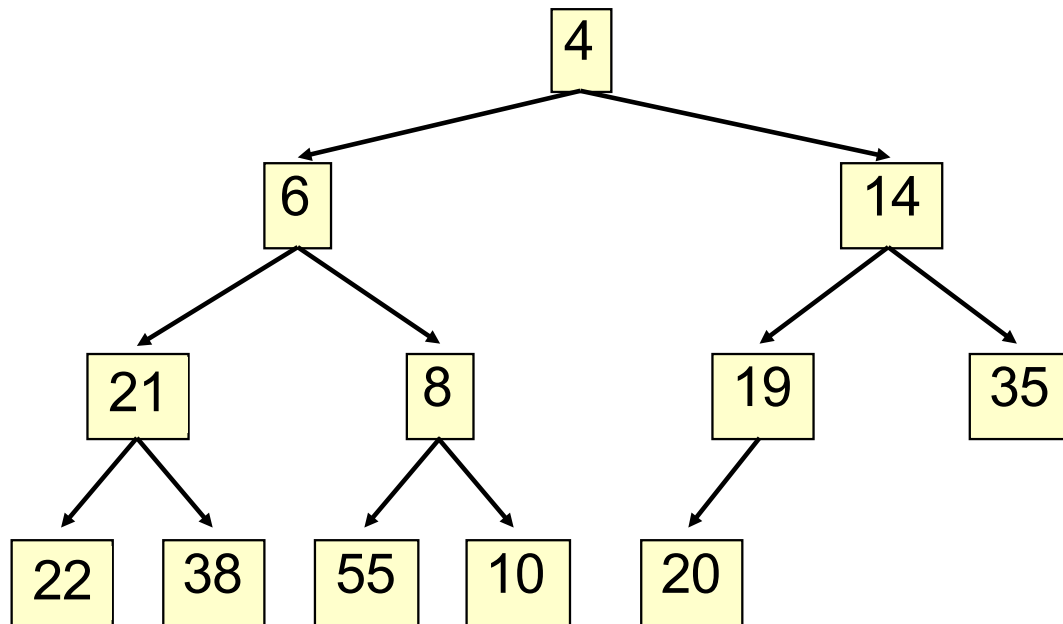
Each element \geq its parent.



A heap is a special binary tree.

2. **Complete:** no holes!

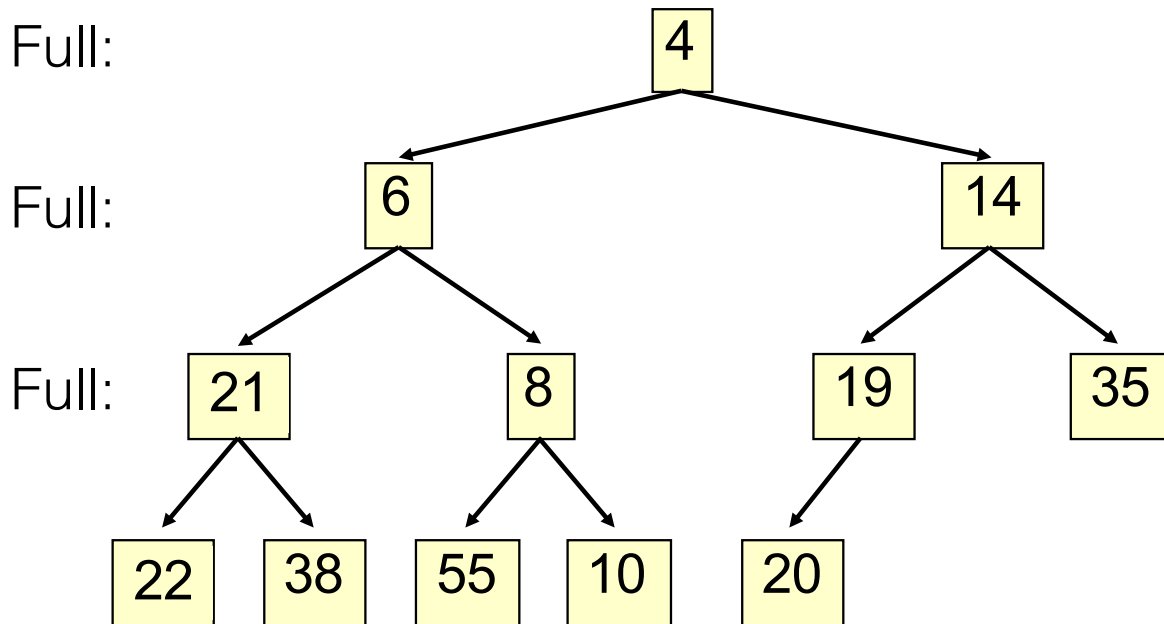
- All levels except the last are full.
- Nodes in last level are as far left as possible.



A heap is a special binary tree.

2. **Complete:** no holes!

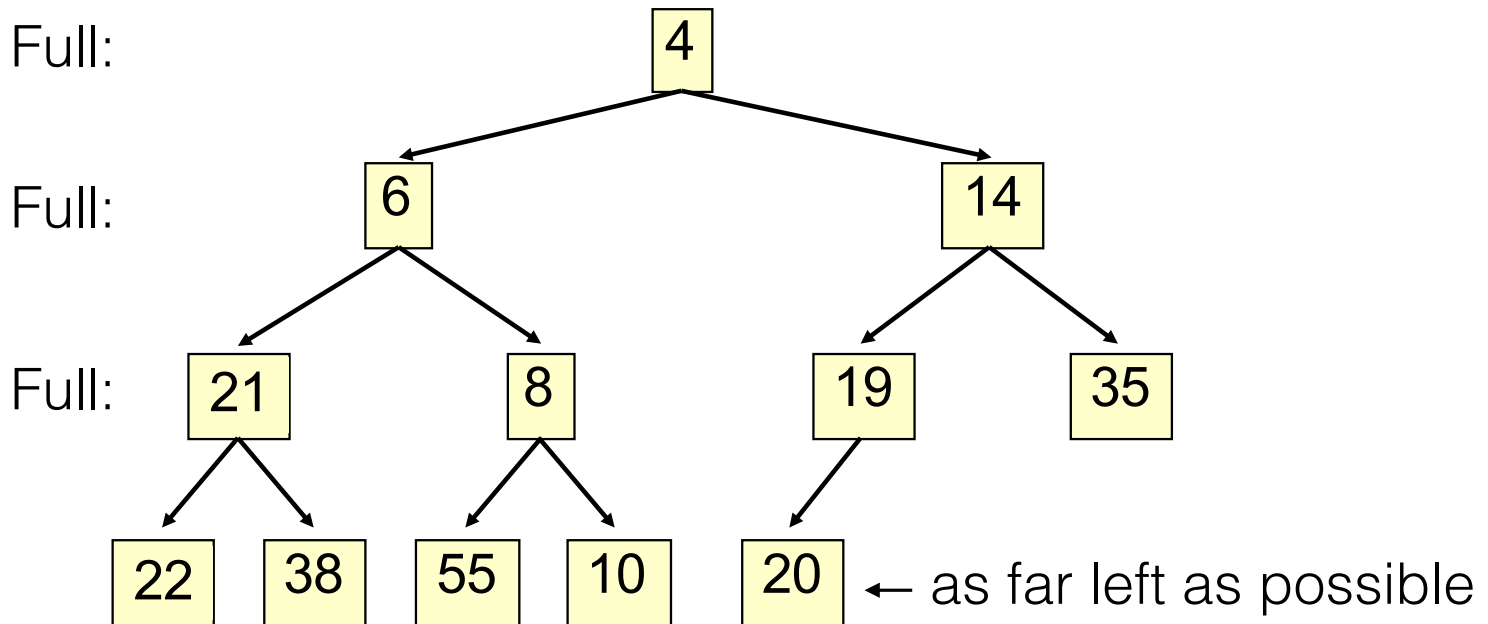
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A heap is a special binary tree.

