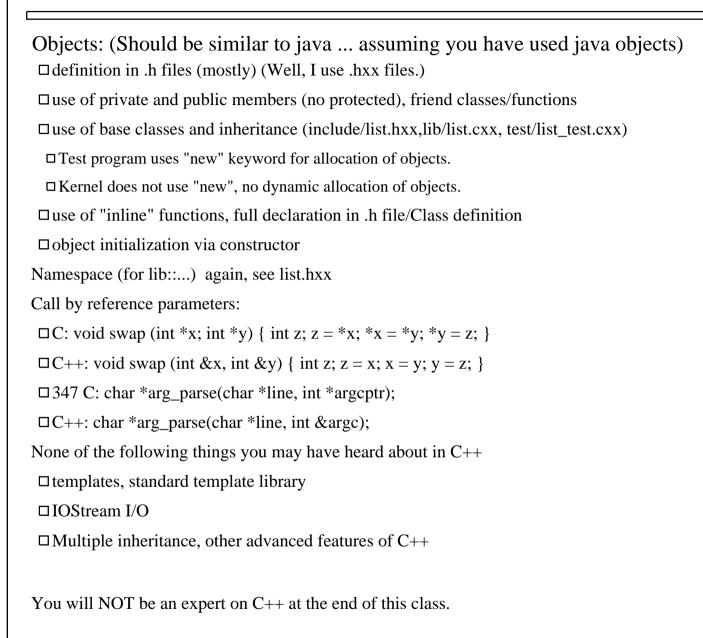
CS 447 - Operating Systems

```
Syllabus (facultyweb.cs.wwu.edu/~phil/classes/f25/447)
Assignments
□Toy Operating System, Toy File System
Environment
    UNIX (Linux, OS X, NetBSD, FreeBSD ....)
    Machine RISCV -- very new architecture
    Toy OS ... object oriented OS written in C++
Reading the book ... you should do it!
C++ used in Toy OS
C++ is a very large language ... won't be using much of it.
C is supposed to be a subset language. (But not quite!)
Standard ideas used in 347 ... includes, functions, pointers, if, for, while, do, function parameters, ...
Except ... libraries: ToyOS has its own, very few of the "normal" ones:
 □Limited version of printf (kprintf inside the kernel)
 □ some string functions: mem* str* (not the full set, see include/string.h)
```



Introduction (Chapt 1) What is an operating system? □ Hardware manager □ Allows "user" (application) programs to utilize the hardware □ Two Views: □ User view: "Abstract machine" □ System View: glue between Abstract machine and real machine Computer systems architecture ... □ CPUs, single, multiple (SMP, parallel, distributed, clusters) ☐ Memory Hierarchy: registers, cache, main memory, SSD, HardDisk, ... □ I/O Devices: Disks, Tape, USB, video, ... □ Other: interrupts (read book), interrupt driven I/O, timers, ... Primary Hardware Mechanism □ Dual Mode: supervisor (system, privileged) vs user □ CPU hardware operation state ☐ User mode provides restriction of use of hardware ☐ Methods to switch between the two □ Multiprogramming -- Multiple programs in memory at the same time □ Multitasking -- runs multiple programs by switching between them or running at the same time

□ Example: RISCV -- 3 modes: Machine, supervisor, user

Processes □ Abstraction for code execution ☐ Uses memory and Dual Mode mechanisms □ Process Management Other issues □ Memory Management □ File-System and Mass-Storage Management □ Caching □ I/O System Management □ Protection and Security □Networking, Virtualization and Distributed Systems □ Special Purpose systems: real time, multimedia, handheld □OS Data structures: lists, stacks, queues, hash tables, bit maps, ...

Other issues and abstractions

Other Issues (page 2)

Operating System Structures (Ch 2)

Program Execution □I/O operations □File systems -- data storage □Communications -- (process to process, network ...) □Error Detection □Resource Allocation (memory, disk, cpu time, ...) □Accounting/Logging □Protection and Security □User Interface? □Some by the OS: e.g. Windows □Some not by the OS: UNIX □GUI vs Command Line vs Touch Screen

Complete OS distributions have more than OS code

□ Kernel: the actual OS itself
☐ Utilities: User land code to make things work
□ UNIX kernel alone is rather useless!
□Linux distribution
□Linux Kernel (essentially same for all distros)
□GNU utilities
□ Other programs
□ Each distro has a different set/ordering
□BSD distributions
□Kernel unique to the xxxBSD
□Core Utilities
□3rd party Utilities (e.g. NetBSD pkgsrc, FreeBSD Ports)

System Calls
The way a User Process requests services from the kernel Syscall API (Application Programming Interface) Transition from "User mode" to "kernel mode"
□Controlled entry into the kernel
Types of system calls, see section 2.3.3 for examples
and Windows Vs Unix system calls
□Process Control
□File Management
□ Device Management
□ Information maintenance (time of day, getpid(),)
□Communications
□Protection
Library Routines
□Often supplied as part of the Distro/OS
□Integrated into API
□ Part of some language e.g. C library

Operating System Design and Implementation

Design Goals
\square kind of OS batch, real time, time sharing, mobile, embedded, parallel
□mechanisms and policies
□ separation
□ policy regardless of mechanism
□ mechanism how to implement policy
□implementation
□ Choice of programming language
Operating System General Structures
□ Simple Structure (aka the big mess) / Monolithic
□ Layered approach (software belongs to a specific layer)
□Microkernel and "servers", message passing
□Modules (aka object oriented)
□Hybrid systems (Mac OS X, iOS, Android)
Operating System Debugging

Virtual Machines □ Experiment with OSes (eg Toy OS) □VM can provided idealized machines □ Abstract VMs (java VM, ...) □ Helps with OS debugging □ Slow down the machine (possibly) □ Simulation can make things repeatable Real OS debugging? □Windows -- second machine as debugger □ Kernel debuggers □ kernel dumps (blue screen or panic)

System boot ... How?



System boot ... How? (page 2)



- □Turn on, enter program via buttons, push "run button"
- □ Basic Binary Loader, read "paper tape" or "mag tape"

□ Power up starts running at location 0. □ Hardware typically maps a ROM image at location 0 □ Or forces a jump to a ROM image □ ROM has "machine monitor" program □ May look for OS/Boot code on a Disk, net, ... □ Qemu / RISCV □ qemu-system-riscv64 -kernel kernel-file -machine virt □ Starts execution at 0x1000

□... and a "ROM" does an immediate jump to 0x8000000

Todays machines -- Boot process