2. **Complete:** no holes!

- All levels except the last are full.
- Nodes in last level are as far left as possible.



Heap operations

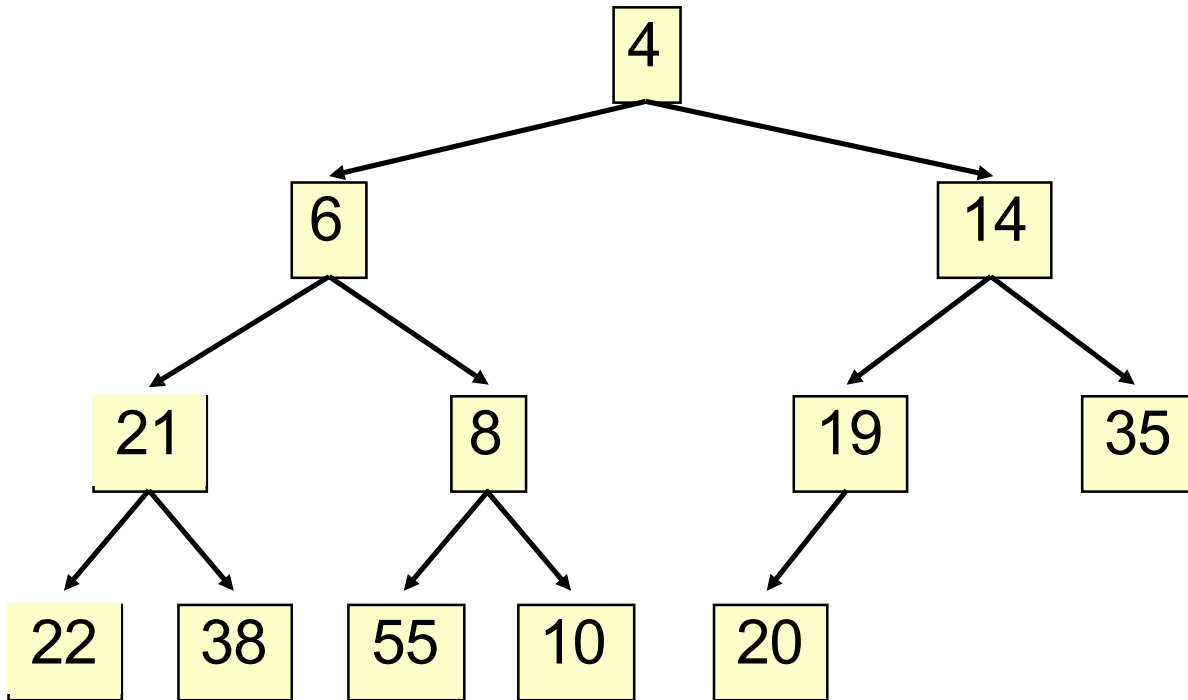
```
interface PriorityQueue<E> {  
    boolean add(E e); // insert e  
    E peek(); // return min element  
    E poll(); // remove/return min element  
    void clear();  
    boolean contains(E e);  
    boolean remove(E e);  
    int size();  
    Iterator<E> iterator();  
}
```

```
void add ( E e ) ;
```

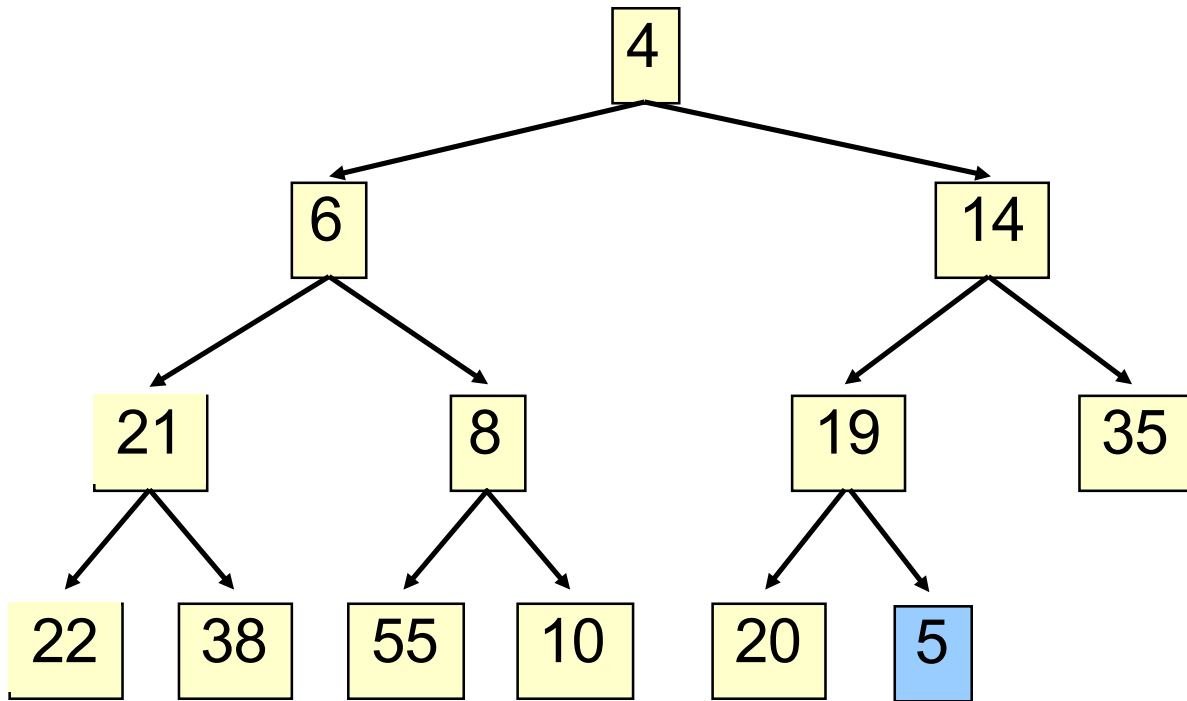
Algorithm:

- Add e in the wrong place
- While e is in the wrong place
 - move e towards the right place

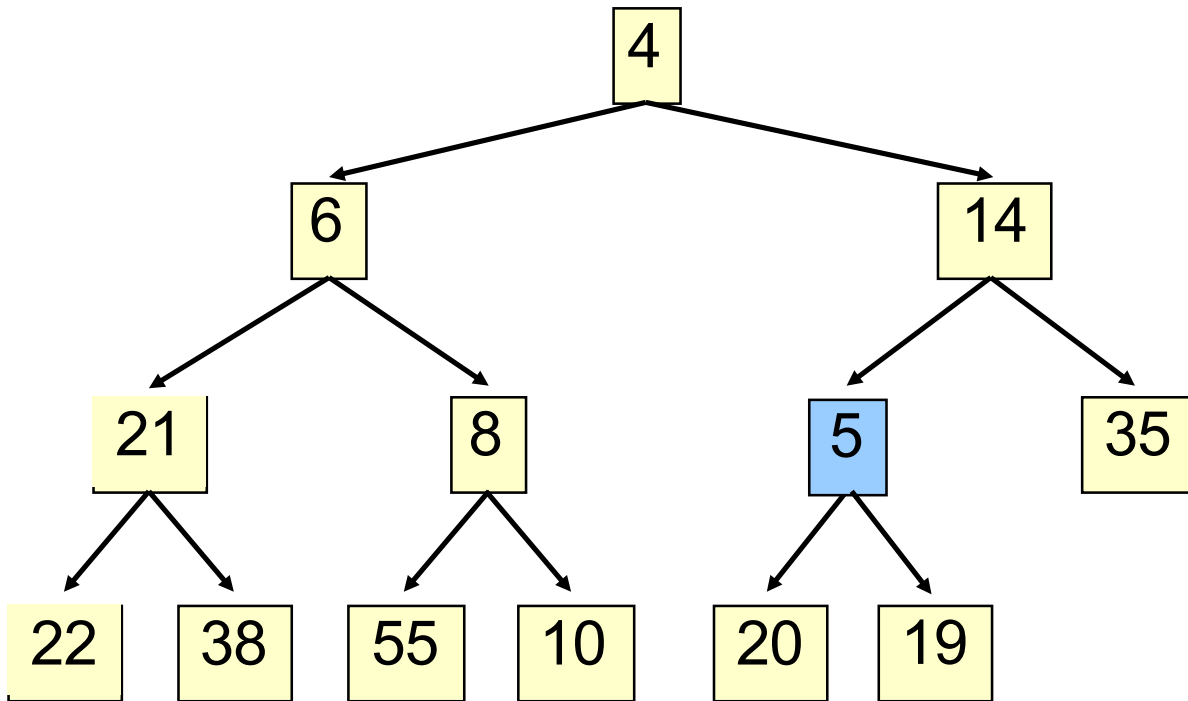
```
void add(E e);
```



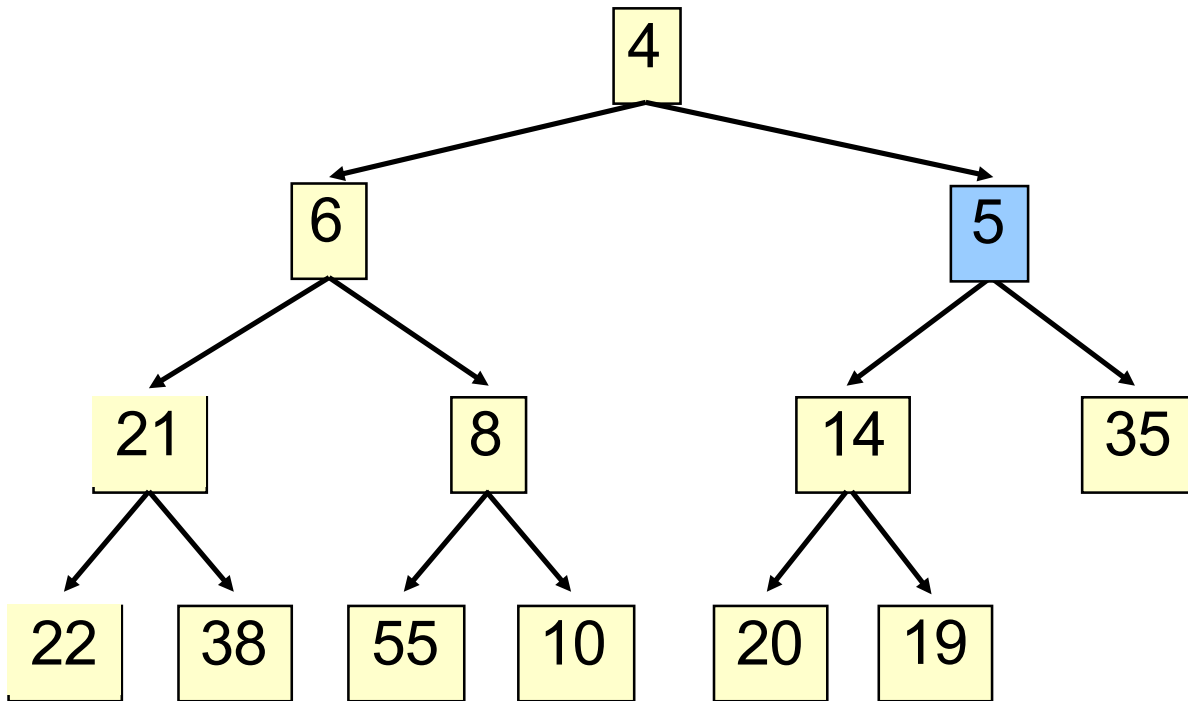
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void add(E e);
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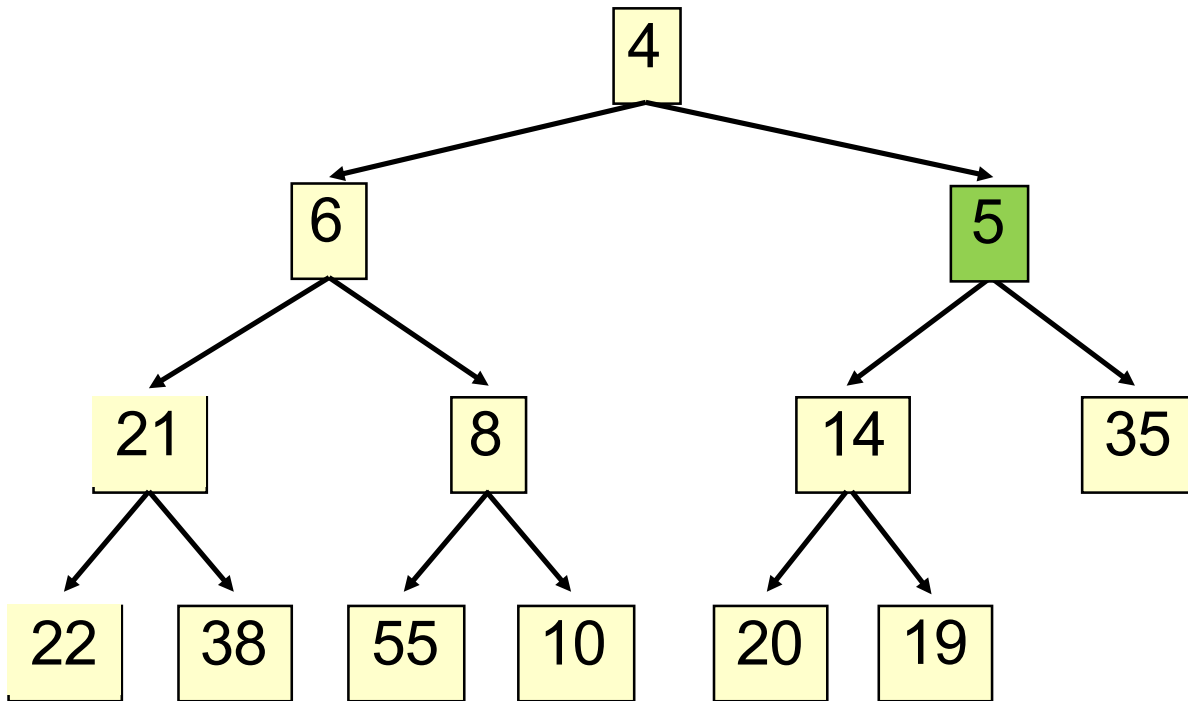
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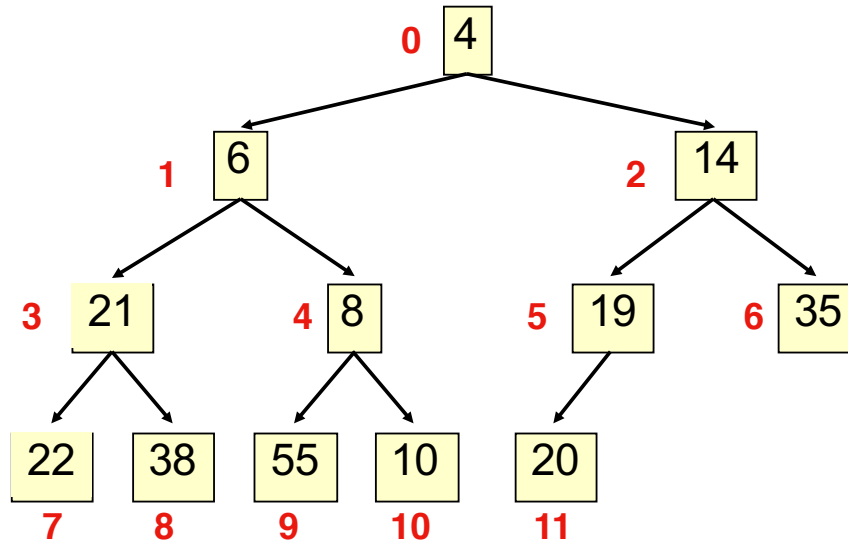
Algorithm:

- Add e in the wrong place (the leftmost empty leaf)
- While e is in the wrong place (it is less than its parent)
 - move e towards the right place (swap with parent)

The heap invariant is maintained!

Storing Heaps: Implicit Tree Structure

2. Complete: **no holes!**



0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

4	6	14	21	8	19	35	22	38	55	10	20				
---	---	----	----	---	----	----	----	----	----	----	----	--	--	--	--

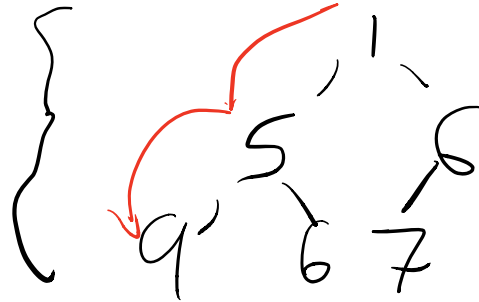


Warmup

What's the height of this heap?

[156967]

- A. 1
- B. 2
- C. 3
- D. 4



Add 2, write array?

Heap Operations

```
interface PriorityQueue<V v, P p> {  
    // insert value v with priority p  
    void add(V v, P p);  
  
    // return value with min priority  
    V peek();  
    // remove/return value with min priority  
    V poll();  
  
    // more methods...  
}
```

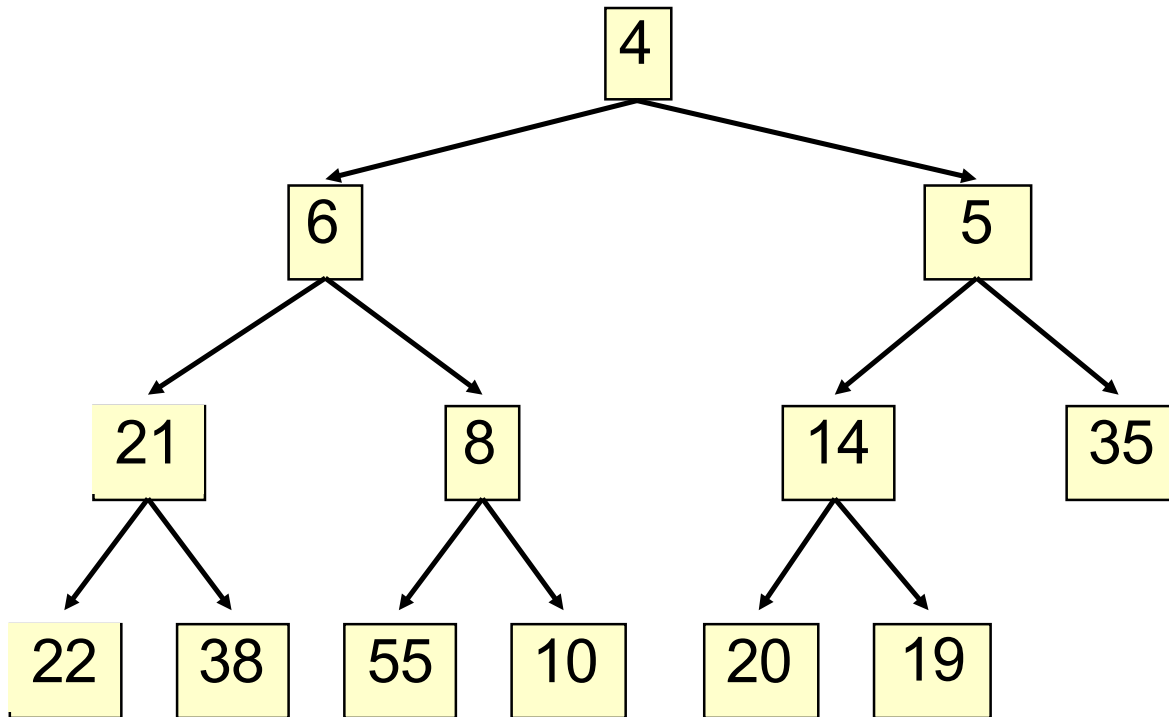
return A[0];

v poll () ;

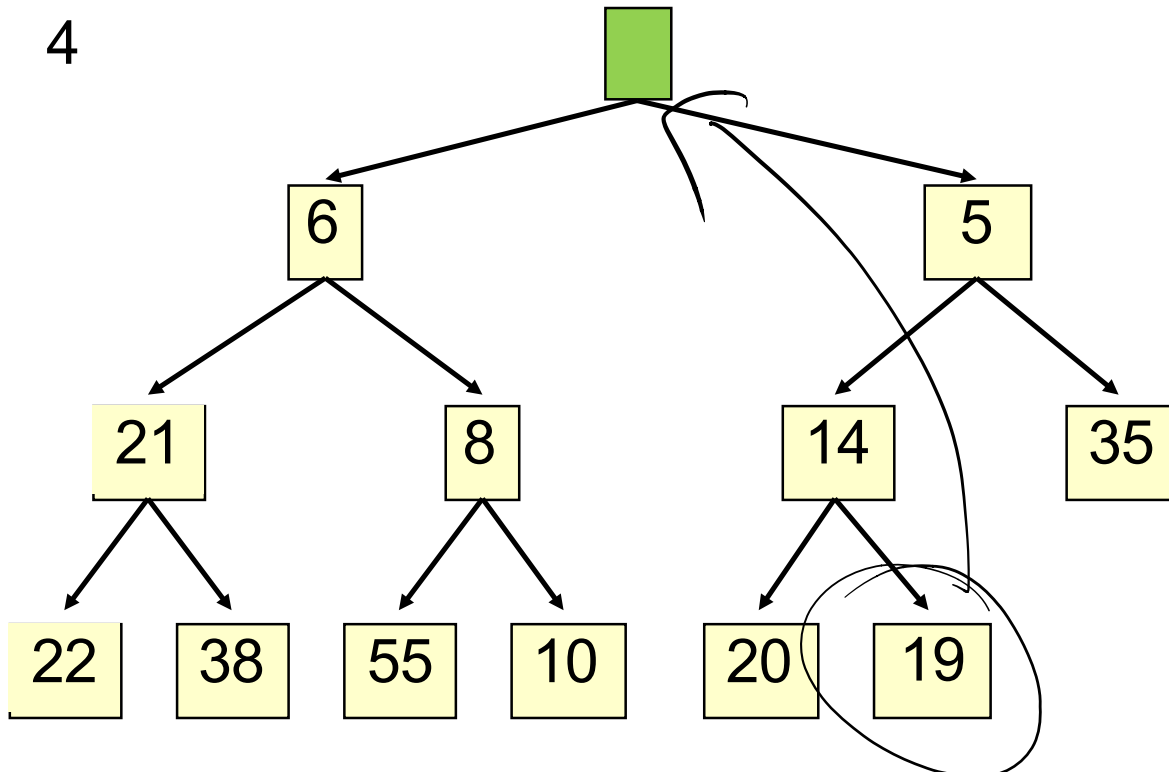
Algorithm:

- ✓ Remove and save the smallest thing
- Fill the resulting hole with the wrong thing
- Bubble the wrong thing down to the right place

v poll();

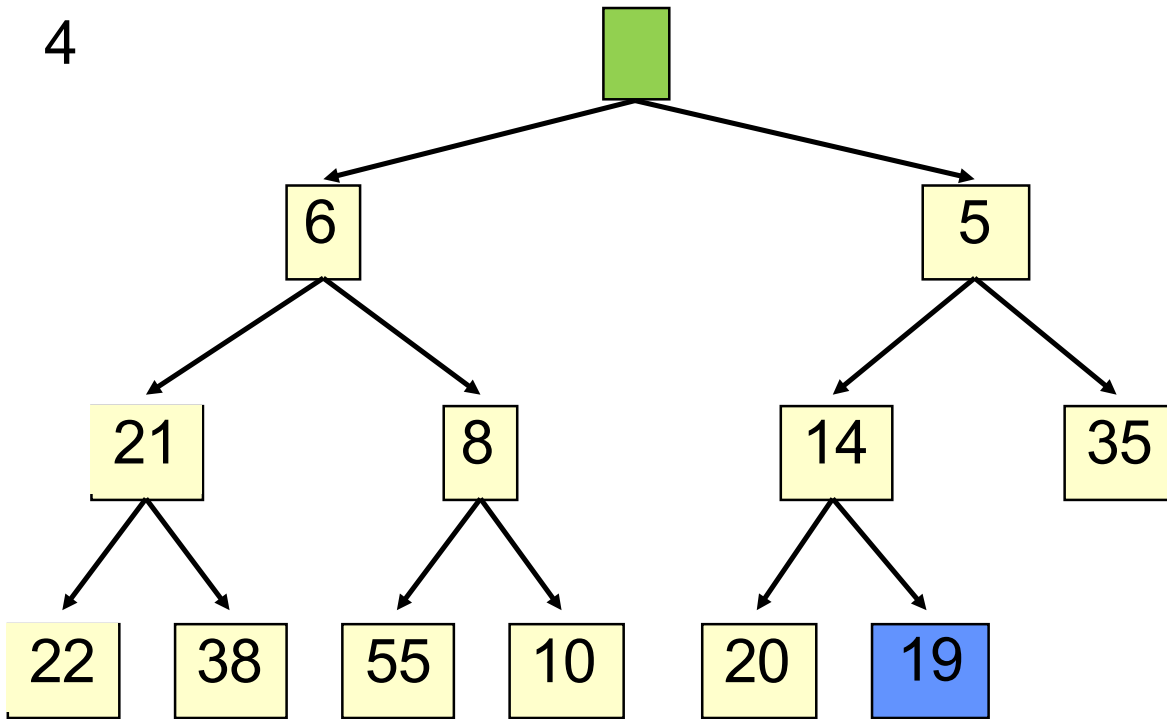


v poll();



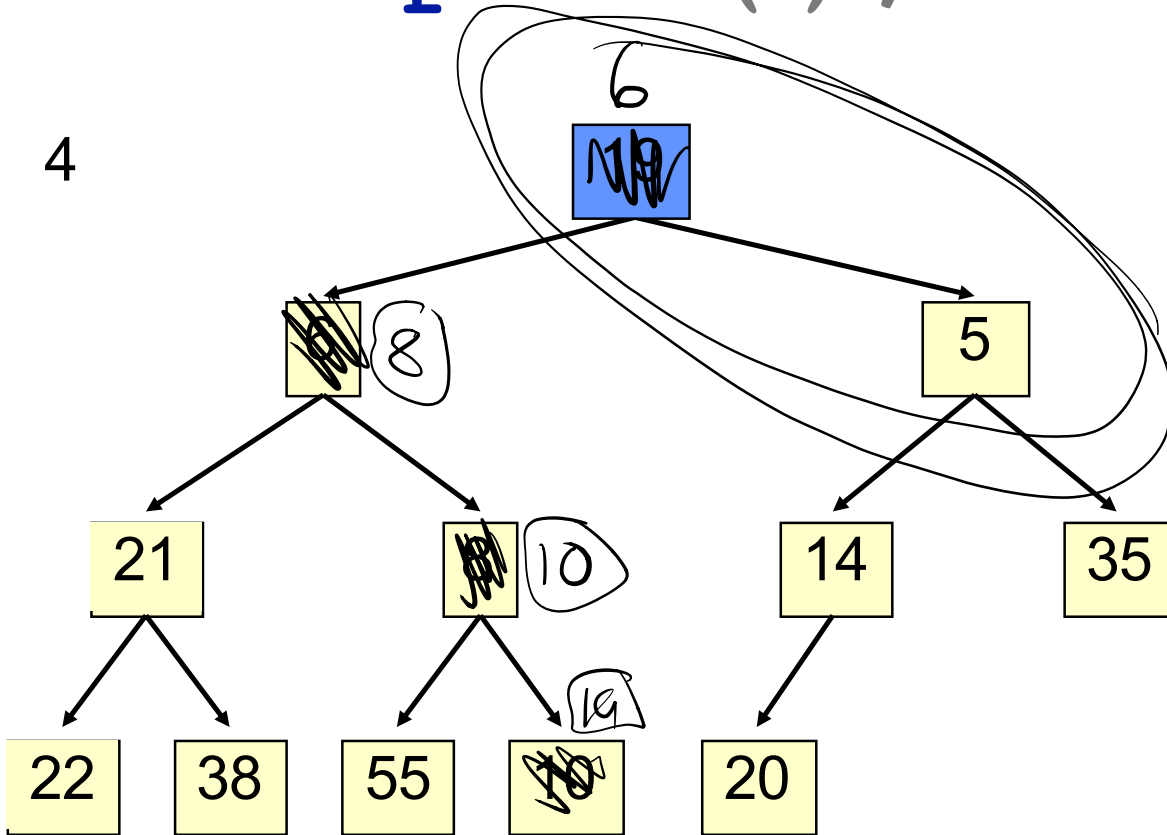
Remove and save the smallest (root) element

v poll();



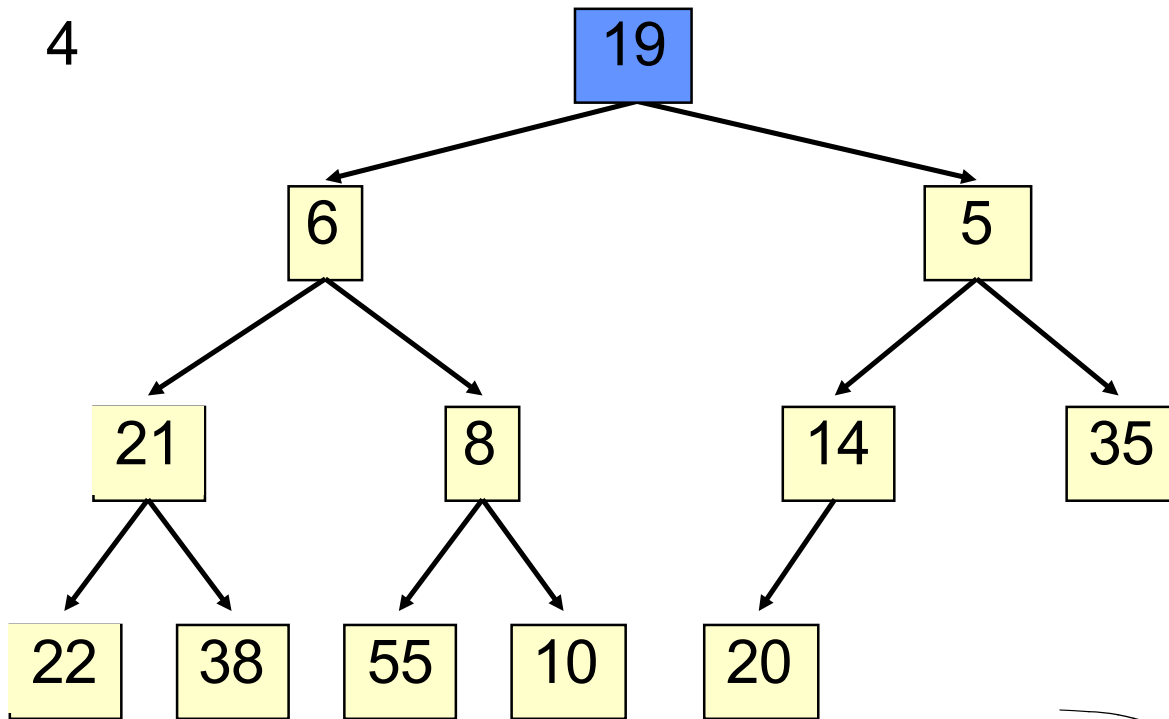
Move the last element to replace the root

v poll();



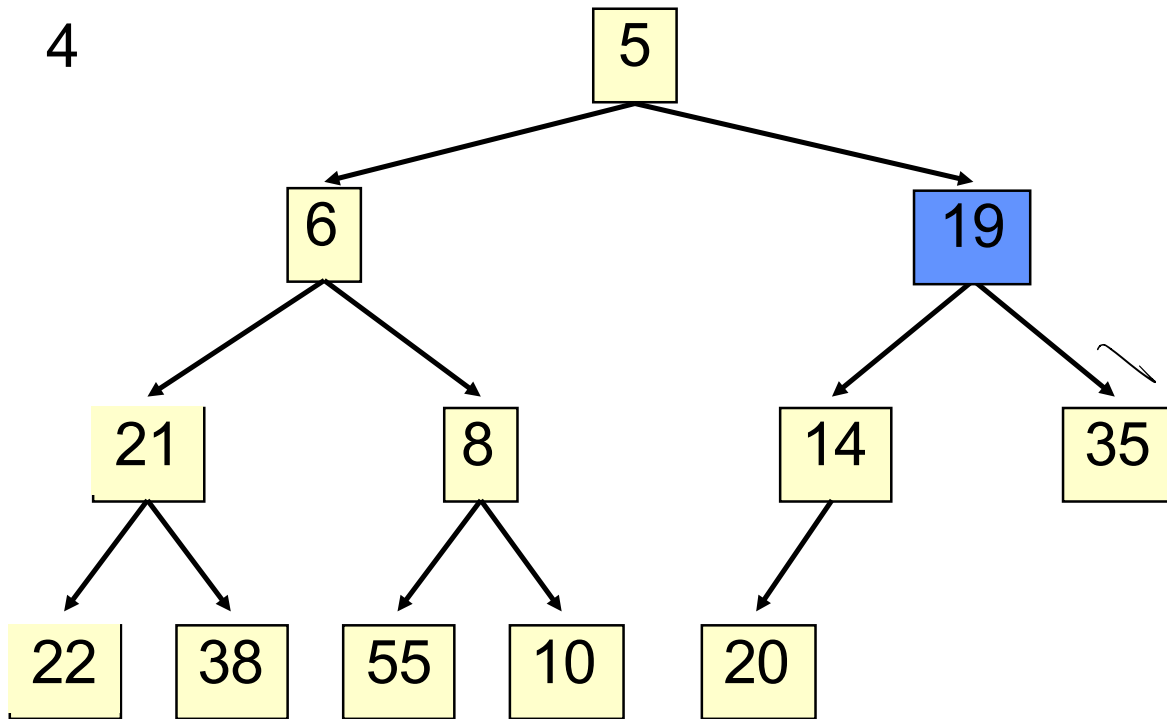
Bubble the root value down

v poll();



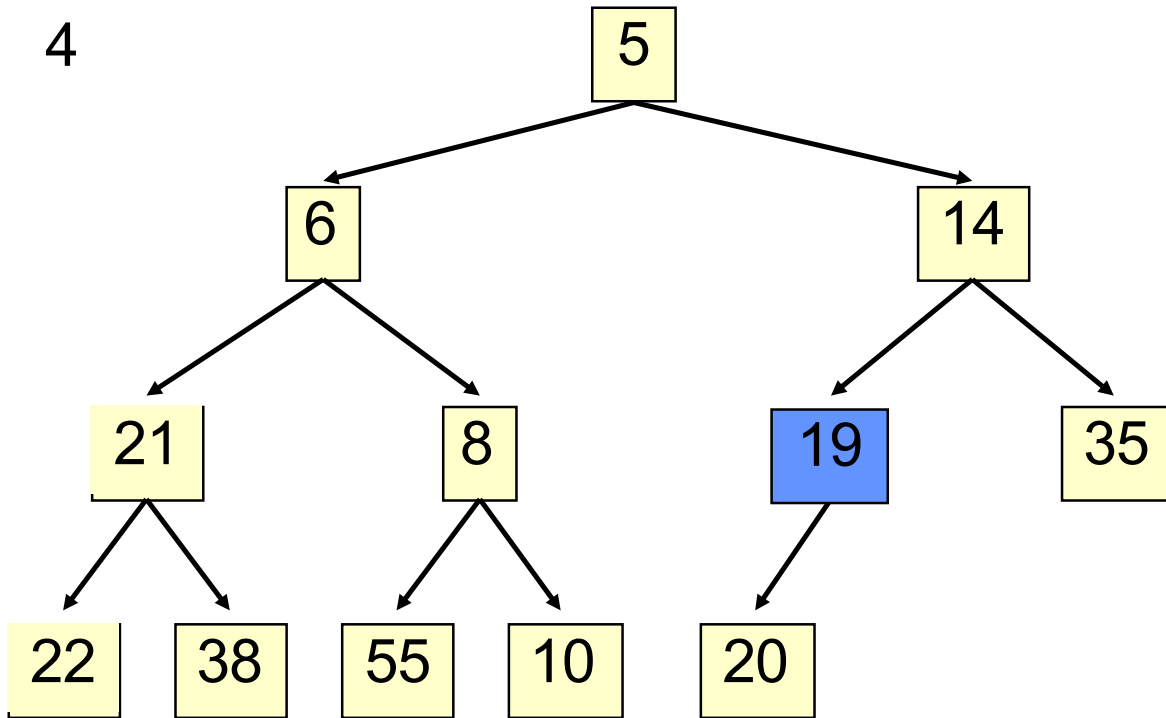
Bubble the root value down, swapping with the **smaller** child

v poll();



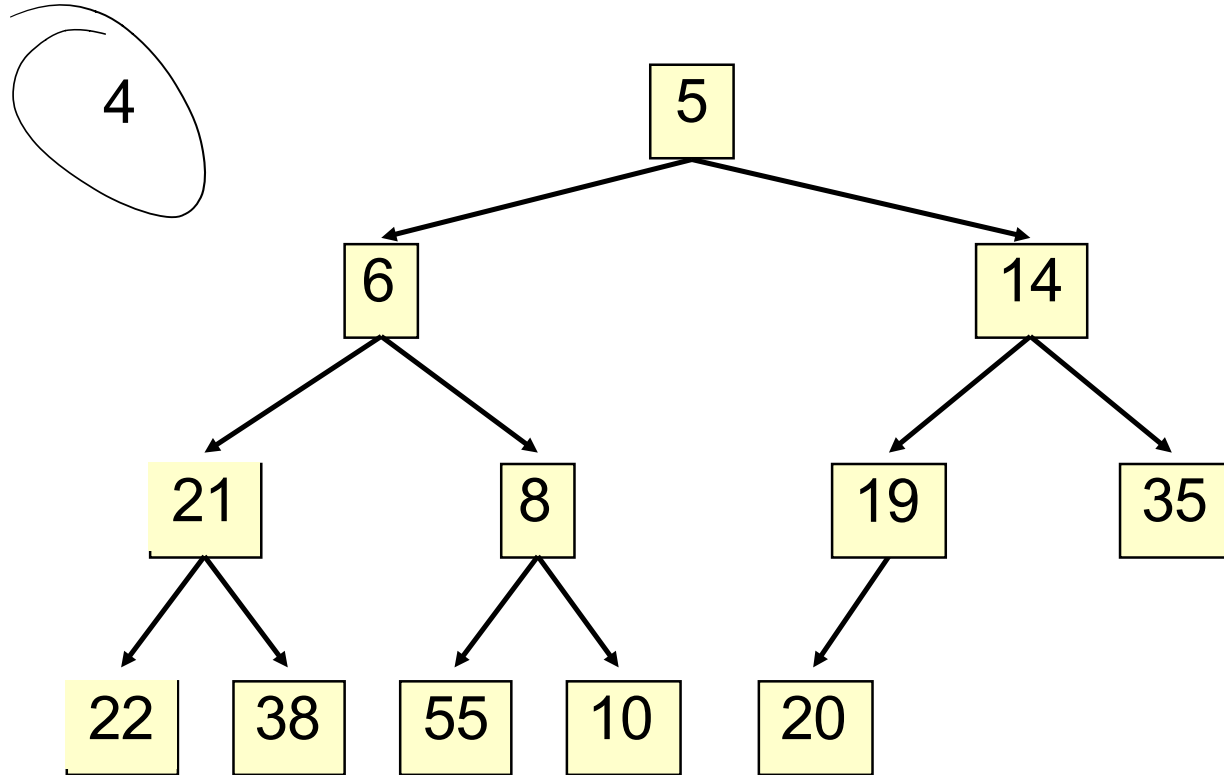
Bubble the root value down, swapping with the **smaller** child

v poll();



Bubble the root value down, swapping with the **smaller** child

`v poll();`



Return the smallest element.

v poll () ;

Algorithm:

- Remove and save the root (first) element
- Move the last element to the first spot.
- While its priority is greater than either of its childrens':
 - Swap it with the child with smaller priority.

Heap operations - runtime

```
interface PriorityQueue<E> {  
    boolean add(E e); // insert e  $O(\log n)$   
    E peek(); // return min  $O(1)$   
    E poll(); // remove/return min  $O(\log n)$   
    void clear();  
    boolean contains(E e);  
    boolean remove(E e);  
    int size();  
    Iterator<E> iterator();  
}
```

Exercise: fill in the runtimes of the rest of the methods.

Heap operations - runtime

```
interface PriorityQueue<E> {  
    boolean add(E e); // insert e    O(log n)  
    E peek(); // return min        O(1)  
    E poll(); // remove/return min  O(log n)  
    void clear();                  O(1)  
    boolean contains(E e);         O(n)  
    boolean remove(E e);           O(n)  
    int size();                    O(1)  
    Iterator<E> iterator();       O(1)  
}
```

Details

- Grow the storage array when the heap exceeds its size (can use ~~Arraylist~~)
AList
- Bubbling routines
- Implementation of contains() and remove()
- Min vs max heaps
- **Efficiently** find, remove, and change priority

Review(?) - Interfaces

Java has a thing called an **interface**.

It's like a class, but doesn't have method bodies. It only exists so other classes can **implement** it.

public interface Set

Specifies public method names, specs, parameters, return values, etc.

Preliminaries - Comparable

The **Comparable** interface has one method:

Method Summary

All Methods

Instance Methods

Abstract Methods

Modifier and Type

Method and Description

int	<code>compareTo(T o)</code> Compares this object with the specified object for order.
-----	--

Returns:

a negative integer if **this** < o

zero if **this** is equal to o

a positive integer if **this** is > o.

From A2: you can call `w.compareTo(node.word)`
because String implements Comparable.

Preliminaries - Comparable

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Method Summary

All Methods

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Abstract Methods

Modifier and Type

Method and Description

int	compareTo (T o) Compares this object with the specified object for order.
-----	---

If you can compare items, you can sort them using comparison sorts!

They have a well-defined **ordering**.

What's with the **V**'s, **P**'s, and **E**'s: Java's Version

- The built-in Java `PriorityQueue` interface:
 - Stores single values of generic type **E**.
 - **E must be Comparable.**
 - The highest-priority element is the “smallest” element (of type **E**) per the `compareTo` ordering
 - In other words: if you sorted the elements in the heap, `poll` would return the first one.
 - But you don't have to sort - the min value is always at the root!

What's with the **V**'s, **P**'s, and **E**'s: Java's Version

```
interface PriorityQueue<E> {  
    boolean add(E e); // insert e  
    E peek(); // return min element  
    E poll(); // remove/return min element  
    void clear();  
    boolean contains(E e);  
    boolean remove(E e);  
    int size();  
    Iterator<E> iterator();  
}
```

What's with the **V**'s, **P**'s, and **E**'s: A3 Version

- The A3 Heap class:

- The Heap has two type parameters:

Heap<**V**, **P** extends **Comparable**<**P**>>

- It stores each element in an *inner* class

Pair<**V**, **P** extends **Comparable**<**P**>> ,

A **Pair** stores a value (of type **V**) together with its priority (of type **P**, which must be **Comparable**)

- The highest-priority element is the **Pair** whose **P** is smallest according to the **compareTo** ordering
- Peek and Poll return (only) the *value* (of type **V**) associated with the smallest *priority* (of type **P**).

What's with the **V**'s, **P**'s, and **E**'s: A3's Version

```
interface PriorityQueue<V v, P p> {  
    // insert value v with priority p  
    void add(V v, P p);  
  
    // return value with min priority  
    V peek();  
  
    // remove/return value with min priority  
    V poll();  
  
    // more methods...  
}
```

Magic trick time!

Heapsort n

```
public static void heapsort(int[] b) {  
    Heap h = new Heap<Integer>();  
    // put everything into a heap  
    for (int k = 0; k < b.length; k = k+1) {  
        h.add(b[k]);  $\leftarrow O(\log n)$   $\} n$   
    }  
  
    // pull everything out in order  
    for (int k = 0; k < b.length; k = k+1) {  
        b[k] = poll(b, k);  $\leftarrow O(\log n)$   $\} n$   
    }  
}
```

$O(n \log n)$

Heapsort

```
public static void heapsort(int[] b) {  
    Heap h = new Heap<Integer>();  
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    // pull everything out in order  
    for (int k = 0; k < b.length; k = k+1) {  
        b[k] = poll(b, k);  
    }  
}
```

Worst-case runtime:

Heapsort

```
public static void heapsort(int[] b) {  
    Heap h = new Heap<Integer>();  
    // put everything into a heap -  $n \cdot \log(n)$   
    for (int k = 0; k < b.length; k = k+1) {  
        h.add(b[k]);  
    }  
  
    // pull everything out in order -  $n \cdot \log(n)$   
    for (int k = 0; k < b.length; k = k+1) {  
        b[k] = poll(b, k);  
    }  
}
```

Worst-case runtime: $O(n \log n)$!